TECHNISCHE UNIVERSITÄT WIEN



Asymptotically correct finite difference schemes for highly oscillatory ODEs

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Berlin, February 2008

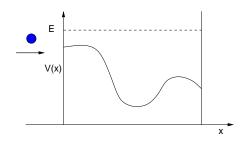


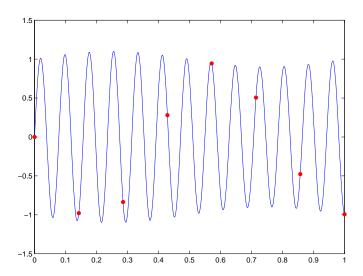
Goal

stationary Schrödinger equation (1d):

$$\frac{\hbar^2}{2m} \psi_{xx}(x) + \underbrace{\left(E - V(x)\right)}_{\geq \alpha > 0} \psi(x) = 0$$

with inhomogeneous open $\mathsf{BCs} \to \mathsf{reformulate}$ as IVP





GOAL: accurate numerical scheme that does NOT NEED to resolve the oscillations

Outline:

- transformation of ODE \rightarrow separate highly oscillatory term & smooth perturbation
- approximation of oscillatory integrals
- error orders
- numerical example

vector valued ODEs

- revisit problem of Lorenz, Jahnke, Lubich [LJL 2005]
- inital value problem: $\psi(x) \in \mathbb{C}^d$

$$\psi''(x) + \frac{1}{\varepsilon^2} A(x) \psi(x) = 0, \quad x \in (x_0, x_{end})$$

 $\psi(x_0) = \psi_0,$
 $\psi'(x_0) = \psi'_0.$

- assumptions: $\mathbb{R}^{d \times d} \ni A(x) = Q(x)a(x)Q^*(x) > 0$
 - ightharpoonup Q(x) orthogonal, smooth
 - ▶ a diagonal smooth
 - eigenvalues a_i remain separated:

$$|a_k(x) - a_l(x)| \ge \delta$$
, $a_k(x) \ge \frac{1}{2}\delta$, $k \ne l$



Separation of highly oscillatory term + slow perturbation

• the ansatz $u_1 := \psi$, $u_2 := \varepsilon A^{-\frac{1}{2}} \psi'$ yields

$$u' = \frac{1}{\varepsilon} \begin{pmatrix} 0 & A^{\frac{1}{2}} \\ -A^{\frac{1}{2}} & 0 \end{pmatrix} u - \begin{pmatrix} 0 & 0 \\ 0 & A^{-\frac{1}{2}}(A^{\frac{1}{2}})' \end{pmatrix} u.$$

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• diagonalisation of the first matrix via v := Pu:

$$egin{array}{lll} v'&=&rac{i}{arepsilon}\left(egin{array}{cc} 1&0\0&-1\end{array}
ight)\otimes a^{rac{1}{2}}\,v-\left(egin{array}{cc} 1&-i\i&1\end{array}
ight)\otimes \mu\,\,v\ &+&I\otimes \left(Q^{*\prime}Q\right)\,v\;, \ \mu&:=&rac{1}{2}Q^*A^{-rac{1}{2}}(A^{rac{1}{2}})'Q\;. \end{array}$$

(⊗ denotes the Kronecker product)

Explicit transformation of high oscillations

• to simplify notation let d = 1 (Schrödinger equ., a(x) = V(x) - E):

$$v' = \frac{i}{\varepsilon} a^{\frac{1}{2}} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} v - \frac{a'}{4a} \begin{pmatrix} 1 & -i \\ i & 1 \end{pmatrix} v$$

• def. phase (exactly integrable for V(x) piecewise linear, e.g.):

$$\phi(x) := \int_{x_0}^x a^{\frac{1}{2}}(s) ds$$
 $(\omega = e^{-\frac{i\phi}{\varepsilon}})$

$$F(x) := \exp\left(-\frac{i}{\varepsilon}\begin{pmatrix}1 & 0 \\ 0 & -1\end{pmatrix}\phi(x)\right) =: \begin{pmatrix}\omega & 0 \\ 0 & \overline{\omega}\end{pmatrix}$$

• let $\eta := F v$

$$\eta' = -\frac{a'}{4a} \begin{pmatrix} 1 & -i\omega^2 \\ i\overline{\omega}^2 & 1 \end{pmatrix} \eta =: \Omega \eta$$

 \Rightarrow new system matrix is arepsilon-uniformly bounded $\Rightarrow \eta$ "smoother"

numerical integration

- let $x_0 < x_1 < \cdots < x_N = x_{end}$ be an equidistant grid with stepsize $h = |x_n x_{n+1}|$
- goal: second order scheme
- integration from x_n to x_{n+1} yields

$$\eta_{n+1} = \eta_n + \int_{x_n}^{x_{n+1}} \Omega(s) \, ds \, \eta_n \\
+ \int_{x_n}^{x_{n+1}} \Omega(s) \int_{x_n}^{s} \Omega(r) \eta(r) \, dr \, ds \\
= \eta_n + \int_{x_n}^{x_{n+1}} \Omega(s) \, ds \, \eta_n \\
+ \int_{x_n}^{x_{n+1}} \Omega(s) \int_{x_n}^{s} \Omega(r) \, dr \, ds \, \eta_n + \mathcal{O}(h^3)$$

