

Existence of similarity profiles for diffusion equations and systems

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Abstract

We study the existence of self-similar profiles for diffusion equations and reaction diffusion systems on the real line, where the different nontrivial limits are imposed for $x \rightarrow -\infty$ and $x \rightarrow +\infty$. These profiles solve a coupled system of nonlinear ODEs that can be treated by monotone operator theory.

1 Introduction

Similarity profiles play an important role in the longtime behavior of nonlinear diffusion problems as well as in certain reaction-diffusion systems, if we consider problems posed on the whole space $\Omega = \mathbb{R}^d$. For simplicity we treat the one-dimensional case $\mathbb{R}^d = \mathbb{R}$ only and leave the case $d > 1$ for subsequent work.

We consider a system of coupled diffusion equations on the real line $\Omega = \mathbb{R}^1$:

$$\dot{\mathbf{u}} = (\mathbf{A}(\mathbf{u}))_{xx} \quad \text{for } t > 0, x \in \mathbb{R}, \quad \mathbf{u}(t, \pm\infty) = \mathbf{U}_{\pm} \quad \text{for } t > 0, \quad (1.1)$$

where $\dot{\mathbf{u}} = \mathbf{u}_t$ and $\mathbf{A} : \mathbb{R}^m \rightarrow \mathbb{R}^m$ is a smooth monotone mapping. Here $\mathbf{U}_{\pm} = \mathbf{u}(t, \pm\infty) := \lim_{x \rightarrow \pm\infty} \mathbf{u}(t, x)$ are nontrivial boundary conditions, namely \mathbf{U}_- for $x \rightarrow -\infty$ and $\mathbf{U}_+ \neq \mathbf{U}_-$ for $x \rightarrow +\infty$.

The aim of this paper concerns the existence of self-similar solutions for this system. As \mathbf{u} cannot be scaled because of the fixed boundary conditions, we use the parabolic similarity coordinates $\tau = \log(t+1)$ and $y = x/(t+1)^{1/2}$. Setting $\tilde{\mathbf{u}}(\tau, y) = \mathbf{u}(t, x)$, the transformed equation reads

$$\tilde{\mathbf{u}}_{\tau} = (\mathbf{A}(\tilde{\mathbf{u}}))_{yy} + \frac{y}{2} \tilde{\mathbf{u}}_y \quad \text{for } \tau > 0, y \in \mathbb{R}, \quad \tilde{\mathbf{u}}(\tau, \pm\infty) = \mathbf{U}_{\pm}. \quad (1.2)$$

A stationary solution $\mathbf{U} \in BC^2(\mathbb{R}; \mathbb{R}^m)$ of this equation is called *similarity profile* as it gives rise to a self-similar solution

$$\mathbf{u}(t, x) = \mathbf{U}(x/(t+1)^{1/2})$$

of the original diffusion system (1.1).

Our main goal is to show that the following boundary value problem for a second order ODE in \mathbb{R}^m has a (unique) solution:

$$(\mathbf{A}(\mathbf{U}(y)))'' + \frac{y}{2} \mathbf{U}'(y) = 0 \quad \text{for } y \in \mathbb{R}, \quad \lim_{y \rightarrow \pm\infty} \mathbf{U}(y) = \mathbf{U}_{\pm}. \quad (1.3)$$

This equation is called the *profile equation*.

Our main existence result of self-similar profiles is formulated in Theorem 2.2 and concerns a vector-valued generalization of the scalar monotonicity result developed in [GaM98, Thm. 3.1]. The advantage of using monotonicity in contrast to the ODE-type arguments in previous works, see e.g. [Sha76, vaP77b], is that we can also handle the vector-valued case.

Section 2 provides a careful theory on existence and uniqueness of similarity profiles solving (1.3). In particular, we show that the solutions and their derivatives can be estimated in a linear way by $\Delta_{\pm} := |U_+ - U_-|$ with prefactors that are given explicitly in terms of the constants $\delta, a_{lo}, a_{up} = \text{Lip}(\mathbf{A})$, see (2.6), where the crucial assumption is the monotonicity $\langle \mathbf{A}(\mathbf{u}) - \mathbf{A}(\mathbf{w}), \mathbf{u} - \mathbf{w} \rangle \geq a_{lo} |\mathbf{u} - \mathbf{w}|^2 \geq 0$.

In Section 3 we specialize to the scalar case and improve the estimates significantly. We show monotonicity of the profile $U : \mathbb{R} \rightarrow [U_-, U_+]$ and exponential decay of the flux $Q(y) = A'(U(y))U'(y)$, namely $0 \leq Q(y) \leq e^{-y^2/(4D^*)}$, where $D^* = \max \{ A'(u) \mid u \in [U_-, U_+] \}$. In particular, we allow for degenerate cases where $A'(U_+) = 0$ and $A'(U_-) = 0$, which may lead to the case $U(y) = U_*$ for all $y \geq y_+^*$ if $A'(u) = \mathcal{O}(U_+ - u)$ for $u \nearrow U_+$.

In Section 4 we study the stability of the similarity profile U as steady solution of the parabolically rescaled diffusion equation

$$u_{\tau} = (A(u))_{yy} + \frac{y}{2} u_y \quad \text{for } (t, y) \in]0, \infty[\times \mathbb{R}, \quad u(\tau, \pm\infty) = U_{\pm}. \quad (1.4)$$

For this, we consider relative entropies of the form

$$\mathcal{H}_{\phi}(u(\tau)) = \int_{\mathbb{R}} \phi(u(\tau, y)/U(y)) U(y) dy$$

for suitable convex functions ϕ with $\phi(1) = 0 = \phi'(1)$. Theorem 4.1 considers the case of a general A with $|A''(u)| \leq C_A < \infty$ and Theorem 4.2 treats the porous medium equation with $A(u) = u^m$. In both cases we provide conditions on U that allow us to conclude a global decay estimate in the Hellinger distance

$$c_0 \left\| \sqrt{u(\tau, \cdot)} - \sqrt{U} \right\|_{L^2(\mathbb{R})}^2 \leq \mathcal{H}_{\phi}(u(\tau)) \leq e^{-\Lambda\tau} \mathcal{H}_{\phi}(u(0)) \quad \text{for all } \tau > 0,$$

with $\Lambda = \frac{1}{2} - \mathcal{O}(|U_+ - U_-|) \leq 1/2$. In particular, for the flat profiles $U \equiv U_{\pm}$ we always obtain the trivial decay like $e^{-\tau/2}$ which is induced by the drift term $\frac{y}{2} u_y$ only. We also refer to [vaP77a] for convergence results to self-similar profiles, but they are quite different and rely on comparison principle arguments, whereas our entropy approach can be applied to systems as well, see [MHM15, MiM18, MiS23].

Section 5 can be seen as a preparation for the theory in [MiS23] that is concerned with reaction-diffusion systems of the type

$$\dot{\mathbf{c}} = \mathbf{D}\mathbf{c}_{xx} + \mathbf{R}(\mathbf{c}), \quad \mathbf{c}(t, \pm\infty) = \mathbf{C}_{\pm},$$

where we impose nontrivial boundary conditions at $x = \pm\infty$. To study the diffusive mixing as introduced in [GaM98], we transform into parabolic similarity coordinates as for (1.2) and obtain

$$\mathbf{c}_{\tau} = \mathbf{D}\mathbf{c}_{yy} + \frac{y}{2}\mathbf{c}_y + e^{\tau}\mathbf{R}(\mathbf{c}), \quad \mathbf{c}(\tau, \pm\infty) = \mathbf{C}_{\pm}.$$

While in [MiS23] the term $e^{\tau}\mathbf{R}(\mathbf{c})$ is treated in full generality, we look here at the simplified model where we assume $\mathbf{R}(\mathbf{c}) = 0$ as an algebraic constraint and replace the limit “ $\infty \cdot \mathbf{0}$ ” of “ $e^{\tau} \cdot \mathbf{R}(\mathbf{c})$ ” for $\tau \rightarrow \infty$ by a vector-valued Lagrange multiplier $\boldsymbol{\lambda}$ lying in the span of $\mathbf{R}(\cdot)$ (the stoichiometric subspace, see Section 5.1).

The set of equilibria $\{ \mathbf{c} \in \mathbb{R}^{i_*} \mid \mathbf{R}(\mathbf{c}) = 0 \}$ is parametrized in the form $\mathbf{c} = \Psi(\mathbf{u})$ for $\mathbf{u} \in \mathbb{R}^m$ such that $\mathbb{Q}\Psi(\mathbf{u}) = \mathbf{u}$ for a suitable linear stoichiometric mapping \mathbb{Q} . This leads to the reduced parabolic equation

$$\mathbf{u}_\tau = (\mathbf{A}(\mathbf{u}))_{yy} + \frac{y}{2}\mathbf{u} \quad \text{with } \mathbf{A}(\mathbf{u}) = \mathbb{Q}\mathbf{D}\Psi(\mathbf{u}).$$

In Section 5 we provide several examples in which we are able to specify conditions on the reactions and the diffusion constants in $\mathbf{D} = \text{diag}(d_j)$ that guarantee that $\mathbf{u} \mapsto \mathbf{A}(\mathbf{u})$ is indeed monotone and satisfies the assumptions of the main existence result for self-similar profiles \mathbf{U} solving (1.3). In particular, Section 5.5 considers a case with three species, i.e. $\mathbf{c} \in \mathbb{R}^3$ and one reaction, such that $\mathbf{u} \in \mathbb{R}^2$ is vector-valued.

Section 6 provides two more systems where self-similar profiles are important to describe the longtime asymptotics. First, we recall the results in [BrK92, GaM98] which establish diffusive mixing for roll pattern in the Ginzburg-Landau equation with real coefficients. Secondly, we comment on the recently established system of degenerate parabolic equations that includes the porous medium equation and is expected to have a rich structure of self-similar profiles, see [Mie23].

2 Vector-valued self-similar profiles

To provide a suitable functional analytical framework for our existence and uniqueness theory, we set

$$\bar{\mathbf{u}}_\pm(y) := \begin{cases} \mathbf{U}_\pm & \text{for } \pm y > 0, \\ \frac{1}{2}(\mathbf{U}_- + \mathbf{U}_+) & \text{for } y = 0. \end{cases}$$

In the following, we give a weak version of the profile equation (1.3). We say that $\mathbf{U} \in L^2_{\text{loc}}(\mathbb{R}; \mathbb{R}^m)$ is a *stationary profile* for (1.2) if

$$\exists \mathbf{v} \in H^1(\mathbb{R}; \mathbb{R}^m) : \quad \mathbf{U} = \bar{\mathbf{u}}_\pm + \mathbf{v}' \quad \text{and} \quad (2.1a)$$

$$\forall \psi \in C_c^2(\mathbb{R}; \mathbb{R}^m) : \quad \int_{\mathbb{R}} \left(\mathbf{A}(\mathbf{U}(y)) \cdot \psi''(y) - \mathbf{U}(y) \cdot \left(\frac{y}{2} \psi(y) \right)' \right) dy = 0. \quad (2.1b)$$

In this formulation \mathbf{U} does not need to have any derivative and may be even discontinuous. We will see that this weak form is important because in degenerate cases the solution \mathbf{u} has low regularity, while we are still able to prove existence of solutions. For instance, in the very degenerate case $\mathbf{A}(\mathbf{U}_+) = \mathbf{A}(\mathbf{U}_-)$ (which is still consistent with the monotonicity desired below, but gives $\mathbf{D}\mathbf{A}((1-\theta)\mathbf{U}_- + \theta\mathbf{U}_+)(\mathbf{U}_+ - \mathbf{U}_-) = 0$ for all $\theta \in [0, 1]$), we see that the piecewise constant function $\mathbf{U} = \bar{\mathbf{u}}_\pm$ is a stationary profile solving (2.1).

We will see later in the Sections 3 and 4 that the scalar porous medium equation with $\mathbf{A}(u) = \frac{1}{m}u^m \in \mathbb{R}^1$ and $m > 1$, leads in the case $U_- = 0$ to profiles $U \in BC^0(\mathbb{R})$ with $U(y) = 0$ for all $y \leq y_* < 0$ and $U(y) = c(y - y_*)^{1/(m-1)} + \text{h.o.t.}$ for $y \rightarrow y^+$. Hence, U is not twice differentiable for $m \geq 2$ and U' does not lie in $H^1_{\text{loc}}(\mathbb{R})$ for $m \geq 3$.

Moreover, the requirement (2.1a) is slightly stronger than asking for $\mathbf{U} - \bar{\mathbf{u}}_\pm \in L^2(\mathbb{R}; \mathbb{R}^m)$. Indeed, using the embedding $H^1(\mathbb{R}; \mathbb{R}^m) \subset C^0_0(\mathbb{R}; \mathbb{R}^m)$ (space of continuous and decaying functions), (2.1a) implies that the following improper integral exists:

$$\int_{\mathbb{R}} (\mathbf{U} - \bar{\mathbf{u}}_\pm) dy = \lim_{a, b \rightarrow \infty} \int_{-a}^b (\mathbf{U} - \bar{\mathbf{u}}_\pm) dy = \lim_{a, b \rightarrow \infty} (\mathbf{v}(b) - \mathbf{v}(-a)) = 0. \quad (2.2)$$

In the following example of linear equations we provide explicit solutions in terms of vector-valued error functions (integrals of Gaussians). We especially address the case of degenerate $\mathbf{A}(\mathbf{u}) = \mathbb{A}\mathbf{u}$, where \mathbb{A} has purely imaginary eigenvalues, in that case \mathbf{U} may be discontinuous or may converge to $\bar{\mathbf{u}}_{\pm}$ only like $\mathcal{O}(1/|y|)$. Moreover, we address the approximation of \mathbb{A} by the regular case $\mathbb{A}_{\varepsilon} = \mathbb{A} + \varepsilon\mathbb{I}$, which will be done in the proof of the main existence result in Theorem 2.2, see Step 5 there.

Example 2.1 (Linear, vector-valued case) We consider the case $\mathbf{A}(\mathbf{u}) = \mathbb{A}\mathbf{u}$ where the matrix $\mathbb{A} \in \mathbb{R}^{m \times m}$ is monotone, i.e. $\mathbf{v} \cdot \mathbb{A}\mathbf{v} \geq a_{10}|\mathbf{v}|^2$ with $a_{10} \geq 0$.

