

# Thermally driven phase transformation in shape-memory alloys

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Oberwolfach Workshop Analysis and Numerics for Rate-Independent Processes,  
February 25th - March 3rd, 2007

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# Introduction

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## Previous works:

- ▶ A. Souza, E. Mamiya, N. Zouain'98,
- ▶ A. Mielke, F. Theil'04,
- ▶ A. Mainik, A. Mielke'05,
- ▶ G. Francfort, A. Mielke'06,
- ▶ A. Mielke'05,
- ▶ F. Auricchio, A. Mielke, U. Stefanelli'07.

# Mathematical formulation

We consider a body with reference configuration  $\Omega \subset \mathbb{R}^d$ .

- ▶  $u : \Omega \rightarrow \mathbb{R}^d$ : the **phase transformation** and **deformations**,
- ▶  $z : \Omega \rightarrow \mathbb{R}_{\text{dev}}^{d \times d} := \{z \in \mathbb{R}_{\text{sym}}^{d \times d} : \text{tr}(z) = 0\}$ : the **internal variable**,

## Notations

- ▶  $\mathbb{R}_{\text{sym}}^{d \times d} := \{z \in \mathbb{R}^{d \times d} : z = z^T\}$ 
  - ▶  $a : b := \text{tr}(ab) = a_{ij}b_{ij}$ : the scalar product,
  - ▶  $|a|^2 := a : a = a_{ij}a_{ij}$ : the norm,
- ▶  $(\cdot)^T$ : the **transpose** of the matrix  $(\cdot)$ ,
- ▶  $\text{tr}(\cdot)$ : the **trace** of the matrix  $(\cdot)$ .

The **potential energy** has the following form:

$$\mathcal{E}(t, u, z) := \int_{\Omega} W(e(u), z, \theta) + \frac{\sigma}{2} |\nabla z|^2 dx - \langle l(t), u \rangle,$$

## Notations

- ▶ The **stored energy density** is defined by

$$W(e(u), z, \theta) := \frac{1}{2} (e(u) - z) : \mathbb{C}(\theta) : (e(u) - z) + h(z, \theta),$$

- ▶  $e(u) := \nabla u + \nabla u^T$ : the **linearized deformation** satisfies the **Korn's inequality**, i.e.

$$\int_{\Omega} |e(u)|^2 dx \geq c_{\text{Korn}} \|u\|_{W^{1,2}}^2, \quad c_{\text{Korn}} > 0,$$

- ▶  $\mathbb{C}(\theta) : \mathbb{R}_{\text{sym}}^{d \times d} \rightarrow \mathbb{R}_{\text{sym}}^{d \times d}$ : the **elasticity tensor** (symmetric positive linear map) that depends on the **temperature**  $\theta$  and is defined as follows:

$$\mathbb{C}(\theta) : a := \lambda(\theta) \text{tr}(a) + 2\mu(\theta)a,$$

- ▶  $\lambda(\theta), \mu(\theta)$ : the **Lamé coefficients** depending on the **temperature**  $\theta$ .

- ▶  $h(z, \theta) := c_1(\theta)|z|^2 + c_2(\theta)\sqrt{\delta^2 + |z|^2} + (|z|^2 - c_3(\theta))_+^3$ ,

- ▶  $\sigma > 0$ : measures some **nonlocal interaction effect** for  $z$ ,

- ▶  $l(t)$ : the **applied mechanical loading** is defined as follows:

$$\langle l(t), u \rangle = \int_{\Omega} f_{\text{appl}}(t, x) \cdot u(x) dx + \int_{\partial\Omega} g_{\text{appl}}(t, x) \cdot u(x) d\gamma.$$

The **dissipation potential** is defined by

$$\mathcal{R}(\dot{z}) := \int_{\Omega} \rho |\dot{z}| dx = \rho \|\dot{z}\|_{L^1(\Omega)}, \quad \rho > 0.$$

### Remark 1.

- ▶ We do not solve an associated **heat equation**,
- ▶ This approximation used in engineering models:

#### Assumptions:

- ▶ the changes of the loading are slow,
- ▶ the body is small in at least one direction,

⇒ excess heat can be transported very fast to the surface.

We specify now the **set of admissible deformations**  $\mathcal{F}$  by choosing a suitable Sobolev space  $W^{1,2}(\Omega; \mathbb{R}^d)$  and by describing **Dirichlet data** at the part  $\Gamma_{\text{Dir}}$  of the boundary  $\partial\Omega$

$$\mathcal{F} := \{u \in W^{1,2}(\Omega; \mathbb{R}^d) : u|_{\Gamma_{\text{Dir}}} = 0\},$$

and the **internal variable**  $z$  live in  $\mathcal{Z} := L^1(\Omega; \mathbb{R}_{\text{dev}}^{d \times d})$ .