Approximation of the Integral

- use standard quadrature rules for the diagonal of the first integral (non-oscillating entries)
- the off-diagonal elements have the same structure, i.e.

$$\mathcal{I} := \int_{x_n}^{x_{n+1}} \Omega_{21}(s) \ ds = -\int_{x_n}^{x_{n+1}} e^{\frac{2i}{\varepsilon}\phi(s)} \cdot \frac{a'(s)}{4a(s)} \ ds$$

- two strategies
 - replacing ϕ by $\phi_n + s\phi_n' + \frac{s^2}{2}\phi_n''$ leads to the *adiabatic midpoint rule* proposed by [LJL] (integration interval: $[x_{n-1}, x_{n+1}]!$)
 - e manipulate $\frac{a'}{4a}$ in order to exactly integrate the remaining integral (AA, Ben Abdallah, Negulescu)

Details for integral strategy (2)

• factorize the integrand $(\phi' = a)$ in:

$$\mathcal{I} = -\int_{x_n}^{x_{n+1}} \underbrace{e^{\frac{2i}{\varepsilon}\phi(s)} \frac{2i\phi'(s)}{\varepsilon}}_{=(e^{\frac{2i}{\varepsilon}\phi})' \dots \text{ oscill.}} \cdot \underbrace{\frac{\varepsilon}{2i\phi'(s)} \frac{a'(s)}{4a(s)}}_{=:f \dots \text{ "smooth"}} ds$$

IDEA: approximate only the smooth factor, integrate oscill. factor exactly

- approximate f: $f \approx \alpha + \beta \phi$ (\rightarrow second order) α , β are determined by interpolation
- the double integral is treated analogously



Properties of the scheme

- both strategies yield a scheme of $\mathcal{O}(h^2)$
- error estimates independent of ε , even for $h > \varepsilon$ (if phase $\Phi = \int \sqrt{a(s)} \, ds$ is exact)
- both methods are exact for constant A
- the oscillatory integrals are of order ε :

$$\int_{a}^{b} e^{\frac{\phi(x)}{\varepsilon}} f(x) dx = \int_{a}^{b} e^{\frac{\phi}{\varepsilon}} \frac{\phi'}{\varepsilon} \cdot \frac{\varepsilon}{\phi'} f dx$$
$$= e^{\frac{\phi}{\varepsilon}} \frac{\varepsilon}{\phi'} f \Big|_{x=a}^{b} - \varepsilon \int_{a}^{b} e^{\frac{\phi}{\varepsilon}} \left(\frac{f}{\phi'}\right)' dx$$

Is it possible to benefit from these property?

Improved scheme

previous equation:

$$\eta' \ = \ -\frac{\mathit{a'}}{\mathit{4a}} \left(\begin{array}{cc} 1 & 0 \\ 0 & 1 \end{array} \right) \ \eta + \mathit{i} \frac{\mathit{a'}}{\mathit{4a}} \left(\begin{array}{cc} 0 & \omega^2 \\ -\overline{\omega}^2 & 0 \end{array} \right) \ \eta$$

• "remove" the diagonal part by transformation: $w:=a^{\frac{1}{4}}(x)$ η

$$w' = i \frac{a'}{4a} \begin{pmatrix} 0 & \omega^2 \\ -\overline{\omega}^2 & 0 \end{pmatrix} w = \tilde{\Omega} w, \quad \omega = e^{-i\frac{\Phi}{\varepsilon}}$$

- same structure as η -equation \Rightarrow replace Ω by $\tilde{\Omega}$ in the previous numerical scheme
- strong ε -limit: $w(x) = w(x_0)$ (for a(x) smooth)
- improved error estimate: $\mathcal{O}(\min(h,\varepsilon) \cdot h)$!
- scheme asymptotically correct as $\varepsilon \to 0$ (for h = const !)

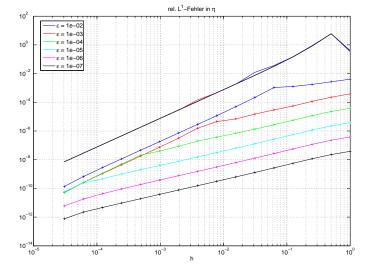


Numerical Example

• example from [LJL 2005]: d = 2, $x \in [-1, 1]$

$$\begin{array}{lcl} a^{\frac{1}{2}}(x) & = & \left(\frac{3}{2}x+3\right)\left(\begin{array}{cc} 1 & 0 \\ 0 & 1 \end{array}\right) + \frac{\sqrt{x^2+4}}{2}\left(\begin{array}{cc} 1 & 0 \\ 0 & -1 \end{array}\right) \\ Q(x) & = & \left(\begin{array}{cc} \cos\xi(x) & -\sin\xi(x) \\ \sin\xi(x) & \cos\xi(x) \end{array}\right) \;, \; \text{with} \\ \xi(x) & = & \frac{\pi}{4} + \frac{1}{2}\arctan\left(\frac{x}{2}\right) \end{array}$$

• error in [LJL 2005]: $\mathcal{O}(h^2)$ (uniformly in ε)



- error of improved scheme: $\mathcal{O}(\min(h, \varepsilon) \cdot h)$
- ullet work in progress: error $=\mathcal{O}(arepsilon h^2)$ (with "better" transformations)