(I) At first, let $a_{10} > 0$ such that \mathbb{A}^{-1} exists and all its eigenvalues have positive real parts. From $\mathbb{A}\mathbf{U}'' + \frac{y}{2}\mathbf{U}' = 0$ we easily find $\mathbf{U}'(y) = e^{-y^2(4\mathbb{A})^{-1}}\mathbf{U}'(0)$. Using $\int_{\mathbb{R}} e^{-y^2(4\mathbb{A})^{-1}} dy = (4\pi\mathbb{A})^{1/2}$ (here $\mathbb{A}^{1/2}$ is the root with eigenvalues satisfying $|\arg \lambda| < \pi/4$), we find the profile connecting \mathbf{U}_- and \mathbf{U}_+ in the form

$$\mathbf{U}(y) = \mathbf{U}_- + \int_{-\infty}^y \frac{1}{\sqrt{4\pi}} \mathbb{A}^{-1/2} e^{-\eta^2(4\mathbb{A})^{-1}} d\eta (\mathbf{U}_+ - \mathbf{U}_-). \quad (2.3)$$

(II) The above formula can also be extended to the case $a_{10} = 0$, where \mathbb{A}^{-1} may no longer exist. For this it suffices to replace \mathbb{A} by $\mathbb{A}_{\varepsilon} = \mathbb{A} + \varepsilon\mathbb{I}$ and take the limit $\varepsilon \rightarrow 0^+$. Indeed, if \mathbb{A} has a single real eigenvalue $\lambda = 0$, then \mathbb{A}_{ε} has the eigenvalue $\lambda_{\varepsilon} = \varepsilon$. Using a suitable basis, it suffices to observe that $\int_{-\infty}^y \frac{1}{\sqrt{4\pi\lambda_{\varepsilon}}} e^{-\eta^2(4\lambda_{\varepsilon})^{-1}} d\eta = \Phi(y/\sqrt{\varepsilon})$ converges to 0 for $y < 0$ and to 1 for $y > 1$. Thus, $\mathbf{U}_{\varepsilon} = \mathbf{U}_- + \Phi(y/\sqrt{\varepsilon})(\mathbf{U}_+ - \mathbf{U}_-)$ converges to the piecewise constant limit $\bar{\mathbf{u}}_{\pm}$.

(III) If \mathbb{A} has a single pair of purely imaginary eigenvalues $\pm i\omega$ with $\omega > 0$, then the limit procedure leads to the linear ODE

$$\mathbb{A}_{\varepsilon}\mathbf{U}_{\varepsilon}'' + \frac{y}{2}\mathbf{U}_{\varepsilon}' = 0 \quad \text{with } \mathbb{A}_{\varepsilon} = \begin{pmatrix} \varepsilon & -\omega \\ \omega & \varepsilon \end{pmatrix}.$$

Turning the vector $\mathbf{U}_{\varepsilon} = (U_{\varepsilon}^1, U_{\varepsilon}^2)$ into a complex number $U_{\varepsilon} = U_{\varepsilon}^1 + iU_{\varepsilon}^2 \in \mathbb{C}$, we have to solve $2\lambda_{\varepsilon}U_{\varepsilon}'' + yU_{\varepsilon}' = 0$ with $\lambda_{\varepsilon} = \varepsilon + i\omega$. Of course, (2.3) holds again but now in (scalar) complex numbers, and the integrand in (2.3) (which equals U_{ε}' up to the factor $U_+ - U_-$) reads

$$\frac{1}{\sqrt{4\pi\lambda_{\varepsilon}}} e^{i\eta^2\omega/(4\varepsilon^2+4\omega^2)} e^{-\eta^2\varepsilon/(4\varepsilon^2+4\omega^2)}.$$

Hence, for $\varepsilon \rightarrow 0^+$ the exponential decay of the integrand is lost, but the improper integrals for $\eta \in]-\infty, y[$ still have a good limit because of the increasing oscillations as in the Fresnel integrals $\int_{\mathbb{R}} e^{i\eta^2/(4\omega)} d\eta = \sqrt{2\pi\omega}(1+i)$. We obtain the expansion

$$U_0(y) = U_- - \frac{i\sqrt{2}\omega}{y} e^{iy^2/(4\omega)} + \mathcal{O}(1/|y|^3) \quad \text{for } y \rightarrow -\infty.$$

Clearly, U_0 can be decomposed into $U_0(y) = \bar{\mathbf{u}}_{\pm}(y) + v'(y)$ with $v \in H^1(\mathbb{R}; \mathbb{C})$ where $|v(y)| \leq C/(1+y^2)$ and $|v'(y)| \leq C/(1+|y|)$. Moreover, the improper integral $\int_{\mathbb{R}} y(U_0 - \bar{\mathbf{u}}_{\pm}) dy$ exists and equals $i\omega(U_- - U_+)$.

For the proof of the following result, we introduce a smoothed version of the function $\bar{\mathbf{u}}_{\pm}$ by fixing an interpolating function $\chi \in C^{\infty}(\mathbb{R}; [-1, 1])$ satisfying

$$\chi(y) = \pm 1 \quad \text{for } \pm y \geq 1 \quad \text{and} \quad \chi(-y) = -\chi(y).$$

For given $\mathbf{U}_-, \mathbf{U}_+ \in \mathbb{R}^m$ and a parameter $a_{\text{up}} > 0$, which will be specified below, we define the interpolation functions $\tilde{\mathbf{u}}_{\pm} \in C^\infty(\mathbb{R}; \mathbb{R}^m)$ via

$$\tilde{\mathbf{u}}_{\pm}(y) = \frac{1-\chi(y/\sqrt{a_{\text{up}}})}{2} \mathbf{U}_- + \frac{1+\chi(y/\sqrt{a_{\text{up}}})}{2} \mathbf{U}_+ \quad (2.4)$$

such that $\tilde{\mathbf{u}}_{\pm}(y) = \bar{\mathbf{u}}_{\pm}(y)$ for $|y| \geq 1/\sqrt{a_{\text{up}}}$. In the sequel, C_χ will denote (possibly different) constants that depend only on χ , and, thus, can be seen as universal constants that are independent of the data \mathbf{A} and \mathbf{U}_{\pm} of our problem. For example, the L^2 norm of $\tilde{\mathbf{u}}'_{\pm}$ and $\tilde{\mathbf{u}}''_{\pm}$ scale as follows:

$$\|y^j \tilde{\mathbf{u}}'_{\pm}\|_{L^2} \leq C_1^\chi a_{\text{up}}^{(2j-1)/4} \Delta_{\pm} \quad \text{and} \quad \|\tilde{\mathbf{u}}''_{\pm}\|_{L^2} \leq C_2^\chi a_{\text{up}}^{-3/4} \Delta_{\pm} \quad \text{with} \quad \Delta_{\pm} := |\mathbf{U}_+ - \mathbf{U}_-|. \quad (2.5)$$

The proof of the following result is based on [Gam98, Thm. 3.1], which exploits monotonicity arguments to obtain existence and uniqueness. Here we generalize this approach to the vector-valued case and provide a careful bookkeeping of constants in the a priori estimates.

Theorem 2.2 (Existence of similarity profiles) *Let $\mathbf{A} \in C^1(\mathbb{R}^m; \mathbb{R}^m)$ satisfy*

$$\exists a_{\text{up}} > 0 \forall \mathbf{u}, \mathbf{w} \in \mathbb{R}^m : |\mathbf{A}(\mathbf{u}) - \mathbf{A}(\mathbf{w})| \leq a_{\text{up}} |\mathbf{u} - \mathbf{w}|, \quad (2.6a)$$

$$\exists a_{\text{lo}} \geq 0 \forall \mathbf{u}, \mathbf{w} \in \mathbb{R}^m : \langle \mathbf{A}(\mathbf{u}) - \mathbf{A}(\mathbf{w}), \mathbf{u} - \mathbf{w} \rangle \geq a_{\text{lo}} |\mathbf{u} - \mathbf{w}|^2, \quad (2.6b)$$

$$\exists \delta \geq 0 \forall \mathbf{u}, \mathbf{v} \in \mathbb{R}^m : \langle \mathbf{v}, \mathbf{D}\mathbf{A}(\mathbf{u})\mathbf{v} \rangle \geq \delta |\mathbf{D}\mathbf{A}(\mathbf{u})\mathbf{v}|^2. \quad (2.6c)$$

If $a_{\text{lo}} + \delta > 0$, then for each pair $(\mathbf{U}_-, \mathbf{U}_+) \in \mathbb{R}^m \times \mathbb{R}^m$ there exists a unique stationary profile $\mathbf{U} = \bar{\mathbf{u}}_{\pm} + \mathbf{v}'$ satisfying (2.1) and the a priori estimate

$$a_{\text{lo}} \|\mathbf{U}'\|_{L^2}^2 + \|\mathbf{U} - \tilde{\mathbf{u}}_{\pm}\|_{L^2}^2 + \frac{1}{a_{\text{up}}} \|\mathbf{v}\|_{H^1}^2 \leq C_\chi a_{\text{up}}^{1/2} \Delta_{\pm}^2. \quad (2.7)$$

Moreover, the flux $\mathbf{q}(y) = (\mathbf{A}(\mathbf{U}(y)))' = \mathbf{D}\mathbf{A}(\mathbf{U}(y))\mathbf{U}'(y)$ satisfies the pointwise estimate

$$|\mathbf{q}(y)| = |\mathbf{A}(\mathbf{U})'| \leq e^{-\delta y^2/4} C_\chi a_{\text{up}}^{1/2} \Delta_{\pm} \quad \text{for all } y \in \mathbb{R}. \quad (2.8)$$

For $\delta > 0$ we have the integral relations

$$\begin{aligned} \int_{\mathbb{R}} (\mathbf{U}(y) - \bar{\mathbf{u}}_{\pm}(y)) dy &= \mathbf{0} \in \mathbb{R}^m \quad \text{and} \\ \int_{\mathbb{R}} y (\bar{\mathbf{u}}_{\pm}(y) - \mathbf{U}(y)) dy &= \mathbf{A}(\mathbf{U}_+) - \mathbf{A}(\mathbf{U}_-) \in \mathbb{R}^m. \end{aligned} \quad (2.9)$$

If $\mathbf{D}\mathbf{A}(\mathbf{u}) \in \mathbb{R}^{m \times m}$ is invertible (as is always the case for $a_{\text{lo}} > 0$), then $\mathbf{U} \in \text{BC}^0(\mathbb{R}; \mathbb{R}^m) \cap \text{H}_{\text{loc}}^1(\mathbb{R}; \mathbb{R}^m)$. If \mathbf{A} additionally satisfies

$$\mathbf{A} \in C_{\text{loc}}^k(\mathbb{R}^m; \mathbb{R}^m) \quad \text{for } k \in \mathbb{N} \quad \text{and} \quad \forall y \in \mathbb{R} : \mathbf{D}\mathbf{A}(\mathbf{U}(y)) \in \mathbb{R}^{m \times m} \text{ is invertible}, \quad (2.10)$$

then the profile \mathbf{U} satisfies $\mathbf{U} \in \text{BC}^k(\mathbb{R}; \mathbb{R}^m)$.

Before providing the proof we remark that conditions (2.6a) and (2.6b) imply condition (2.6c) with $\delta = a_{\text{lo}}/(a_{\text{up}})^2$. However, $\delta \gg a_{\text{lo}}/(a_{\text{up}})^2$ is possible, and interesting cases occur for $a_{\text{lo}} = 0$ and $\delta = 1/a_{\text{up}} > 0$, which is the case for the scalar porous medium equation in Section 4.

We emphasize that an important point in the proof is the exploitation of the term $\frac{1}{2}y \cdot \mathbf{u}'$, which generates strict monotonicity and an a priori estimate for $\|\mathbf{U} - \tilde{\mathbf{u}}_{\pm}\|_{L^2}$ independent of \mathbf{A} , see (2.7).

Proof. Throughout this proof all constants C_{χ} only depend on χ , which is kept fixed, whereas the dependence on $\Delta_{\pm} = |\mathbf{U}_+ - \mathbf{U}_-|$ and \mathbf{A} (via a_{lo} , a_{up} , and δ) will be given explicitly.

We first treat the nondegenerate case $a_{\text{lo}} > 0$. There we obtain a suitable maximally strictly monotone operator \mathcal{A} that provides existence and uniqueness of solutions. The case $a_{\text{lo}} = 0$ is treated by regularizing \mathbf{A} to $\mathbf{A}_{\varepsilon}(\mathbf{u}) = \mathbf{A}(\mathbf{u}) + \varepsilon \mathbf{u}$, which gives $a_{\text{lo}\varepsilon} = \varepsilon > 0$ and solutions \mathbf{U}_{ε} . Using ε -independent a priori estimates for $\|\mathbf{U}_{\varepsilon} - \tilde{\mathbf{u}}_{\pm}\|_{L^2}$ we obtain a weak limit \mathbf{U} which is the desired profile.

Step 1. Preparations: We proceed as is [GaM98, Thm. 3.1] and search for \mathbf{U} in the form $\mathbf{U}(y) = \tilde{\mathbf{u}}_{\pm}(y) + \mathbf{v}'(y)$ with $\mathbf{v} \in H^1(\mathbb{R}; \mathbb{R}^m)$. Inserting the ansatz for \mathbf{u} into the stationarity equation, we obtain (in $H^{-2}(\mathbb{R}; \mathbb{R}^m)$) the relation

$$0 = \mathbf{A}(\tilde{\mathbf{u}}_{\pm} + \mathbf{v}')'' + \left(\frac{y}{2}(\tilde{\mathbf{u}}_{\pm} + \mathbf{v}')\right)' - \frac{1}{2}(\tilde{\mathbf{u}}_{\pm} + \mathbf{v}').$$

This equation can be integrated with respect to y yielding the relation (in $H^{-1}(\mathbb{R}; \mathbb{R}^m)$)

$$0 = \mathbf{A}(\tilde{\mathbf{u}}_{\pm} + \mathbf{v}')' + \frac{y}{2} \mathbf{v}' - \frac{1}{2} \mathbf{v} + \mathbf{g}, \quad \text{where } \mathbf{g}(y) = \int_{-\infty}^y \frac{\eta}{2} \tilde{\mathbf{u}}'_{\pm}(\eta) d\eta. \quad (2.11)$$

By construction, we have $\mathbf{g} \in C_c^{\infty}(\mathbb{R}; \mathbb{R}^m)$ and $\mathbf{g}(y) = 0$ for $|y| \geq 1/\sqrt{a_{\text{up}}}$ (use that $\tilde{\mathbf{u}}'_{\pm}$ is even, see (2.4)). Moreover, by the scaling of $\tilde{\mathbf{u}}_{\pm}$ via a_{up} one obtains

$$\|\mathbf{g}\|_{L^2(\mathbb{R})} \leq C_{\chi} a_{\text{up}}^{3/4}. \quad (2.12)$$

Step 2. Monotone operator theory for $a_{\text{lo}} > 0$: We set $\mathbf{H} := H^1(\mathbb{R}; \mathbb{R}^m)$, which gives $\mathbf{H}^* = H^{-1}(\mathbb{R}; \mathbb{R}^m)$, and define the monotone operator $\mathcal{A} : \text{dom}(\mathcal{A}) \subset \mathbf{H} \rightarrow \mathbf{H}^*$ via

$$\text{dom}(\mathcal{A}) := \left\{ \mathbf{v} \in H^1(\mathbb{R}; \mathbb{R}^m) \mid y\mathbf{v}'(y) \in \mathbf{H}^* \right\} \text{ and } \mathcal{A}(\mathbf{v}) := -(\mathbf{A}(\tilde{\mathbf{u}}_{\pm} + \mathbf{v}'))' - \frac{y}{2} \mathbf{v}' + \frac{1}{2} \mathbf{v}.$$

Based on the assumptions (2.6) and slightly generalizing the results in [GaM98, Thm. 3.1], we obtain that \mathcal{A} is a maximal monotone operator which is strongly monotone, namely

$$\forall \mathbf{v}_1, \mathbf{v}_2 \in \text{dom}(\mathcal{A}) : \quad \langle \mathcal{A}(\mathbf{v}_1) - \mathcal{A}(\mathbf{v}_2), \mathbf{v}_1 - \mathbf{v}_2 \rangle_{\mathbf{H}} \geq \int_{\mathbb{R}} \left(a_{\text{lo}} |\mathbf{v}'_1 - \mathbf{v}'_2|^2 + \frac{1}{2} |\mathbf{v}_1 - \mathbf{v}_2|^2 \right) dy, \quad (2.13)$$

and hence also coercive because of $a_{\text{lo}} > 0$. Thus, (2.11), which now takes the form $\mathcal{A}(\mathbf{v}) = \mathbf{g}$, has exactly one solution $\mathbf{v} \in \mathbf{H} = H^1(\mathbb{R}; \mathbb{R}^m)$ such that the unique solution $\mathbf{U} = \tilde{\mathbf{u}}_{\pm} + \mathbf{v}'$ is constructed.