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### **Energetic formulation:**

A function  $(u, z) : [0, T] \rightarrow \mathcal{F} \times \mathcal{Z}$  is an **energetic solution** of the rate-independent problem associated with  $\mathcal{E}$  and  $\mathcal{R}$  if for all  $t \in [0, T]$ , the **global stability condition** (S) and the **global energy conservation** (E) are satisfied, i.e.

$$(S) \quad \forall (\bar{u}, \bar{z}) \in \mathcal{F} \times \mathcal{Z} : \mathcal{E}(t, u(t), z(t)) \leq \mathcal{E}(t, \bar{u}, \bar{z}) + \mathcal{R}(\bar{z} - z(t)),$$

$$(E) \quad \mathcal{E}(t, u(t), z(t)) + \int_0^t \mathcal{R}(\dot{z}(s)) ds \\ = \mathcal{E}(0, u_0, z_0) + \int_0^t \partial_s \mathcal{E}(s, u(s), z(s)) ds.$$

## A priori estimates

We clarify now the assumptions and we establish some preliminary results that we will use in the next section.

**Lemma 1.** Assume  $c_j(\theta)$ ,  $j = 1, \dots, 3$ , belong to  $C^1([0, T])$ . Then there exist  $c_j^W$ ,  $j = 1, 2$ , such that for all  $j = 1, 2$ ,

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**Lemma 2.** Under the assumptions of Lemma 1, for all  $\theta_1 \in [\theta_{\min}, \theta_{\max}]$ , we have

$$W(e(u), z, \theta_1) + c_0^W \leq \exp(c_1^W |\theta_1 - \theta|) (W(e(u), z, \theta) + c_0^W).$$

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**Remark 1.** There exist  $c > 0$  and  $C > 0$  such that

$$W(e(u), z, \theta) \geq c|e(u)|^2 - C.$$

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**Proposition 1.** Under the above assumptions the following holds:



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1. If for some  $(t, u, z) \in [0, T] \times \mathcal{F} \times \mathcal{Z}$  we have  $\mathcal{E}(t, u, z) < +\infty$ , then  $\mathcal{E}(\cdot, u, z)$  are bounded in  $C^1([0, T])$  and

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3. For each strictly positive  $\varepsilon$  and  $E \in \mathbb{R}$  there exists  $\delta$  such that  $\mathcal{E}(t_1, u, z) \leq E$  and  $|t_1 - t_2| < \delta$  imply

$$|\partial_t \mathcal{E}(t_1, u, z) - \partial_t \mathcal{E}(t_2, u, z)| \leq \varepsilon. \quad (3)$$

*Proof.*

1. The **Korn's inequality** and Remark 1  $\Rightarrow \exists c > 0, C > 0$  such that

$$\mathcal{E}(t, u, z) \geq c_0 \|u\|_{W^{1,2}}^2 - C_0.$$

For all  $h \neq 0$  and  $t + h \in [0, T]$  the mean-value theorem provides that

$$\begin{aligned} \frac{1}{h}(\mathcal{E}(t+h, u, z) - \mathcal{E}(t, u, z)) &= \partial_t \mathcal{E}(t+sh, u, z) \\ &= \int_{\Omega} \partial_{\theta} W(e(u), z, \theta_{\text{appl}}) \dot{\theta}_{\text{appl}}(t+sh) dx - \langle l(t+h) - l(t), u \rangle, s \in (0, 1). \end{aligned}$$

The **Lebesgue's theorem**  $\Rightarrow$  the differentiability of  $\mathcal{E}(t, u, z)$  ( $\partial_t \mathcal{E}(t, u, z)$ ).  
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Proof:

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3. Observe now that

$$\begin{aligned} &|\partial_t \mathcal{E}(t_1, u, z) - \partial_t \mathcal{E}(t_2, u, z)| \\ &\leq \int_{\Omega} |\partial_{\theta} W(e(u), z, \theta_{\text{appl}}(t_1)) - \partial_{\theta} W(e(u), z, \theta_{\text{appl}}(t_2))| dx \|\dot{\theta}_{\text{appl}}\|_{L^{\infty}} \\ &+ \int_{\Omega} |\partial_{\theta} W(e(u), z, \theta_{\text{appl}})| dx \|\dot{\theta}_{\text{appl}}(t_1) - \dot{\theta}_{\text{appl}}(t_2)\|_{L^{\infty}} \\ &+ \|\dot{l}(t_1) - \dot{l}(t_2)\|_{(W^{1,2})'} \|u\|_{W^{1,2}}. \end{aligned}$$

The mean-value theorem, Lemma 1 and Lemma 2  $\Rightarrow$  (3).

