

On time-splitting methods for gradient flows with two dissipation mechanisms

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A gradient systems $(\mathbf{X}, \mathcal{E}, \mathcal{R})$ is a triple consisting of a state space \mathbf{X} (typically a separable, reflexive Banach space), an energy or entropy functional $\mathcal{E} : \mathbf{X} \rightarrow \mathbb{R} \cup \{\infty\}$, and a dissipation potential $\mathcal{R} : \mathbf{X}_1 \times \mathbf{X} \rightarrow [0, \infty]$. The associated gradient-flow equation is reads

$$0 \in \partial_{\dot{u}} \mathcal{R}(u, \dot{u}) + D\mathcal{E}(u) \quad \text{or equivalently} \quad \dot{u} \in \partial_{\xi} \mathcal{R}^*(u, -D\mathcal{E}(u)).$$

We are interested in the case where \mathcal{R}^* is a sum, namely $\mathcal{R}^* = \mathcal{R}_1^* + \mathcal{R}_2^*$. A simple linear application occurs for reaction-diffusion systems $\dot{u} = \operatorname{div}(\mathbb{D}\nabla u) - \mathbb{A}u$, where $\mathcal{E}(u) = \int_{\Omega} \frac{1}{2}|u|^2 dx$ and $\mathcal{R}^*(\xi) = \int_{\Omega} (\frac{1}{2}\nabla\xi : \mathbb{D}\nabla\xi + \frac{1}{2}\xi \cdot \mathbb{A}\xi) dx$. Other applications occur in the mechanics of dissipative materials e.g. in viscoelastic-viscoplastic materials with displacement u and plastic tensor p :

$$\mathcal{E}(u, p) = \int_{\Omega} (\frac{1}{2}\mathbf{e}(u) : \mathbb{C}\mathbf{e}(u) + \frac{1}{2}p : \mathbb{H}p) dx \quad \text{and} \quad \mathcal{R}(\dot{u}, \dot{p}) = \int_{\Omega} (\mathbf{e}(\dot{u}) : \mathbb{V}_e \mathbf{e}(\dot{u}) + \sigma_{\text{yield}} |\dot{p}| + \frac{1}{2} \dot{p} : \mathbb{V}_{pl} \dot{p}) dx.$$

We investigate the question under what assumption the time-splitting algorithm

$$\begin{aligned} \dot{u} &\in 2 \partial_{\xi} \mathcal{R}_1^*(-D\mathcal{E}(u)) && \text{for } Nt \in [0, 1/2[\pmod{1}, \\ \dot{u} &\in 2 \partial_{\xi} \mathcal{R}_2^*(-D\mathcal{E}(u)) && \text{for } Nt \in [1/2, 1[\pmod{1}, \end{aligned}$$

converges for $N \rightarrow \infty$. We give a finite-dimensional example showing that convergence does not hold if \mathcal{E} is only convex but not differentiable. Under natural conditions we provide convergence results, also for the case where only time-discrete minimization steps are done.

This is ongoing, joint work with Riccarda Rossi (U Brescia) and Artur Stephan (WIAS).