For the reader's convenience and for checking that the vector-valued case works exactly the same way, we repeat the argument. We first observe that $\mathbf{v} \mapsto \mathcal{A}_1(\mathbf{v}) := -(\mathbf{A}(\tilde{\mathbf{u}}_{\pm} + \mathbf{v}'))' + \frac{1}{2} \mathbf{v}$ is monotone and continuous from \mathbf{H} to \mathbf{H}^* , hence \mathcal{A}_1 is a maximally monotone operator, cf. [Zei90, Prop. 32.7, p. 854]. Next, we consider the linear operator $\mathbf{v} \mapsto \mathcal{A}_2(\mathbf{v}) := \frac{y}{2} \mathbf{v}'$ with $\text{dom}(\mathcal{A}_2) = \text{dom}(\mathcal{A})$. Hence, \mathcal{A}_2 is maximally monotone by [Zei90, Thm. 32.L, p. 897]. (A linear operator L is maximally monotone if and only if L and L^* are monotone and L has a closed graph.) With this we conclude that $\mathcal{A} = \mathcal{A}_1 + \mathcal{A}_2$ is maximally monotone by [Zei90, Thm. 32.I, p. 897], as both are maximally monotone

and $\text{dom}(\mathcal{A}_2) \cap \text{int}(\text{dom}(\mathcal{A}_1)) = \text{dom}(\mathcal{A}) \cap \mathbf{H} = \text{dom}(\mathcal{A}) \neq \emptyset$. Finally, we use (2.13) with $\mathbf{v}_2 = 0$ and conclude that \mathcal{A} is strongly coercive, i.e. $\langle \mathcal{A}(v), v \rangle / \|v\|_{\mathbf{H}} \rightarrow \infty$ for $\|v\|_{\mathbf{H}} \rightarrow \infty$. Then, [Zei90, Cor. 32.35, p. 887] implies that \mathcal{A} is surjective.

Step 3. A priori estimates for $a_{10} > 0$: The first a priori estimate is obtained by testing (2.11) with \mathbf{v} itself and using the monotonicity of \mathbf{A} . Recalling $\Delta_{\pm} := |\mathbf{U}_+ - \mathbf{U}_-|$ and employing (2.6b) we have

$$\begin{aligned} a_{10} \|\mathbf{v}'\|_{L^2}^2 + \frac{3}{4} \|\mathbf{v}\|_{L^2}^2 &\leq \int_{\mathbb{R}} \left((\mathbf{A}(\tilde{\mathbf{u}}_{\pm} + \mathbf{v}') - \mathbf{A}(\tilde{\mathbf{u}}_{\pm})) \cdot \mathbf{v}' + \frac{3}{4} |\mathbf{v}|^2 \right) dy \\ &= \int_{\mathbb{R}} \left(\left(\frac{y}{2} \mathbf{v}' - \frac{1}{2} \mathbf{v} + \mathbf{g} \right) \cdot \mathbf{v} - \mathbf{A}(\tilde{\mathbf{u}}_{\pm}) \cdot \mathbf{v}' + \frac{3}{4} |\mathbf{v}|^2 \right) dy = \int_{\mathbb{R}} (\mathbf{g} \cdot \mathbf{v} - \mathbf{A}(\tilde{\mathbf{u}}_{\pm})' \cdot \mathbf{v}) dy \\ &\leq (\|\mathbf{g}\|_{L^2} + \|\mathbf{D}\mathbf{A}(\tilde{\mathbf{u}}_{\pm})\tilde{\mathbf{u}}'_{\pm}\|_{L^2}) \|\mathbf{v}\|_{L^2} \leq C_{\chi} a_{\text{up}}^{3/4} \Delta_{\pm} \|\mathbf{v}\|_{L^2}, \end{aligned} \quad (2.14)$$

where the last estimate used (2.5) and (2.12).

A second a priori estimate for $a_{10} > 0$ uses the monotonicity which implies $\mathbf{D}\mathbf{A}(\mathbf{u})\mathbf{w} \cdot \mathbf{w} \geq a_{10} |\mathbf{w}|^2$ such that $a_{10} > 0$ gives the invertibility of $\mathbf{D}\mathbf{A}(\mathbf{u}) \in \mathbb{R}^{m \times m}$. Thus, (2.11) implies that $\mathbf{U} = \tilde{\mathbf{u}}_{\pm} + \mathbf{v}'$ lies in $H_{\text{loc}}^1(\mathbb{R}; \mathbb{R}^m)$ and satisfies the strong profile equation $(\mathbf{D}\mathbf{A}(\mathbf{U})\mathbf{U}')' + \frac{y}{2}\mathbf{U}' = 0$ in \mathbf{H}^* . In particular, we can test this equation with $\mathbf{U} - \tilde{\mathbf{u}}_{\pm} = \mathbf{v}'$ giving

$$\int_{\mathbb{R}} \mathbf{D}\mathbf{A}(\mathbf{U})\mathbf{U}' \cdot \mathbf{U}' dy = \int_{\mathbb{R}} (\mathbf{A}(\mathbf{U})' \cdot \tilde{\mathbf{u}}'_{\pm} + \frac{y}{2}\mathbf{U}' \cdot (\mathbf{U} - \tilde{\mathbf{u}}_{\pm})) dy.$$

With this, (2.6b), and suitable integrations by part we obtain

$$\begin{aligned} a_{10} \|\mathbf{U}'\|_{L^2}^2 + \frac{1}{4} \|\mathbf{U} - \tilde{\mathbf{u}}_{\pm}\|_{L^2}^2 &\leq \int_{\mathbb{R}} \left(\mathbf{D}\mathbf{A}(\mathbf{U})\mathbf{U}' \cdot \mathbf{U}' + \frac{1}{4} |\mathbf{U} - \tilde{\mathbf{u}}_{\pm}|^2 \right) dy \\ &= \int_{\mathbb{R}} \left(\mathbf{A}(\mathbf{U})' \cdot \tilde{\mathbf{u}}'_{\pm} + \frac{y}{2}\mathbf{U}' \cdot (\mathbf{U} - \tilde{\mathbf{u}}_{\pm}) + \frac{1}{4} |\mathbf{U} - \tilde{\mathbf{u}}_{\pm}|^2 \right) dy \\ &= \int_{\mathbb{R}} \left(\mathbf{A}(\tilde{\mathbf{u}}_{\pm})' \cdot \tilde{\mathbf{u}}'_{\pm} + (\mathbf{A}(\tilde{\mathbf{u}}_{\pm}) - \mathbf{A}(\mathbf{U})) \cdot \tilde{\mathbf{u}}''_{\pm} + \frac{y}{2}\tilde{\mathbf{u}}'_{\pm} \cdot (\mathbf{U} - \tilde{\mathbf{u}}_{\pm}) \right) dy \\ &\leq a_{\text{up}} \|\tilde{\mathbf{u}}'_{\pm}\|_{L^2}^2 + a_{\text{up}} \|\mathbf{U} - \tilde{\mathbf{u}}_{\pm}\|_{L^2} \|\tilde{\mathbf{u}}''_{\pm}\|_{L^2} + \|\frac{y}{2}\tilde{\mathbf{u}}'_{\pm}\|_{L^2} \|\mathbf{U} - \tilde{\mathbf{u}}_{\pm}\|_{L^2} \\ &\leq C_{\chi} (a_{\text{up}}^{1/2} \Delta_{\pm}^2 + (a_{\text{up}} a_{\text{up}}^{-3/4} + a_{\text{up}}^{1/4}) \Delta_{\pm}) \|\mathbf{U} - \tilde{\mathbf{u}}_{\pm}\|_{L^2}. \end{aligned}$$

Together with (2.14) we have established the a priori estimate (2.7).

Step 4. Exponential convergence for $a_{10}, \delta > 0$: Using $a_{10} > 0$ we have shown that the unique solution $\mathbf{U} = \tilde{\mathbf{u}}_{\pm} + \mathbf{v}'$ has the regularity $\mathbf{v} \in H^2(\mathbb{R}; \mathbb{R}^m)$. Thus, equation (2.11) shows that the flux $\mathbf{q} : y \mapsto \mathbf{A}(\mathbf{U}(y))' = \mathbf{D}\mathbf{A}(\mathbf{U}(y))\mathbf{U}'(y)$ lies in $H_{\text{loc}}^1(\mathbb{R}; \mathbb{R}^m)$. Because of $a_{10} > 0$ the Jacobian $\mathbf{D}\mathbf{A}(\mathbf{u}) \in \mathbb{R}^{m \times m}$ is invertible, which shows that \mathbf{q} satisfies $\mathbf{q}' + \frac{y}{2}\mathbf{D}\mathbf{A}(\mathbf{U})^{-1}\mathbf{q} = 0$. Thus, for $y \geq 0$ we find

$$\frac{d}{dy} |\mathbf{q}|^2 = -y \mathbf{q} \cdot \mathbf{D}\mathbf{A}(\mathbf{U})^{-1}\mathbf{q} \leq -y\delta |\mathbf{q}|^2,$$

where we used (2.6c) with $\mathbf{w} = \mathbf{D}\mathbf{A}(\mathbf{U})^{-1}\mathbf{q} = \mathbf{U}'$. Arguing similarly for $y \leq 0$ we arrive at $|\mathbf{q}(y)| \leq e^{-\delta y^2/4} |\mathbf{q}(0)|$ for $y \in \mathbb{R}$. Evaluating (2.11) at $y = 0$ gives $\mathbf{q}(0) = \frac{1}{2}\mathbf{v}(0) - \mathbf{g}(0)$. Using $\mathbf{v}(0) = \int_{-\infty}^0 e^{y/\sqrt{a_{\text{up}}}} (\mathbf{v}'(y) + \mathbf{v}(y)/\sqrt{a_{\text{up}}}) dy$ together with (2.7) and the scaling properties of \mathbf{g} yields $|\mathbf{q}(0)| \leq C_{\chi} a_{\text{up}}^{1/2} \Delta_{\pm}$. Hence, the flux estimate (2.8) is established.

Having \mathbf{q} under control, we return to the main equation (2.11) taking now the form $\mathbf{q} + \frac{y}{2}\mathbf{v}' - \frac{1}{2}\mathbf{v} + \mathbf{g} = 0$ and find the explicit representation in terms of \mathbf{q} :

$$\mathbf{v}(y) = \begin{cases} y \int_y^\infty \mathbf{h}(\eta) d\eta & \text{for } y > 0, \\ 2\mathbf{g}(0) + 2\mathbf{q}(0) & \text{for } y = 0, \\ -y \int_{-\infty}^y \mathbf{h}(\eta) d\eta & \text{for } y < 0, \end{cases} \quad \text{where } \mathbf{h}(\eta) = \frac{2}{\eta^2} (\mathbf{g}(\eta) + \mathbf{q}(\eta)). \quad (2.15)$$

By construction \mathbf{g} has support in $[-\sqrt{a_{\text{up}}}, \sqrt{a_{\text{up}}}]$ and satisfies $\|\mathbf{g}\|_{L^\infty} \leq C_\chi a_{\text{up}}^{1/2} \Delta_\pm$. Hence, we obtain $|\mathbf{g}(y)| \leq C_\chi a_{\text{up}}^{1/2} \Delta_\pm e^{-y^2/a_{\text{up}}}$. Setting $\gamma = \min\{1/a_{\text{up}}, \delta/4\} > 0$ and recalling (2.8) we find $|\mathbf{h}(y)| \leq C_\chi a_{\text{up}}^{1/2} \Delta_\pm e^{-\gamma y^2}/y^2$ and conclude

$$|\mathbf{v}(y)| \leq C_\chi a_{\text{up}}^{1/2} \Delta_\pm \Phi(\sqrt{\gamma} y) \quad \text{with } \Phi(z) := z \int_z^\infty \frac{2e^{-r^2}}{r^2} dr \leq 2e^{-z^2}.$$

Note that Φ has a continuous extension at $z = 0$ with $\Phi(0) \leq 2$, such that we also have a uniform bound for \mathbf{v} in the case $\delta = 0$.

With $y\mathbf{v}'(y) = \mathbf{v}(y) - 2\mathbf{q}(y) - 2\mathbf{g}(y)$ we obtain the pointwise a priori estimate

$$|\mathbf{v}(y)| + |y\mathbf{v}'(y)| \leq C_\chi a_{\text{up}}^{1/2} \Delta_\pm e^{-\gamma y^2} \quad \text{for } y \in \mathbb{R}. \quad (2.16)$$

Step 5. The degenerate case with $a_{\text{lo}} = 0$: We study the auxiliary problem where \mathbf{A} is replaced by $\mathbf{A}_\varepsilon : \mathbf{u} \mapsto \mathbf{A}(\mathbf{u}) + \varepsilon\mathbf{u}$ for $\varepsilon \in]0, 1[$. Then, \mathbf{A}_ε satisfies the assumptions (2.6) with $a_{\text{up}\varepsilon} = a_{\text{up}} + \varepsilon$, $a_{\text{lo}\varepsilon} = \varepsilon > 0$, and $\delta_\varepsilon = \delta/(1+\delta\varepsilon)$. To see the latter, we set $B = D\mathbf{A}(\mathbf{u})$ and $B_\varepsilon = B + \varepsilon I$ and observe

$$\begin{aligned} \delta_\varepsilon |B_\varepsilon \mathbf{w}|^2 &\leq \frac{\delta}{1+\delta\varepsilon} \left(|B\mathbf{w}|^2 + 2\varepsilon |\mathbf{w}| |B\mathbf{w}| + \varepsilon^2 |\mathbf{w}|^2 \right) \leq \frac{\delta}{1+\delta\varepsilon} \left((1+\delta\varepsilon) |B\mathbf{w}|^2 + (\varepsilon^2 + \frac{\varepsilon^2}{\delta\varepsilon}) |\mathbf{w}|^2 \right) \\ &= \delta |B\mathbf{w}|^2 + \varepsilon |\mathbf{w}|^2 \stackrel{(2.6c)}{\leq} \mathbf{w} \cdot B\mathbf{w} + \varepsilon |\mathbf{w}|^2 = \mathbf{w} \cdot B_\varepsilon \mathbf{w}, \end{aligned}$$

which is the desired replacement of (2.6c) for $\varepsilon > 0$.