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- ▶  $\text{Argmin}\{\varphi(u) : u \in \mathcal{H}\}$ : the **set of all minimizers** of a functional  $\varphi : \mathcal{H} \rightarrow \mathbb{R}_\infty$ ,
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We define the **incremental problem** as follows:

$$(IP)_\Pi \quad \left\{ \begin{array}{l} \text{for } k = 1, \dots, d \text{ find} \\ (u_k, z_k) \in \text{Argmin}\{\mathcal{E}(t_k, \tilde{u}, \tilde{z}) + \mathcal{R}(\tilde{z} - z_k) : (\tilde{u}, \tilde{z}) \in \mathcal{F} \times \mathcal{Z}\}. \end{array} \right.$$

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- ▶  $(IP)_\Pi$  has always solutions,
- ▶ we are able to define the piecewise constant interpolant  $(u^\Pi, z^\Pi) : [0, T] \rightarrow \mathcal{F} \times \mathcal{Z}$  with  $(u^\Pi(t), z^\Pi(t)) = (u_j, z_j)$  for  $t \in [t_{j-1}, t_j]$  for  $j = 0, \dots, N$ .

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$$(IP)_\Pi \quad \left\{ \begin{array}{l} \text{for } k = 1, \dots, d \text{ find} \\ (u_k, z_k) \in \text{Argmin}\{\mathcal{E}(t_k, \tilde{u}, \tilde{z}) + \mathcal{R}(\tilde{z} - z_k) : (\tilde{u}, \tilde{z}) \in \mathcal{F} \times \mathcal{Z}\}. \end{array} \right.$$

- ▶  $(IP)_\Pi$  has always solutions,
- ▶ we are able to define the piecewise constant interpolant  $(u^\Pi, z^\Pi) : [0, T] \rightarrow \mathcal{F} \times \mathcal{Z}$  with  $(u^\Pi(t), z^\Pi(t)) = (u_j, z_j)$  for  $t \in [t_{j-1}, t_j]$  for  $j = 0, \dots, N$ .

**Assumption:**  $(u_0, z_0) \in \mathcal{F} \times \mathcal{Z}$  are given **stable initial datum**, i.e.  $(u_0, z_0)$  satisfies the **global stability condition**  $(S)$  at  $t = 0$ .

**Theorem 1.** Assume that  $\mathcal{E}$  and  $\mathcal{R}$  satisfy the assumptions from above. Then, for each **stable**  $(u(0), z(0)) = (u_0, z_0)$ , there exists an **energetic solution**  $(u, z) : [0, T] \rightarrow \mathcal{F} \times \mathcal{Z}$  such that

$$u \in L^\infty([0, T]; W^{1,2}(\Omega; \mathbb{R}^d)),$$

$$z \in BV([0, T]; L^1(\Omega; \mathbb{R}_{\text{dev}}^{d \times d})).$$

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Moreover, let  $\Pi_k = \{0 = t_0^k < t_1^k < \dots < t_{N_k}^k = T\}$ ,  $k \in \mathbb{N}$ , be a sequence of partitions with fineness  $\Delta(\Pi_k) := \max\{t_j^k - t_{j-1}^k \mid j = 1, \dots, N_k\}$  tends to zero and  $(u^{\Pi_k}, z^{\Pi_k}) : [0, T] \rightarrow \mathcal{F} \times \mathcal{Z}$  be piecewise constant interpolants of the solution of the incremental problem  $(IP)_{\Pi_k}$ , then there exists a subsequence  $(\bar{u}_n, \bar{z}_n) := (u^{\Pi_{k_n}}, z^{\Pi_{k_n}})$  such that for all  $t \in [0, T]$  the following holds

$$\begin{aligned} \bar{z}_n(t) &\rightarrow z(t) \text{ in } \mathcal{Z}, \\ \mathcal{E}(t, \bar{u}_n(t), \bar{z}_n(t)) &\rightarrow \mathcal{E}(t, u(t), z(t)), \\ \int_0^t \mathcal{R}(\dot{\bar{z}}_n(s)) ds &\rightarrow \int_0^t \mathcal{R}(\dot{z}(s)) ds, \end{aligned}$$

there exists a subsequence  $(N_l^t)_{l \in \mathbb{N}}$  such that

$$\bar{u}_{N_l^t}(t) \rightarrow u(t) \text{ in } \mathcal{F} \text{ for } l \rightarrow 0.$$

## Conclusion

- ▶ Uniqueness result,
- ▶ Existence result for the same problem with an associated **heat equation**.



Assumptions on  $\theta_{\text{appl}}$  and  $I$  imply that

$$\|\dot{I}(t_1) - \dot{I}(t_2)\|_{(W^{1,2})'} + \|\dot{\theta}_{\text{appl}}(t_1) - \dot{\theta}_{\text{appl}}(t_2)\|_{L^\infty} \leq \omega(|t_1 - t_2|),$$

where  $\omega : [0, +\infty) \rightarrow [0, +\infty)$  is a modulus of continuity with  $\omega(0) = 0$ .