By the previous steps, there are unique solutions $\mathbf{U}_\varepsilon = \tilde{\mathbf{u}}_\pm + \mathbf{v}'_\varepsilon$, where (2.7) provides a uniform bound for \mathbf{v}_ε in $H^1(\mathbb{R}; \mathbb{R}^m)$. Hence, after extracting a subsequence (not relabeled) we may assume

$$\mathbf{v}_\varepsilon \rightharpoonup \mathbf{v}_0 \text{ in } \mathbf{H} = H^1(\mathbb{R}; \mathbb{R}^m) \quad \text{and} \quad \mathbf{v}_\varepsilon \rightarrow \mathbf{v} \text{ in } L^2(\mathbb{R}; \mathbb{R}^m). \quad (2.17)$$

For the strong convergence, we employ the uniform decay estimate (2.16), where the decay factor $\gamma_\varepsilon = \min\{1/a_{\text{up}\varepsilon}, \delta_\varepsilon/4\}$ is uniformly bounded away from 0.

By the global Lipschitz continuity of \mathbf{A} we also have boundedness of $\mathbf{a}_\varepsilon = \mathbf{A}(\tilde{\mathbf{u}}_\pm + \mathbf{v}'_\varepsilon) - \mathbf{b}$ with $\mathbf{b}(y) := \mathbf{A}(\tilde{\mathbf{u}}_\pm(y))$ and may assume

$$\mathbf{a}_\varepsilon \rightharpoonup \mathbf{a}_0 \text{ in } L^2(\mathbb{R}; \mathbb{R}^m).$$

Clearly, for $\varepsilon > 0$ the function \mathbf{v}_ε solves (2.11) if and only if

$$0 = \mathbf{a}'_\varepsilon + \mathbf{b}' + \frac{y}{2}\mathbf{v}'_\varepsilon - \frac{1}{2}\mathbf{v}_\varepsilon + \mathbf{g} \quad \text{in } \mathbf{H}^* = H^{-1}(\mathbb{R}; \mathbb{R}^m). \quad (2.18)$$

Using the weak convergences of \mathbf{v}_ε in H^1 and \mathbf{a}_ε in L^2 , we see that this relation holds also for $\varepsilon = 0$. To show that \mathbf{v}_0 solves (2.11), or equivalently that the profile $\mathbf{U} = \tilde{\mathbf{u}}_\pm + \mathbf{v}'_0$ is a solution of (2.1), it remains to show that $\mathbf{a}_0(y) = \mathbf{A}(\tilde{\mathbf{u}}_\pm(y) + \mathbf{v}'_0(y)) - \mathbf{b}(y)$ a.e. on \mathbb{R} .

By the monotonicity of $\mathcal{B} : L^2(\mathbb{R}; \mathbb{R}^m) \rightarrow L^2(\mathbb{R}; \mathbb{R}^m)$; $\mathbf{w} \mapsto \mathbf{A}(\tilde{\mathbf{u}}_{\pm} + \mathbf{w}) - \mathbf{b}$ and Minty's monotonicity trick (see e.g. [Zei90, Ch. 25(4), p. 474]), it suffices to show that $\int_{\mathbb{R}} \mathbf{a}_{\varepsilon} \cdot \mathbf{v}'_{\varepsilon} \, dy \rightarrow \int_{\mathbb{R}} \mathbf{a}_0 \cdot \mathbf{v}'_0 \, dy$ for $\varepsilon \rightarrow 0^+$. For this, we can exploit (2.18) as follows:

$$\begin{aligned} \int_{\mathbb{R}} \mathbf{a}_{\varepsilon} \cdot \mathbf{v}'_{\varepsilon} \, dy &= \int_{\mathbb{R}} -\mathbf{a}'_{\varepsilon} \cdot \mathbf{v}_{\varepsilon} \, dy \stackrel{(2.18)}{=} \int_{\mathbb{R}} (\mathbf{b}' + \frac{y}{2} \mathbf{v}'_{\varepsilon} - \frac{1}{2} \mathbf{v}_{\varepsilon} + \mathbf{g}) \cdot \mathbf{v}_{\varepsilon} \, dy = \int_{\mathbb{R}} (\mathbf{b}' \cdot \mathbf{v}_{\varepsilon} - \frac{3}{4} |\mathbf{v}_{\varepsilon}|^2 + \mathbf{g} \cdot \mathbf{v}_{\varepsilon}) \, dy \\ &\rightarrow \int_{\mathbb{R}} (\mathbf{b}' \cdot \mathbf{v}_0 - \frac{3}{4} |\mathbf{v}_0|^2 + \mathbf{g} \cdot \mathbf{v}_0) \, dy \stackrel{(2.18)}{=} - \int_{\mathbb{R}} \mathbf{a}'_0 \cdot \mathbf{v}_0 \, dy = \int_{\mathbb{R}} \mathbf{a}_0 \cdot \mathbf{v}'_0 \, dy, \end{aligned}$$

where “ \rightarrow ” uses the strong convergence (2.17). Thus, Minty's trick gives $\mathbf{a}_0 = \mathcal{B}(\mathbf{v}'_0) = \mathbf{A}(\tilde{\mathbf{u}}_{\pm} + \mathbf{v}'_0) - \mathbf{b}$ and (2.11) and (2.1) are established.

The uniqueness of \mathbf{v}_0 again follows by strict monotonicity, see (2.13) with $a_{10} = 0$.

Step 6. Two relations: Using the fast decay of $\mathbf{U} - \tilde{\mathbf{u}}_{\pm}$ arising from $\delta > 0$ we can evaluate the indefinite integrals as follows:

$$\begin{aligned} 0 &= 2\mathbf{A}(\mathbf{U}(y))' \Big|_{-\infty}^{\infty} = \int_{\mathbb{R}} 2(\mathbf{A} \circ \mathbf{U})'' \, dy = - \int_{-\infty}^0 y \mathbf{U}' \, dy + \int_0^{\infty} y \mathbf{U}' \, dy \\ &= [y(\mathbf{U} - \mathbf{U}_-)]_{-\infty}^0 - \int_{-\infty}^0 (\mathbf{U} - \mathbf{U}_-) \, dy + [y(\mathbf{U} - \mathbf{U}_+)]_0^{\infty} - \int_0^{\infty} (\mathbf{U} - \mathbf{U}_+) \, dy \\ &= - \int_{\mathbb{R}} (\mathbf{U}(y) - \bar{\mathbf{u}}_{\pm}(y)) \, dy, \end{aligned}$$

which is the first relation in (2.9). Similarly, we obtain

$$\begin{aligned} \mathbf{A}(\mathbf{U}_+) - \mathbf{A}(\mathbf{U}_-) &= \int_{\mathbb{R}} (\mathbf{A} \circ \mathbf{U})' \, dy = \\ &= [y(\mathbf{A} \circ \mathbf{U})']_{-\infty}^0 - \int_{-\infty}^0 y(\mathbf{A} \circ \mathbf{U})'' \, dy + [y(\mathbf{A} \circ \mathbf{U})']_0^{\infty} - \int_0^{\infty} y(\mathbf{A} \circ \mathbf{U})'' \, dy = \int_{\mathbb{R}} \frac{y^2}{2} \mathbf{U}'(y) \, dy \\ &= [\frac{y^2}{2}(\mathbf{U} - \mathbf{U}_-)]_{-\infty}^0 - \int_{-\infty}^0 y(\mathbf{U} - \mathbf{U}_-) \, dy + [\frac{y^2}{2}(\mathbf{U} - \mathbf{U}_+)]_0^{\infty} - \int_0^{\infty} y(\mathbf{U} - \mathbf{U}_+) \, dy \\ &= - \int_{\mathbb{R}} y(\mathbf{U}(y) - \bar{\mathbf{u}}_{\pm}(y)) \, dy, \end{aligned}$$

which is the second relation in (2.9).

Step 7. Further regularity: We know $\mathbf{v} \in H^1 := H^1(\mathbb{R}, \mathbb{R}^m)$, which implies $\mathbf{U} \in L^2_{\text{loc}}$. From the weak equation (2.1b) we conclude that $\mathbf{H} : y \mapsto \mathbf{A}(\mathbf{U}(y))$ lies in H^1_{loc} by applying the Lemma of du Bois-Reymond. Thus, the invertibility of $D\mathbf{A}(\mathbf{U})$ allows to apply the implicit function theorem giving $\mathbf{U} \in H^1_{\text{loc}}$.

If \mathbf{A} satisfies the further smoothness (2.10), then we obtain higher regularity of \mathbf{U} by the classical bootstrap argument applied to the equation $(D\mathbf{A}(\mathbf{U})\mathbf{U}')' = -\frac{y}{2}\mathbf{U}'$. ■

It is interesting to compare the approximation $\mathbf{A}_{\varepsilon}(\mathbf{u}) = \mathbf{A}(\mathbf{u}) + \varepsilon\mathbf{u}$ in Step 5 of this proof with the linear approximation $\mathbb{A}_{\varepsilon} = \mathbb{A} + \varepsilon\mathbb{I}$ in Example 2.1, where the solutions are given explicitly. Hence one can see that the approximation is needed for smoothness and exponential decay of the flux.

While (2.7) provides an a priori estimate for $\mathbf{U} - \tilde{\mathbf{u}}_{\pm}$ in $L^2(\mathbb{R}; \mathbb{R}^m)$, we now show that in the case $a_{10} > 0$ one can also obtain a uniform bound, which will be useful in Section 5.5.

Corollary 2.3 (Uniform bound on $U - \tilde{u}_\pm$) Assume the conditions (2.6) with $\delta, a_{10} > 0$, then the unique solution $U : \mathbb{R} \rightarrow \mathbb{R}^m$ obtained in Theorem 2.2 satisfies

$$|U(y) - \tilde{u}_\pm(y)| \leq C_\chi \frac{a_{\text{up}}^{1/2}}{\delta^{1/2} a_{10}} \Delta_\pm \quad \text{for all } y \in \mathbb{R}, \quad \text{where } \Delta_\pm = |U_+ - U_-|. \quad (2.19)$$

Proof. We set $\mathbb{A}(y) = D\mathbf{A}(U(y))$ and observe that (2.6b) implies $\langle \mathbb{A}\mathbf{v}, \mathbf{v} \rangle \geq a_{10}|\mathbf{v}|^2$. Inserting $\mathbf{v} = \mathbb{A}^{-1}\mathbf{w}$ we obtain $|\mathbb{A}^{-1}\mathbf{w}| \leq |\mathbf{w}|/a_{10}$. Now exploiting the flux estimate (2.8) yields

$$|U'(y)| = |D\mathbf{A}(U(y))^{-1}\mathbf{q}(y)| \leq \frac{1}{a_{10}} C_\chi a_{\text{up}}^{1/2} e^{-\delta y^2/4} \Delta_\pm \quad \text{for all } y \in \mathbb{R}.$$

Using $U(y) - \bar{u}_\pm(y) = \int_{-\infty}^y U'(z) dz$ for $y < 0$ and $U(y) - \bar{u}_\pm(y) = -\int_y^\infty U'(z) dz$ for $y > 0$, we obtain the desired estimate (2.19) if we take into account $|\tilde{u}_\pm(y) - \bar{u}_\pm(y)| \leq \Delta_\pm$. ■

We conclude this section on existence and uniqueness of similarity profiles U solving the weak form (2.1) of the profile equation (1.3) with the important remark, that our result provides existence also in the degenerate case with $a_{10} = 0$. While for $a_{10} > 0$ the solutions are automatically smooth, see the statement after (2.10) in Theorem 2.2, the case allows for discontinuous solutions U or for continuous solutions where U' has singularities. The latter case will be important in the scalar situation discussed in the following section.

3 The case of scalar profiles

We now restrict to the scalar case and consider the problem

$$(\mathbb{D}(U)U')' + \frac{y}{2}U' = 0 \quad \text{for } y \in \mathbb{R}, \quad U(\pm\infty) = U_\pm, \quad (3.1)$$

where we always assume that $\mathbb{D} : \mathbb{R} \rightarrow \mathbb{R}$ is continuous and nonnegative. We observe that $A(u) = \int_0^u \mathbb{D}(s) ds$ is monotone and C^1 with $A'(u) = \mathbb{D}(u)$. We have strict monotonicity if \mathbb{D} has only isolated zeros. The global conditions (2.6) are satisfied with

$$a_{\text{up}} = \sup_{u \in \mathbb{R}} \mathbb{D}(u), \quad a_{10} = \inf_{u \in \mathbb{R}} \mathbb{D}(u), \quad \delta = 1/a_{\text{up}} = \inf_{u \in \mathbb{R}} \frac{1}{\mathbb{D}(u)}.$$

However, below we will show that all stationary profiles $U : \mathbb{R} \rightarrow \mathbb{R}$ are monotone, e.g. for $U_- < U_+$ the profile is nondecreasing and satisfies $U(y) \in [U_-, U_+]$ for all $y \in \mathbb{R}$. Hence, it will be sufficient to restrict the above infima and supremum to the interval $[U_-, U_+]$.

Before giving the general existence theory, we look at a few examples with degenerate diffusion, that is $a_{10} = 0$.

Example 3.1 (Degenerate profiles)

(I) As a first simple example we have

$$\mathbb{D}(u) = (1-u^2)/4 \quad \text{and} \quad u(y) = \begin{cases} U_- = -1 & \text{for } y \leq -1, \\ y & \text{for } y \in [-1, 1], \\ U_+ = 1 & \text{for } y \geq 1. \end{cases} \quad (3.2)$$

(II) A second example can be constructed by setting

$$\tilde{u}(y) = \begin{cases} U_- = -1 & \text{for } y \leq -1, \\ \frac{3}{2}y - \frac{1}{2}y^3 & \text{for } y \in [-1, 1], \\ U_+ = +1 & \text{for } y \geq 1. \end{cases}$$

By exploiting equation (3.1) for $y \in]-1, 1[$ we obtain

$$\tilde{\mathbb{D}}(u) = \frac{1}{8}(1 - \tilde{Y}(u)^2), \quad \text{where } \tilde{Y} := (\tilde{u}|_{[-1,1]})^{-1} : [-1, 1] \rightarrow [-1, 1].$$

We observe that $\tilde{\mathbb{D}}(u) = c|u \mp 1|^{1/2} + \text{h.o.t.}$ for $1 \mp u \rightarrow 0^+$.

(III) As a third example we set $\hat{Y} : [-1, 1] \rightarrow [-1, 1]; u \mapsto \frac{3}{2}u - \frac{1}{2}u^3$ and define

$$\hat{u}(y) = \begin{cases} U_- = -1 & \text{for } y \leq -1, \\ (\hat{Y}|_{[-1,1]})^{-1}(y) & \text{for } y \in [-1, 1], \\ U_+ = 1 & \text{for } y \geq 1. \end{cases}$$

A direct calculation shows that (3.1) is satisfied for $\mathbb{D}(u) = \frac{3}{16}(1-u^2)^2(5-u^2)$.

(IV) More generally, using advanced ODE techniques, one can show that for \mathbb{D} satisfying $\mathbb{D}(u) = d_0(u-U_-)^\theta$ with $\theta > 0$ that there exists $y_-^* < 0$ such that the profile U satisfies $U(y) = U_-$ for $y \leq y_-^*$ and $U(y) = c_0(y-y_-^*)^{1/\theta} + \text{h.o.t.}$ Indeed, the three cases (I) to (III) above correspond to $\theta = 1, 1/2$, and 2 , respectively.

Moreover, for $\theta > 1$ this shows that U' can only lie in $L_{\text{loc}}^p(\mathbb{R})$ for $p < \theta/(\theta-1)$, which is exactly the restriction in Theorem 3.5 below.

(V) However, if \mathbb{D} has an interior zero $U_0 \in]U_-, U_+[$ of the form $\mathbb{D}(u) = d_0|u-U_0|^\theta + \text{h.o.t.}$, then the profile U will behave like $U(y) = U_0 + c(y-y_0)^{1/(1+\theta)} + \text{h.o.t.}$ Thus, we find $U'(y) \sim |y-y_0|^{-\theta/(1+\theta)} + \text{h.o.t.}$, which is a stronger singularity than those that would occur near U_\pm .

The difference between the singularities at the boundaries $U_0 \in \{U_-, U_+\}$ and in the interior $U_0 \in]U_-, U_+[$ is explained as follows: Interior singularities occur at positive continuous flux $0 < q(y_0)$ with $q(y) = \mathbb{D}(U(y))U'(Y) \approx q(y_0)$, while at the two end points singularities occur at flux $q(U_\pm) = 0$.

To derive our subsequent a priori estimates we use the strategy implemented in Step 5 of the proof for Theorem 2.2. We will derive the estimates for the case that \mathbb{D} is bounded from below by $a_{\text{lo}} > 0$ and then we conclude that the same result holds for the case $a_{\text{lo}} = 0$ by taking the limit for $D_\varepsilon = \varepsilon + \mathbb{D}$. For $\varepsilon \in [0, 1]$ let U_ε denote the solution of (3.1) with \mathbb{D} replaced by D_ε , then we have

$$U_\varepsilon - \tilde{u}_* \rightharpoonup U_0 - \tilde{u}_* \text{ in } L^2(\mathbb{R}) \quad \text{and} \quad q_\varepsilon = D_\varepsilon(U_\varepsilon)U'_\varepsilon \rightharpoonup q_0 = \mathbb{D}(U_0)U'_0 \text{ in } H^{-1}(\mathbb{R}).$$

Our first result concerns the monotonicity of the profiles, which then will also improve the convergence by using Helly's selection principle for sequences of monotone functions.

Lemma 3.2 (Monotonicity of scalar profiles) Assume that $(U_-, U_+) \in \mathbb{R}^2$ are given with $U_- < U_+$ and that $\mathbb{D} \in C^0(\mathbb{R})$ is nonnegative. Then, the unique front U provided by Theorem 2.2 is nondecreasing and hence only depends on $\mathbb{D}|_{[U_-, U_+]}$.

Proof. We first consider the case $a_{lo} = \min \{ \mathbb{D}(u) \mid u \in \mathbb{R} \} > 0$, then the flux $q(y) = \mathbb{D}(U(y))U'(y)$ satisfies the ODE $q' + yq/(2\mathbb{D}(u)) = 0$. Hence, q cannot change its sign. Moreover, the boundary conditions impose $\int_{\mathbb{R}} q \, dy = \int_{\mathbb{R}} \mathbb{D}(U)U' \, dy = \int_{U_-}^{U_+} \mathbb{D}(u) \, du \geq \alpha(U_+ - U_-) > 0$. Hence, we find $q \geq 0$ and thus $U'(y) \geq 0$.

The general case with $a_{lo} = 0$ follows by approximation. ■

Restricting to the case $U_- < U_+$ we now define the relevant constants

$$D_* := \min \{ \mathbb{D}(u) \mid u \in [U_-, U_+] \} \quad \text{and} \quad D^* := \max \{ \mathbb{D}(u) \mid u \in [U_-, U_+] \},$$

which satisfy $a_{lo} \leq D_* < D^* \leq a_{up}$. Clearly, all estimates on the profile U will only depend on D_* and D^* . Moreover, when approximating U by U_ε as indicated above, we can use the monotonicity $U'_\varepsilon(y) \geq 0$ and employ Helly's selection principle to conclude

$$U_\varepsilon(y) \rightarrow U(y) \quad \text{at all continuity points } y \in \mathbb{R} \text{ of } U.$$

We proceed by supplying further a priori estimates that are essentially contained in [vaP77b, Thm. 5] and have their origin in [Sha76]. However, here we provide a much shorter direct proof.

Proposition 3.3 (A priori estimates) *Assume $U_- < U_+$ and that $\mathbb{D} \in C^0([U_-, U_+])$ with $D_* = \min \mathbb{D} \geq 0$ and $D^* = \max \mathbb{D}$. Then, the solution U and its associated flux $Q(y) = \mathbb{D}(U(y))U'(y)$ satisfy the estimates*

$$\begin{aligned} 0 \leq U_+ - U(y) &\leq (U_+ - U(z)) e^{-(y^2 - z^2)/(4D^*)} \quad \text{for } 0 \leq z \leq y, \\ 0 \leq U(y) - U_- &\leq (U(z) - U_-) e^{-(y^2 - z^2)/(4D^*)} \quad \text{for } 0 \geq z \geq y, \\ 0 \leq Q(\pm y) &\leq Q(\pm z) e^{-(y^2 - z^2)/(4D^*)} \quad \text{for } 0 \leq z \leq y. \end{aligned} \quad (3.3)$$

Moreover, the values $U(0) \in]U_-, U_+[$ and $Q(0) > 0$ are restricted by the inequalities

$$\begin{aligned} \int_{U_-}^{U(0)} (s - U_-) \mathbb{D}(s) \, ds &\leq 2Q(0)^2 \leq (U(0) - U_-) \int_{U_-}^{U(0)} \mathbb{D}(s) \, ds, \\ \int_{U(0)}^{U_+} (U_+ - s) \mathbb{D}(s) \, ds &\leq 2Q(0)^2 \leq (U_+ - U(0)) \int_{U(0)}^{U_+} \mathbb{D}(s) \, ds. \end{aligned} \quad (3.4)$$

Proof. Again we may use $D_* \geq a_{lo} > 0$ for deriving the following estimates.

We first show the last estimate in (3.3). For this we observe

$$Q'(y) = -\frac{y}{2} U'(y) = \frac{-y}{2\mathbb{D}(U(y))} Q(y),$$

which gives the relation $Q(y) = \Psi_z(y)Q(z)$ with $\Psi_z(y) = \exp\left(\int_z^y \frac{-\eta}{2\mathbb{D}(U(\eta))} d\eta\right)$. Using $\mathbb{D}(u) \leq D^*$ gives the third estimate in (3.3).

From this bound for $Q = \mathbb{D}(U)U'$ and the lower bound $\mathbb{D} \geq D_* > 0$ we now deduce that U converges faster than exponential to its limits U_\pm for $y \rightarrow \pm\infty$. For $y \geq 0$ we set $w(y) = U_+ - U(y)$, and by integrating (3.1) over $y \in]z, \infty[$ we obtain

$$\mathbb{D}(U(z))w'(z) = -\frac{z}{2}w(z) - \beta(z) \quad \text{with } \beta(z) = \frac{1}{2} \int_z^\infty w(y) \, dy \geq 0.$$

For $0 \leq z \leq y$ Duhamel's formula gives

$$U_+ - U(y) = w(y) = \Psi_z(y)w(z) - \int_z^y \Psi_\eta(y) \frac{\beta(\eta)}{\mathbb{D}(U(\eta))} d\eta$$

$$\stackrel{\beta \geq 0}{\leq} \Psi_z(y)w(z) \leq e^{-(y^2-z^2)/(4D^*)} (U_+ - U(0)).$$

Together with the analogous result for $y \leq 0$ the estimates in (3.3) are established.

For (3.4) it suffices to show the second line by integration over $y \geq 0$. The first line follows similarly by integration over $y \leq 0$. For the upper estimate we proceed as follows:

$$4Q(0)^2 = \left(\int_0^\infty 2Q'(y) dy \right)^2 \stackrel{(3.1)}{=} \left(\int_0^\infty y U'(y) dy \right)^2$$

$$\stackrel{\text{CS}}{\leq} \int_0^\infty U'(y) dy \int_0^\infty y^2 U'(y) dy = (U_+ - U(0)) \int_0^\infty -2yQ'(y) dy$$

$$= (U_+ - U(0)) \left[-2yQ(y) \Big|_0^\infty + \int_0^\infty 2Q(y) dy \right] = (U_+ - U(0)) \int_0^\infty 2\mathbb{D}(U(y))U'(y) dy$$

$$= 2(U_+ - U(0)) \int_{U(0)}^{U_+} \mathbb{D}(s) ds,$$

where we used the monotonicity $U'(y) \geq 0$. This is the desired upper estimate for $Q(0)^2$.

For the lower estimate we proceed as follows:

$$\int_{U(0)}^{U_+} (U_+ - s)\mathbb{D}(s) ds = \int_{U(0)}^{U_+} \int_{U(0)}^u \mathbb{D}(s) ds du = \int_{y=0}^\infty \int_{U(0)}^{U(y)} \mathbb{D}(s) ds U'(y) dy$$

$$= \int_{y=0}^\infty \int_{z=0}^y \mathbb{D}(U(z))U'(z) dz U'(y) dy = \int_{y=0}^\infty \int_{z=0}^y Q(z) dz U'(y) dy$$

$$\stackrel{**}{\leq} \int_{y=0}^\infty y Q(0) U'(y) dy \stackrel{(3.1)}{=} Q(0) \int_0^\infty -2Q'(y) dy = 2Q(0)^2,$$

where in $\stackrel{**}{\leq}$ we used $Q(z) \leq Q(0)$ from (3.3). Hence, Proposition 3.3 is established. \blacksquare

As a simple consequence of (3.4) we see that $Q(0) > 0$ and $U(0) \in]U_-, U_+[$ as soon as $\mathbb{D} \in C^0([U_-, U_+])$ is nontrivial. In the case of constant \mathbb{D} we have $D_* = D^*$ and the explicit linear solution gives $U(0) = \frac{1}{2}(U_- + U_+)$ and $Q(0) = \sqrt{D_*/(4\pi)}(U_+ - U_-)$. Moreover, we obtain upper and lower bounds for $Q(0)$ and $U(0)$ in the case $D_* > 0$. These results are valuable if D_*/D^* is close to 1 but deteriorate for $D_*/D^* \approx 0$.

Corollary 3.4 (Simple bounds on $Q(0)$ and $U(0)$) Assume $D^* \geq \mathbb{D}(u) \geq D_* > 0$ for all $u \in [U_-, U_+]$ and set $\gamma = \sqrt{D_*/(2D^*)} \leq \sqrt{1/2}$. Then, the unique profile U with $U(\pm\infty) = U_\pm$ satisfies

$$U(0) \in \left[\frac{U_- + \gamma U_+}{1 + \gamma}, \frac{\gamma U_- + U_+}{1 + \gamma} \right] \quad \text{and} \quad Q(0) \in \left[\sqrt{D_*/16}(U_+ - U_-), \sqrt{D^*/8}(U_+ - U_-) \right].$$

In particular, we have $0 \leq U'(y) \leq (U_+ - U_-)\sqrt{D^*/(8D_*^2)}$.

Proof. We simply insert the upper and lower bound for \mathbb{D} into (3.4) and find

$$\begin{aligned} \frac{1}{2}(U(0)-U_-)^2 D_* &\leq 2Q(0)^2 \leq (U(0)-U_-)^2 D^* \quad \text{and} \\ \frac{1}{2}(U_+-U(0))^2 D_* &\leq 2Q(0)^2 \leq (U_+-U(0))^2 D^*. \end{aligned}$$

From this the first two estimates follow easily.

The derivative satisfies $U'(y) = Q(y)/\mathbb{D}(U(y)) \leq Q(0)/D_*$ giving the result. \blacksquare

With this information we can pass to the limit and obtain the following existence result. The conditions for deriving $U' \in L^p(\mathbb{R})$ are indeed sharp (but leaving the critical cases open), as can be seen by comparing with the cases (IV) and (V) in Example 3.1.

Theorem 3.5 (Self-similar fronts in the degenerate case) *Assume $U_- < U_+$ and that $\mathbb{D} \in C^0([U_-, U_+])$ satisfies*

$$\exists \theta \in]0, 1[, p \in [1, \infty[: \quad \tilde{C}_{p,\theta} := \int_{U_-}^{U_+} \left(\frac{(U_+-u)^\theta (u-U_-)^\theta}{\mathbb{D}(u)} \right)^{p-1} du < \infty. \quad (3.5)$$

Then, the unique and monotone solution U of (3.1) satisfies $U' \in L^p(\mathbb{R})$, namely

$$\|U'\|_{L^p(\mathbb{R})}^p \leq \hat{C}_\theta^{p-1} \tilde{C}_{p,\theta} \quad \text{with } \hat{C}_\theta := \sqrt{\frac{2D^*}{1-\theta}} \frac{U_+ - U_-}{(U_+-U(0))^\theta (U(0)-U_-)^\theta}. \quad (3.6)$$

Moreover, if $\int_{U(0)}^{U_+} \mathbb{D}(s)/(U_+-s) ds < \infty$, then we have

$$U(y) = U_+ \quad \text{for } y \geq y_+^* := \frac{U_+-U(0)}{Q(0)} \int_{U(0)}^{U_+} \frac{\mathbb{D}(u)}{U_+-u} du > 0, \quad (3.7)$$

and an analogous statement holds for $y \leq y_-^ := -\frac{U(0)-U_-}{Q(0)} \int_{U_-}^{U(0)} \frac{\mathbb{D}(u)}{u-U_-} du < 0$.*

Proof. We again assume $\mathbb{D}(U) \geq D_* > 0$ such that U is smooth.

Step 1. Bound for Q in terms of $\min\{U-U_-, U_+-U\}$: We first show that for all $\theta \in [0, 1[$ there exists C_θ such that

$$\forall y \in \mathbb{R} : \quad Q(y) \leq \sqrt{\frac{2D^*}{1-\theta}} \left(\frac{(U_+-U(y))(U(y)-U_-)}{(U_+-U(0))(U(0)-U_-)} \right)^\theta (U_+ - U_-). \quad (3.8)$$

It is sufficient to estimate $Q(y)$ by $(U_+-U(y))^\theta$ for $y \geq 0$ and by $(U(y)-U_-)^\theta$ for $y \leq 0$. We concentrate on $y > 0$, the case $y < 0$ is similar. From $2Q' = -yU'$ we obtain

$$2Q(y) = - \int_y^\infty 2Q'(z) dz = \int_y^\infty z(U'(z)-U_+) dz = y(U_+-U(y)) + \int_y^\infty (U_+-U(z)) dz.$$

Using the first estimate in (3.3), the last term can be estimated via

$$\begin{aligned} \int_y^\infty (U_+-U(z)) dz &\leq (U_+-U(y)) \int_y^\infty e^{-(z^2-y^2)/(4D^*)} dz \\ &\leq (U_+-U(y)) \int_y^\infty e^{-(z-y)^2/(4D^*)} dz = (U_+-U(y)) \sqrt{D^*/\pi}. \end{aligned}$$

Applying the first estimate in (3.3) once again we find

$$Q(y) \leq \frac{1}{2}(y + \sqrt{\pi D^*})(U_+ - U(y)) \leq \sqrt{\frac{2D^*}{1-\theta}}(U_+ - U(y))^\theta (U_+ - U(0))^{1-\theta},$$

where for $y \geq 0$ we estimated $\frac{1}{2}(y + \sqrt{\pi D^*}) e^{-(1-\theta)y^2/(4D^*)} \leq ((2e(1-\theta))^{-1/2} + \sqrt{\pi/4}) \sqrt{D^*} \leq \sqrt{2D^*/(1-\theta)}$. Moreover, monotonicity gives $U(y) \in [U(0), U_+]$ and we conclude

$$(U_+ - U(y))^\theta (U_+ - U(0))^{1-\theta} \leq \left(\frac{(U_+ - U(y))(U(y) - U_-)}{(U_+ - U(0))(U(0) - U_-)} \right)^\theta (U_+ - U_-).$$

Thus, (3.8) is shown for $y \geq 0$ and the result for $y \leq 0$ follows analogously.

Step 2. L^p estimate for U' : We abbreviate $\delta(y) = \mathbb{D}(U(y))$ and $\mu(u) = (U_+ - u)(u - U_-)$. Recalling $Q = \delta U'$ and writing estimate (3.8) as $\delta U' \leq C_* \mu(U(y))^\theta$ we obtain

$$\int_{\mathbb{R}} (U')^p dy = \int_{\mathbb{R}} \left(\frac{\delta(y)U'(y)}{\mu(U(y))^\theta} \right)^{p-1} \left(\frac{\mu(U(y))^\theta}{\delta(y)} \right)^{p-1} U'(y) dy \leq C_*^{p-1} \int_{U_-}^{U_+} \left(\frac{\mu(u)^\theta}{\mathbb{D}(u)} \right)^{p-1} du < \infty,$$

which is the desired estimate (3.6).

Step 3: Constant values for $y \geq y_+^*$. To show (3.7) consider $y > 0$ such that $U'(z) > 0$ for $z \in [0, y]$. For this, note that U' is continuous on the set $]Y_-, Y_+[$ which is defined by the condition $U(y) \in]U_-, U_+[$. On $[0, Y_+[$ we define the auxiliary functions

$$w(y) = U_+ - U(y) > 0 \quad \text{and} \quad h(y) = \frac{2\mathbb{D}(U(y))U'(y)}{U_+ - U(y)} = \frac{2Q(y)}{w(y)} = y + \frac{1}{w(y)} \int_y^\infty w(z) dz,$$

where the last identity results from integrating (3.1) over $z \in [y, \infty[$. We easily find $h'(y) = -w'(y) \int_y^\infty w dz / w(y)^2 > 0$ because of $U' = -w' > 0$ and conclude $h(y) \geq h(0)$ for all $y \in [0, Y_+[$. With this and $U' > 0$ we obtain

$$y = \int_0^y dz = \int_0^y \frac{2}{h(z)} \frac{\mathbb{D}(U(z))}{U_+ - U(z)} U'(z) dz \leq \frac{2}{h(0)} \int_0^y \frac{\mathbb{D}(U(z))}{U_+ - U(z)} U'(z) dz = \frac{2}{h(0)} \int_{U(0)}^{U(y)} \frac{\mathbb{D}(u)}{U_+ - u} du.$$

In the limit $y \rightarrow Y_+ - 0$ we find $U(y) \rightarrow U_+$ and conclude $Y_+ \leq y_+^*$ after inserting $h(0) = 2Q(0)/w(0)$. The estimate $y_-^* \leq Y_-$ is shown analogously. ■

4 Stability of profiles in the scalar case

The porous medium equation (see e.g. [Váz07]) is given by $u_t = \Delta A(u)$, where one is typically interested in nonnegative solutions and A is defined only for $u \geq 0$. The classical choice, which we will also consider below, is given by $A(u) = u^m$ for $m > 0$.

The one-dimensional case in parabolic scaling is given in the form

$$u_\tau = (A(u))_{yy} + \frac{y}{2}u_y = (\mathbb{D}(u)u_y)_y + \frac{y}{2}u_y, \quad u(\tau, \pm\infty) = U_\pm. \quad (4.1)$$

Applying the theory of Section 3 with $\mathbb{D}(u) = mu^{m-1}$, we can treat the case $m \geq 1$ and obtain for all $0 \leq U_- \leq U_+ < \infty$ a unique monotone profile $U : \mathbb{R} \rightarrow [U_-, U_+]$ satisfying (3.1). For $m = 1$ we obtain the trivial solution (2.3) in terms of the error function. For $m > 1$ there are two

cases, namely (i) $U_- > 0$, which implies that $U \in C^\infty(\mathbb{R}; [U_-, U_+])$, and (ii) $U_- = 0$. In the latter case we have $\int_0^u \mathbb{D}(s)/s \, ds = m \int_0^u s^{m-2} \, ds = \frac{m}{m-1} u^{m-1} < \infty$ which implies $U(y) = 0$ for all $y \leq y_-^* = Y(m, U_+) < 0$, see (3.7). It can be shown that $U \in C^{1/(m-1)}(\mathbb{R}; [0, U_+])$ for $m > 1$ and $m \neq 1 + 1/k$ for $k \in \mathbb{N}$; for $m = 1 + 1/k$ one obtains $U \in C^{k-1, \text{lip}}(\mathbb{R})$. Note that (3.6) in Theorem 3.5 implies $U' \in L^\infty(\mathbb{R})$ for $m \in]1, 2[$ and $U' \in L^{(m-1)/(m-2)}(\mathbb{R})$ for $m > 2$.

Having the self-similar profile U satisfying $A(U)_{yy} + \frac{y}{2}U_y = 0$ and $U(\pm\infty) = U_\pm > 0$ we can also establish convergence of general solutions u of (4.1), at least in some cases. We also refer to [vaP77a] for convergence results to self-similar profiles, but they are quite different and rely on comparison principle arguments, whereas we use entropy estimates that may also be extended to vector-valued cases, see [MHM15, MiM18, MiS23]. For this we introduce the relative entropy

$$\mathcal{H}_\phi(u) = \int_{\mathbb{R}} \phi(u(y)/U(y))U(y) \, dy, \quad \text{where } \phi''(\rho) > 0, \phi(1) = \phi'(1) = 0.$$

Typical entropy functions are given by the family $E_p : [0, \infty[\rightarrow [0, \infty]$ via

$$E_p(\rho) = \frac{1}{(p-1)p} (\rho^p - p\rho + p - 1) \quad \text{for } p \in \mathbb{R} \setminus \{0, 1\},$$

$$E_1(\rho) := \rho \log \rho - \rho + 1, \quad E_0(\rho) = -\log \rho + \rho - 1,$$

which is uniquely determined by the conditions $E_p''(\rho) = \rho^{p-2}$ for $\rho > 0$ and $E_p(1) = E_p'(1) = 0$. Our entropy functions will be of the form

$$\varphi_{p,q}(\rho) = \begin{cases} E_p(\rho) & \text{for } \rho \in [0, 1], \\ E_q(\rho) & \text{for } \rho \geq 1, \end{cases} \quad (4.2)$$

with suitable p and q .

Because of the multiplicative ansatz $u = \rho U$ and $\phi(\rho) > 0$ for $\rho \neq 1$ in the definition of \mathcal{H} , the condition $\mathcal{H}_\phi(u) < \infty$ implies that u has to approach the same limits as U . Moreover, $\mathcal{H}_\phi(u(\tau)) \rightarrow 0$ for $\tau \rightarrow \infty$ implies $u(\tau) \rightarrow U$ in a suitable sense, see below.

A direct calculation, using the shorthand $\rho = u/U$, gives

$$\begin{aligned} \frac{d}{d\tau} \mathcal{H}_\phi(u(\tau)) &= \int_{\mathbb{R}} \phi'(\rho) \rho_\tau U \, dy = \int_{\mathbb{R}} \phi'(\rho) (A(\rho U)_{yy} + \frac{y}{2}(\rho U)_y) \, dy \\ &= \int_{\mathbb{R}} \left(-\phi'(\rho)_y A(\rho U)_y + \rho_y \phi'(\rho) \frac{y}{2} U + \rho \phi'(\rho) \frac{y}{2} U_y \right) \, dy \\ &\stackrel{*}{=} \int_{\mathbb{R}} \left(-\phi''(\rho) \rho_y A'(\rho U) (\rho U)_y - \phi(\rho) \frac{1}{2} U + (\phi(\rho) - \rho \phi'(\rho)) A(U)_{yy} \right) \, dy, \end{aligned}$$

where we have used the profile equation to substitute $\frac{y}{2}U_y$ by $-A(U)_{yy}$. Integrating the last term by parts, we arrive at the identity

$$\frac{d}{d\tau} \mathcal{H}_\phi(u(\tau)) = -\frac{1}{2} \mathcal{H}_\phi(u) - \int_{\mathbb{R}} \phi''(\rho) \left(A'(\rho U) U \rho_y^2 + \rho (A'(\rho U) - A'(U)) \rho_y U_y \right) \, dy.$$

We can estimate the last term by minimizing the integrand with respect to ρ_y pointwise and obtain

$$\frac{d}{d\tau} \mathcal{H}_\phi(u(\tau)) \leq -\frac{1}{2} \mathcal{H}_\phi(u) + \int_{\mathbb{R}} \phi''(\rho) \frac{\rho^2 U_y^2 (A'(\rho U) - A'(U))^2}{4A'(\rho U)U} \, dy. \quad (4.3)$$

In the linear case $A(u) = \delta u$ the last term vanishes and $\mathcal{H}_\phi(u(\tau)) \leq e^{-\tau/2} \mathcal{H}_\phi(u(0))$ follows immediately. For general A , one can prove exponential convergence if it is possible to estimate the last term by $\varkappa \mathcal{H}_\phi(u) = \varkappa \int_{\mathbb{R}} \phi(\rho) U \, dy$ for some $\varkappa < 1/2$.

Before we consider the important special case $A(u) = u^m$ further down below, we consider the case where $u \mapsto A'(u)$ is globally Lipschitz continuous, namely

$$\exists a_{10} > 0, C_A > 0 \forall u, v \geq 0: \quad A'(u) \geq a_{10} \quad \text{and} \quad |A'(u) - A'(v)| \leq C_A |u - v|, \quad (4.4)$$

and derive an exponential decay estimate. Under a suitable flatness condition on U we obtain a uniform exponential decay on \mathcal{H}_ϕ for all initial conditions.

Theorem 4.1 (Exponential decay if $|A''(u)| \leq C_A$) Consider the diffusion equation (4.1) with general $A \in C^2(\mathbb{R})$ satisfying assumption (4.4) and choose $\phi = \varphi_{1/2, -1}$. Assume further that the stationary profile $U \in C^1(\mathbb{R}; [U_-, U_+])$ from (3.1) satisfies

$$U_+ \geq U_- > 0 \quad \text{and} \quad \Sigma_{U,0} := \sup \{ U'(y)^2 \mid y \in \mathbb{R} \} < a_{10}/C_A^2.$$

Then, all solutions u of (4.1) with $u(0, y) \geq 0$ and $\mathcal{H}_\phi(u(0)) < \infty$ satisfy the exponential decay estimates

$$\begin{aligned} \mathcal{H}_\phi(u(\tau)) &:= \int_{\mathbb{R}} \varphi_{1/2, -1}(u(\tau, y)/U(y)) U(y) \, dy \leq e^{-\Lambda} \mathcal{H}_\phi(u(0)) \quad \text{for all } \tau > 0, \\ \|\sqrt{u(\tau, \cdot)} - \sqrt{U(\cdot)}\|_{L^2(\mathbb{R})}^2 &\leq e^{-\Lambda\tau} \mathcal{H}_\phi(u(0)) \quad \text{for all } \tau > 0, \end{aligned}$$

where $\Lambda = \frac{1}{2} \left(1 - C_A^2 \Sigma_{U,0}/a_{10}\right)$.

Proof. We first observe that the choice $\phi = \varphi_{1/2, -1}$ leads to the estimate

$$\phi''(\rho) \rho^2 (\rho - 1)^2 \leq 2\phi(\rho) \quad \text{for all } \rho \geq 0,$$

see Figure 4.1. Using this and (4.4), the estimate (4.3) takes the form

$$\frac{d}{d\tau} \mathcal{H}_\phi(u) = -\frac{1}{2} \mathcal{H}_\phi(u) + \int_{\mathbb{R}} 2\phi(\rho) \frac{U'(y)^2 C_A^2 U(y)^2}{4 a_{10} U(y)} \, dy \leq -\frac{1}{2} \left(1 - \frac{C_A^2}{a_{10}} \Sigma_{U,0}\right) \mathcal{H}_\phi(u).$$

This proves the first decay estimate, and the second follows by using

$$(\sqrt{u} - \sqrt{U})^2 = (\sqrt{\rho} - 1)^2 U = \frac{1}{2} E_{1/2}(\rho) U \leq \varphi_{1/2, -1}(\rho) U.$$

Integration over $y \in \mathbb{R}$ completes the proof. ■

As a second example we restrict to the case $A(u) = u^m$, which leads to a strong simplification because the integrand in the last term in (4.3) can be factored in the form $\phi''(\rho) B_m(\rho) U_y^2 U^{m-2}$ for some B_m . Proceeding as for the last result we find the following decay estimates.

Theorem 4.2 (Convergence in the PME $A(u) = u^m$) Consider the porous medium equation (4.1) with $A(u) = u^m$ for $m \geq 1$ and let $U \in C^0(\mathbb{R}; [U_-, U_+])$ denote the similarity profile satisfying (3.1) and

$$U_+ \geq U_- > 0 \quad \text{and} \quad \Sigma_{U,m} = \sup \{ U'(y)^2 U(y)^{m-2} \mid y \in \mathbb{R} \} < \frac{1}{m(m-1)^2}. \quad (4.5)$$

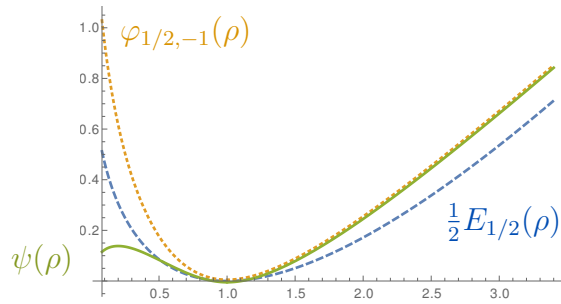


Figure 4.1: The function $\psi(\rho) = \frac{1}{2}\phi''(\rho)\rho^2(\rho-1)^2$ (full line, green) is less or equal to $\phi = \varphi_{1/2,-1}$ (dotted orange). Moreover, $\varphi_{1/2,-1}$ lies above $\frac{1}{2}E_{1/2}(\rho) = (\sqrt{\rho} - 1)^2$ (dashed, blue).

Then, choosing the entropy density function

$$\phi_m := \varphi_{p_m, q_m} \quad \text{with } p_m = \max\{1/2, m-1\} \text{ and } q_m = \min\{1/2, 2-m\},$$

all solutions of (4.1) with $u(0, y) \geq 0$ satisfy the global decay estimates

$$\begin{aligned} \mathcal{H}_{\phi_m}(u(\tau)) &\leq e^{-\Lambda\tau} \mathcal{H}_{\phi_m}(u(0)) \quad \text{for all } \tau > 0, \\ \|\sqrt{u(\tau, \cdot)} - \sqrt{U(\cdot)}\|_{L^2(\mathbb{R})}^2 &\leq e^{-\Lambda\tau} \widehat{C}_m \mathcal{H}_{\phi}(u(0)) \quad \text{for all } \tau > 0, \end{aligned}$$

where $\Lambda = \frac{1}{2}(1 - m(m-1)^2 \Sigma_{U,m})$ and $\widehat{C}_m := \sup \{ (\sqrt{r} - 1)^2 / \phi_m(r) \mid 0 < r \neq 1 \} < \infty$.

Proof. We proceed exactly as in the previous proof. The choice $\phi_m = \varphi_{p_m, q_m}$ yields

$$\phi_m''(\rho) \frac{m(\rho^{m-1} - 1)^2}{4\rho^{m-3}} \leq \frac{m(m-1)^2}{2} \phi_m(\rho).$$

With this and the definition of $\Sigma_{U,m}$, we arrive at

$$\frac{d}{d\tau} \mathcal{H}_{\phi_m}(u(\tau)) \leq -\frac{1}{2} \mathcal{H}_{\phi}(u) + \int_{\mathbb{R}} \frac{m(m-1)^2}{2} \phi_m(\rho) \Sigma_{U,m} U(y) dy = -\Lambda \mathcal{H}_{\phi_m}(u(\tau)).$$

This proves the first estimate, and the second follows by the definition of \widehat{C}_m . ■

Next we show that the second condition on U imposed in (4.5) can be controlled by the estimates obtained in Section 3. With $Q = A'(U)U' = mU^{m-1}U'$ we have

$$\Sigma_{U,m} = \sup_{y \in \mathbb{R}} (U')^2 U^{m-2} = \sup_{y \in \mathbb{R}} \frac{Q^2}{m^2 U^m} \leq \frac{D^*(U_+ - U_-)^2 / 8}{m^2 U_-^m} \leq \frac{U_+^{m-1}}{8m U_-^m} (U_+ - U_-)^2,$$

where we used the monotonicity $U_- \leq U(y) \leq U_+$ from Lemma 3.2 and the flux estimates $Q(y) \leq Q(0)$ and $Q(0)^2 \leq D^*(U_+ - U_-)^2 / 8$ from Proposition 3.3 and Corollary 3.4, respectively. In particular, we see that for the linear case $m = 1$ there is no restriction at all, whereas for $m > 1$ there is always a range of $0 < U_- < U_+$ that is allowed including the constant case arising from $U_+ = U_- > 0$.

We now return to the general case of a monotone relation $u \mapsto A(u)$ and observe that the integral relations (2.9) for the similarity profiles U obtained in Theorem 2.2 lead to simple relations for all solutions u of the diffusion equation (4.1), namely

$$\begin{aligned} \frac{d}{d\tau} \int_{\mathbb{R}} (u(\tau, y) - \bar{u}_{\pm}(y)) dy &= -\frac{1}{2} \int_{\mathbb{R}} (u(\tau, y) - \bar{u}_{\pm}(y)) dy, \\ \frac{d}{d\tau} \int_{\mathbb{R}} y(u(\tau, y) - \bar{u}_{\pm}(y)) dy &= A(U_+) - A(U_-) - \int_{\mathbb{R}} y(u(\tau, y) - \bar{u}_{\pm}(y)) dy. \end{aligned}$$

Moreover, the linearization of the diffusion equation (4.1) around $u = U$ leads to the equation

$$v_\tau = \mathbb{L}_U v := (A'(U)v)'' + \frac{y}{2}v', \quad v(\pm\infty) = 0.$$

It can be easily checked that the linear operator \mathbb{L}_U has the eigenvalues $\lambda_1 = -\frac{1}{2}$ and $\lambda_2 = -1$ with the corresponding eigenfunctions $V_1(y) = U'(y)$ and $V_2(y) = yU'(y)$, namely

$$\mathbb{L}_U U' = -\frac{1}{2}U' \quad \text{and} \quad \mathbb{L}_U(yU') = -yU'.$$

Finally, the adjoint operator \mathbb{L}_U^* is given via $\mathbb{L}_U^* w = A'(U)w'' - (\frac{y}{2}w)'$ and has the corresponding eigenfunctions $W_1(y) = 1$ and $W_2(y) = y$.

Based on this, we conjecture that the global stability obtained in Theorem 4.2 can be improved via a local stability analysis. Without loss of generality we can assume that the initial condition $u(0, \cdot)$ satisfies

$$\int_{\mathbb{R}} (u(0, y) - \bar{u}_\pm(y)) dy = 0 \quad \text{and} \quad \int_{\mathbb{R}} y(u(0, y) - \bar{u}_\pm(y)) dy = A(U_+) - A(U_-).$$

This can always be achieved by a suitable translation and scaling $\tilde{u}(0, y) = u(0, \mu(y - y_0))$. Then, for initial conditions $u(0)$ close to U one can expect a decay with a decay rate close to the third eigenvalue $\lambda_3 < \lambda_2 = -1$, i.e.

$$\|u(\tau) - U\|_Y \leq C e^{-(1+\delta)\tau} \|u(0) - U\|_Y \quad \text{for all } \tau > 0$$

whenever $\|u(0) - U\|_y \leq \delta \ll 1$, where Y is a suitably chosen Banach space.

Such results could then be transformed back into the physical variables $t = e^\tau - 1$ and $x = e^{\tau/2}y$ for obtaining algebraic decay, e.g. in $L^1(\mathbb{R}_x)$, see [vaP77a, Ber82] for related results in this direction.

5 Diffusion systems with reaction constraints

We consider one-dimensional RDS for nonnegative concentration vectors $\mathbf{c}(t, x) \in [0, \infty]^{i^*}$ with reaction of mass-action law satisfying the detailed-balance condition

$$\mathbf{c}_t = (\mathbb{D}(\mathbf{c})\mathbf{c}_x)_x + \mathbf{R}(\mathbf{c}) \quad \text{with} \quad \mathbf{R}(\mathbf{c}) = \sum_{r=1}^{r_*} k_r \left(\frac{\mathbf{c}^{\alpha^r}}{\mathbf{w}^{\alpha^r}} - \frac{\mathbf{c}^{\beta^r}}{\mathbf{w}^{\beta^r}} \right) (\beta^r - \alpha^r) \in \mathbb{R}^{i_*}, \quad (5.1)$$

where $\mathbf{w} = (w_i)_i \in]0, \infty]^{i_*}$ denotes the nonnegative equilibrium state. Using parabolic coordinates

$$y = x/\sqrt{t+1} \quad \text{and} \quad \tau = \log(t+1),$$

the transformed system takes the form

$$\mathbf{c}_\tau = (\mathbb{D}(\mathbf{c})\mathbf{c}_y)_y + \frac{y}{2}\mathbf{c}_y + e^\tau \mathbf{R}(\mathbf{c}), \quad (5.2)$$

where now an exponential factor occurs in front of the reaction terms because they do not scale in the same way as the parabolic terms. We leave the analysis of the model involving the growing term e^τ to the work [MiS23] and restrict here to the simpler case with full invariance.

A scaling invariant problem is obtained by setting e^τ formally to $+\infty$, i.e. we assume that the reactions \mathbf{R} are already in equilibrium, whereas the spatial diffusion is much slower and still allows for diffusive fluxes, see the constrained system (5.4) below.

5.1 The formally reduced system with reaction constraint

In the parabolic scaling the reactions must be considered very fast. In a first non-rigorous approximation we can follow the standard argument in chemical modeling and assume that for all τ and y the concentration vector $\mathbf{c}(\tau, y)$ is always in equilibrium (i.e. $\mathbf{R}(\mathbf{c}(\tau, y)) = 0$), but the equilibrium may still depend on τ and y and will equilibrate spatially by diffusion only. We refer to [Bot03, MPS21, PeR21, Ste21] for some recent works justifying the limit of infinitely fast reactions in slow-fast systems.

To describe the set of all equilibria, we assume that the dimension γ_* of the stoichiometric subspace $\Gamma := \text{span}\{\beta^r - \alpha^r \mid r = 1, \dots, r_*\}$ is less than i_* , which implies that $\mathbf{R}(\mathbf{c}) = 0$ has a nontrivial family of solutions, which contains the equilibrium \mathbf{w} . By arguments from standard linear algebra we can construct a matrix $\mathbb{Q} \in \mathbb{R}^{m_* \times i_*}$ with $m_* = i_* - \gamma_*$, such that $\Gamma = \ker \mathbb{Q}$ and $\text{range } \mathbb{Q}^\top = \Gamma^\perp$. Thus, by construction we have $\mathbb{Q}\mathbf{R}(\mathbf{c}) = 0$ for all \mathbf{c} .

We introduce the so-called slow variables via

$$\mathbf{u}(t, x) = \mathbb{Q}\mathbf{c}(t, x).$$

Following [MiS20, MPS21], the detailed-balance condition can be exploited to characterize the set of all steady states. For this we introduce

$$\mathfrak{C} := [0, \infty]^{i_*}, \quad \mathfrak{U} := \mathbb{Q}\mathfrak{C}, \quad \mathcal{E}(\mathbf{c}) := \sum_{i=1}^{i_*} w_i \lambda_B(c_i/w_i) \text{ with } \lambda_B(r) = r \log r - r + 1.$$

The following is shown in [MPS21, Sec. 3.3]:

$$\begin{aligned} \{ \mathbf{c} \in \mathfrak{C} \mid \mathbf{R}(\mathbf{c}) = 0 \} &= \text{clos}(\{ \mathbf{c} \in [0, \infty]^{i_*} \mid \exists \mu \in \mathbb{R}^{m_*}: (\log(c_i/w_i))_i = \mathbb{Q}^\top \mu \}) \\ &= \{ \mathbf{c} \in \mathfrak{C} \mid \exists \mathbf{u} \in \mathfrak{U}: \mathbf{c} \text{ minimizes } \mathcal{E} \text{ subject to } \mathbb{Q}\mathbf{c} = \mathbf{u} \}. \end{aligned}$$

Moreover, it is shown in [MPS21, Prop. 3.6] that there is a continuous map $\Psi : \mathfrak{U} \rightarrow \mathfrak{C}$ such that

$$\Psi(\mathbf{u}) = \arg \min \{ \mathcal{E}(\mathbf{c}) \mid \mathbb{Q}\mathbf{c} = \mathbf{u} \} \quad \text{and} \quad \mathbf{u} = \mathbb{Q}\Psi(\mathbf{u}).$$

The last relation is a direct consequence from the definition of Ψ .

Returning to the parabolically scaled RDS in (5.2), the exponentially growing prefactor e^τ forces the reactions to equilibrate very fast, see [GaS22] where the rate $(1+t)^{-1/2} = e^{-\tau/2}$ is established. Thus we may assume that for $\tau \gg 1$ we always have $\mathbf{c}(\tau, y) \approx \Psi(\mathbf{u}(\tau, y))$. Moreover we may apply the linear operator \mathbb{Q} to the equation and, using $\mathbf{u} = \mathbb{Q}\Psi(\mathbf{u})$ we obtain the reduces problem

$$\mathbf{u}_\tau = \left(\mathbb{Q}\mathbb{D}(\Psi(\mathbf{u})) \Psi(\mathbf{u})_y \right)_y + \frac{y}{2} \mathbf{u}_y \quad \text{for } \mathbf{u}(\tau, y) \in \mathfrak{U} \subset \mathbb{R}^{m_*}. \quad (5.3)$$

Note that the reactions have disappeared completely because of $\mathbb{Q}\mathbf{R} \equiv 0$, but we also have assumed that they are equilibrated, i.e. $\mathbf{c} = \Psi(\mathbf{u})$. In summary, we are left with a pure diffusion problem in parabolic scaling variables.

This system can equivalently be formulated in terms of the original concentration vector \mathbf{c} as follows:

$$\mathbf{c}_\tau = \left(\mathbb{D}(\mathbf{c})\mathbf{c}_y \right)_y + \frac{y}{2} \mathbf{c}_y + \boldsymbol{\lambda}, \quad \mathbb{Q}\boldsymbol{\lambda} = 0, \quad \mathbf{R}(\mathbf{c}) = 0 \quad \text{for } \tau > 0, y \in \mathbb{R}. \quad (5.4)$$

Here $\boldsymbol{\lambda} \in \Gamma$ arises via the limit $e^\tau \mathbf{R}(\mathbf{c}) \rightarrow \infty \mathbf{0}$ and is, thus, a remainder of the much faster reactions. Mathematically $\boldsymbol{\lambda} \in \Gamma$ can be understood as a Lagrange multiplier corresponding to the algebraic constraint $\mathbf{R}(\mathbf{c}) = 0$.

If \mathbb{D} is independent of \mathbf{c} , we can define $\mathbf{A}(\mathbf{u}) = \mathbb{Q}\mathbb{D}\Psi(\mathbf{u})$ and observe that steady states of (5.3) have to satisfy our profile equation

$$\mathbf{A}(\mathbf{U})'' + \frac{y}{2}\mathbf{U}' = 0 \text{ for } y \in \mathbb{R}, \quad \mathbf{U}(y) \rightarrow \mathbf{U}_{\pm} \text{ for } y \rightarrow \pm\infty.$$

If we find such a profile $\mathbf{U} : \mathbb{R} \rightarrow \mathfrak{U} \subset \mathbb{R}^{m_*}$, it gives rise to a stationary profile $\mathbf{C} : \mathbb{R} \rightarrow \mathfrak{C} \subset \mathbb{R}^{i_*}$ via $\mathbf{C}(y) := \Psi(\mathbf{U}(y))$ which then is a steady state of the constrained diffusion system (5.4). In [MiS23] cases are discussed in which it is possible to show that all solutions $\mathbf{c}(\tau, \cdot)$ of the full scaled reaction-diffusion system (5.2) satisfying $\mathbf{c}(0, y) \rightarrow \Psi(\mathbf{U}_{\pm})$ for $y \rightarrow \pm\infty$ converge to \mathbf{C} for $\tau \rightarrow \infty$.

In this work we restrict the discussion to the existence question for the self-similar profiles $\mathbf{U} : \mathbb{R} \rightarrow \mathfrak{U} \subset \mathbb{R}^{m_*}$ and hence of $\mathbf{C} : \mathbb{R} \rightarrow \mathfrak{C} \subset \mathbb{R}^{i_*}$. The profiles \mathbf{C} provide exact self-similar solutions to the unscaled constrained system

$$\dot{\mathbf{c}} = (\mathbb{D}\mathbf{c}_x)_x + \boldsymbol{\lambda}, \quad \mathbb{Q}\boldsymbol{\lambda} = 0, \quad \mathbf{R}(\mathbf{c}) = 0 \quad \text{for } t > 0, x \in \mathbb{R}. \quad (5.5)$$

Because of the nonlinear constraint $\mathbf{R}(\mathbf{c}) = 0$, this is a quasilinear system.

In light of the analysis in [GaS22] and [MiS23], it is to be expected that the solutions of the full reaction-diffusion system (5.1) with the additional boundary conditions $\mathbf{c}(t, \pm\infty) = \Psi(\mathbf{U}_{\pm})$ behave asymptotically self-similar as well. But such results are beyond the scope of this work.

5.2 Linear reaction-diffusion systems

We consider a linear reaction-diffusion system of the form

$$\mathbf{c}_t = \mathbb{D}\mathbf{c}_{xx} + \mathbb{B}\mathbf{c} \quad \text{for } \mathbf{c}(t, x) \in \mathfrak{C} \subset \mathbb{R}^{i_*}.$$

Here $\mathbb{D} = \text{diag}(d_i)_{i=1, \dots, i_*}$ and \mathbb{B} is obtained from a detailed-balance system as in (5.1), i.e. all stoichiometric vectors $\boldsymbol{\alpha}^r$ and $\boldsymbol{\beta}^r$ are unit vectors $\{e_j \mid j = 1, \dots, i_*\}$. It is shown in [MiS20, Sec. 2] that the operator $\mathbb{Q} \in \mathbb{R}^{m_* \times i_*}$ can be constructed such that each column is a unit vector and that $\Psi(\mathbf{u}) = \mathbb{N}\mathbf{u}$ with $\mathbb{N} \in \mathbb{R}^{i_* \times m_*}$ have nonnegative entries such that each column sum equals 1. In particular, one has

$$\mathbb{Q}\mathbb{B} = 0, \quad \mathbb{Q}\mathbb{N} = I_{m_*} \in \mathbb{R}^{m_* \times m_*} \quad \text{and} \quad \mathbb{N}\mathbb{Q} \in \mathbb{R}^{i_* \times i_*} \text{ is a projection.}$$

Thus, for this special case the reduced RDS for $\mathbf{u} = \mathbb{Q}\mathbf{c}$ in scaling coordinates takes the form

$$\mathbf{u}_{\tau} = \mathbb{A}\mathbf{u}_{yy} + \frac{y}{2}\mathbf{u}_y \quad \text{with } \mathbb{A} = \mathbb{Q}\mathbb{D}\mathbb{N}.$$

If \mathbb{D} is diagonal, then it can be shown that \mathbb{A} is also diagonal, containing the effective diffusion constants for the components u_m , cf. [Ste21]. However, if \mathbb{D} is nondiagonal but still positive semidefinite, then \mathbb{A} may non longer be monotone, i.e. $\mathbb{A} + \mathbb{A}^{\top}$ is no longer positive semidefinite. For instance consider

$$\mathbb{D} = \begin{pmatrix} d_1 & \delta & 0 \\ \delta & d_2 & 0 \\ 0 & 0 & d_3 \end{pmatrix}, \quad \mathbb{Q} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \end{pmatrix}, \quad \mathbb{N} = \begin{pmatrix} 1 & 0 \\ 0 & \nu \\ 0 & 1-\nu \end{pmatrix}, \quad \mathbb{A} = \begin{pmatrix} d_1 & & \\ \delta & \nu\delta & \\ & \nu d_2 + (1-\nu)d_3 & \end{pmatrix}$$

with $d_1 = d_2 = 1$, $\delta = 1/2$, $\nu = d_3 = 1/50$. Thus, monotonicity is not obtained automatically.

5.3 Linear diffusion systems without reactions

We consider now linear systems without reactions of the form

$$\mathbf{u}_t = \mathbb{A}\mathbf{u}_{xx} \text{ for } (t, x) \in]0, \infty[\times \mathbb{R}, \quad \mathbf{u}(t, \pm\infty) = \mathbf{U}_\pm.$$

Here \mathbb{A} is a monotone matrix, i.e. $\mathbf{w} \cdot \mathbb{A}\mathbf{w} \geq a_{10}|\mathbf{w}|^2 \geq 0$. Of course, the parabolically scaled equation reads

$$\mathbf{u}_\tau = \mathbb{A}\mathbf{u}_{yy} + \frac{y}{2}\mathbf{u}_y \text{ for } (t, y) \in]0, \infty[\times \mathbb{R}, \quad \mathbf{u}(t, \pm\infty) = \mathbf{U}_\pm. \quad (5.6)$$

As explained in Example 2.1, there is always a unique similarity profile \mathbf{U} for any pair $(\mathbf{U}_-, \mathbf{U}_+) \in \mathbb{R}^m \times \mathbb{R}^m$.

By classical energy estimates using the monotonicity of \mathbb{A} one obtains convergence towards the stationary profile by linearity. If \mathbf{u} is a general solution of (5.6), then the difference $\mathbf{w}(\tau, y) = \mathbf{u}(\tau, y) - \mathbf{U}(y)$ is a solution as well. Hence, we obtain

$$\begin{aligned} \frac{1}{2} \frac{d}{d\tau} \|\mathbf{w}\|_{L^2}^2 &= \int_{\mathbb{R}} \mathbf{w} \cdot \mathbf{w}_\tau = \int_{\mathbb{R}} \mathbf{w} \cdot (\mathbb{A}\mathbf{w}_{yy} + \frac{y}{2}\mathbf{w}_y) dy \\ &= \int_{\mathbb{R}} (-\mathbf{w}_y \cdot \mathbb{A}\mathbf{w}_y - \frac{1}{4}|\mathbf{w}|^2) dy \leq -\frac{1}{4} \|\mathbf{w}\|_{L^2}^2. \end{aligned}$$

Thus, Gronwall's estimate yields

$$\|\mathbf{u}(\tau) - \mathbf{U}\|_{L^2}^2 \leq e^{-\tau/2} \|\mathbf{u}(0) - \mathbf{U}\|_{L^2}^2.$$

We emphasize that this estimate is even true in the case of the linear Schrödinger equation $i\psi_t = \psi_{xx}$ which can be realized as a real system with $\mathbf{u} = (\operatorname{Re} \psi, \operatorname{Im} \psi)$ and $\mathbb{A} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}$, see Example 2.1(III).

5.4 One reaction for two species

In [GaS22, MiS23] the following system of two equations is studied in detail:

$$\begin{pmatrix} \dot{c}_1 \\ \dot{c}_2 \end{pmatrix} = \begin{pmatrix} d_1 \partial_x^2 c_1 \\ d_2 \partial_x^2 c_2 \end{pmatrix} - \kappa \begin{pmatrix} \gamma (c_1^\gamma - c_2^\beta) \\ \beta (c_2^\beta - c_1^\gamma) \end{pmatrix} \quad \text{for } t > 0 \text{ and } x \in \mathbb{R}.$$

The two concentrations $c_1, c_2 \geq 0$ for the species X_1, X_2 diffusive with diffusion constants d_j and undergo the reversible mass-action reaction $\gamma X_1 \rightleftharpoons \beta X_2$.

The scaled and constrained system (5.4) takes the form

$$\partial_\tau \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} d_1 \partial_y^2 c_1 \\ d_2 \partial_y^2 c_2 \end{pmatrix} + \frac{y}{2} \partial_y \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} + \lambda \begin{pmatrix} \gamma \\ -\beta \end{pmatrix}, \quad \lambda \in \mathbb{R}, \quad c_1^\gamma = c_2^\beta.$$

The set of equilibria for \mathbf{R} is a one-parameter family given by

$$\{ \mathbf{c} \in \mathfrak{C} \mid \mathbf{R}(\mathbf{c}) = 0 \} = \{ (A^\beta, A^\gamma) \mid A \geq 0 \}.$$

We consider the stoichiometric mapping $\mathbb{Q} = \begin{pmatrix} \beta & \gamma \end{pmatrix} \in \mathbb{R}^{1 \times 2}$ defining $u = \beta c_1 + \gamma c_2 \geq 0$. The function $\Psi : [0, \infty[\rightarrow [0, \infty]^2$ is defined via

$$\mathbf{c} = \Psi(u) = \begin{pmatrix} \psi_1(u) \\ \psi_2(u) \end{pmatrix} \iff (u = \mathbb{Q}\mathbf{c} = \beta c_1 + \gamma c_2 \text{ and } c_1^\gamma = c_2^\beta).$$

The case $\gamma = \beta$ leads to the simple relation $\Psi(u) = \frac{1}{\beta+\gamma} \binom{u}{u}$. If $\beta \neq \gamma$, we may assume $\beta < \gamma$ without loss of generality. Then,

$$\begin{aligned} \psi_1 \text{ is concave,} \quad \psi_1(u) &= u/\beta + \text{h.o.t.}_{u \rightarrow 0^+}, & \psi_1(u) &= (u/\gamma)^{\beta/\gamma} + \text{l.o.t.}_{u \rightarrow \infty}, \\ \psi_2 \text{ is convex,} \quad \psi_2(u) &= (u/\beta)^{\gamma/\beta} + \text{h.o.t.}_{u \rightarrow 0^+}, & \psi_2(u) &= u/\gamma + \text{l.o.t.}_{u \rightarrow \infty}. \end{aligned}$$

For $A_\Psi(u) := \mathbb{Q}D\Psi(u) = \binom{\beta d_1}{\gamma d_2} \cdot \Psi(u)$ we can use $0 < \psi'_1(u) \leq \psi'_1(0) = 1/\beta$ and $0 < \psi'_2(u) \leq \psi'_2(\infty) = 1/\gamma$. This yields

$$\mathbb{D}(u) = A'_\Psi(u) \in [D_*, D^*], \quad \mathbb{D}(u) \rightarrow d_1 \text{ for } u \rightarrow 0^+, \quad \mathbb{D}(u) \rightarrow d_2 \text{ for } u \rightarrow \infty,$$

where $D_* = \min\{d_1, d_2\}$ and $D^* = \max\{d_1, d_2\}$.

Thus, the theory of Section 3 applies (simply extend \mathbb{D} by $\mathbb{D}(u) = d_1$ for $u \leq 0$). We are in the nondegenerate case, where the resulting profiles U solving

$$(A_\Psi(U))'' + \frac{y}{2} U' = 0 \text{ on } \mathbb{R}, \quad U(\pm\infty) = U_\pm,$$

are smooth, strictly monotone and converge to its two limits like the error function. In addition to $U_- \leq U(y) \leq U_+$ the estimate

$$0 \leq U'(y) \leq e^{-y^2/(4D^*)} \sqrt{\frac{D^*}{8D_*^2}} (U_+ - U_-) \quad \text{for all } y \in \mathbb{R} \quad (5.7)$$

holds, even in the case $U_- = 0$, where asymptotically the concentrations vanish, viz. $\mathbf{C}_- = \Psi(U_-) = \binom{0}{0}$, because the effective diffusion is still bounded from below by $D_* > 0$.

Of course, a profile $U : \mathbb{R} \rightarrow [U_-, U_+]$ for the reduced equation leads to a smooth concentration profile $\mathbf{C} : \mathbb{R} \rightarrow \mathfrak{C} \subset \mathbb{R}^2$ given by $\mathbf{C}(y) = \Psi(U(y))$ and satisfying the profile equation

$$\begin{aligned} 0 &= \begin{pmatrix} d_1 & 0 \\ 0 & d_2 \end{pmatrix} \mathbf{C}''(y) + \frac{y}{2} \mathbf{C}'(y) + \Lambda_U(y) \begin{pmatrix} \gamma \\ -\beta \end{pmatrix}, \quad C_1(y)^\gamma = C_2(y)^\beta, \\ \mathbf{C}(y) &\rightarrow \Psi(U_\pm) \text{ for } y \rightarrow \pm\infty. \end{aligned}$$

Remark 5.1 In [MiS23] the convergence to the asymptotic steady state $y \mapsto \mathbf{C}(y) = \Psi(U(y))$ for the scaled reaction-diffusion system (5.2) is investigated. For this, it is necessary to bound the Lagrange multiplier

$$\Lambda_U(y) := -\frac{1}{\gamma} \left(d_1 C_1''(y) + \frac{y}{2} C_1'(y) \right) = \frac{1}{\beta} \left(d_2 C_2''(y) + \frac{y}{2} C_2'(y) \right) \text{ in } L^\infty(\mathbb{R}),$$

where the second identity holds by construction from $A_\Psi(u) = \beta d_1 \psi_1(u) + \gamma d_2 \psi_2(u)$. Using the relation $C_1(y) = \psi_1(U(y))$, where $\psi_1 :]0, \infty[\rightarrow]0, \infty[$ is C^∞ , and exploiting the bounds $0 < U_- \leq U(y) \leq U_+$, the identity $U'' = -(A''(U)(U')^2 + \frac{y}{2} U')/A'(U)$, and estimate (5.7), we obtain the following result. Fixing $d_1, d_2 > 0$ and $\gamma > \beta > 0$, for every $M > 0$ there exists a constant $C_M > 0$ such that

$$U_+, U_- \in [1/M, M] \text{ implies } |\Lambda_U(y)| \leq C_M |U_+ - U_-| \text{ for all } y \in \mathbb{R}.$$

5.5 One reaction for three species

We consider the classical binary reaction $X_3 \rightleftharpoons X_1 + X_2$ leading to the scaled RDS

$$\partial_\tau \mathbf{c} = \mathbf{D} \partial_y^2 \mathbf{c} + \frac{y}{2} \partial_y \mathbf{c} - e^\tau (c_1 c_2 - c_3) \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix} \quad \text{with } \mathbf{D} = \begin{pmatrix} d_1 & 0 & 0 \\ 0 & d_2 & 0 \\ 0 & 0 & d_3 \end{pmatrix}.$$

The associated profile equation reads

$$\mathbf{D} \mathbf{C}'''(y) + \frac{y}{2} \mathbf{C}'(y) + \lambda(y) \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix} = 0, \quad C_1(y)C_2(y) = C_3(y) \quad \text{and} \quad \mathbf{C}(\pm\infty) = \Psi(\mathbf{U}_\pm). \quad (5.8)$$

The set of equilibria for \mathbf{R} is a two-parameter family, namely

$$\{ \mathbf{c} \in \mathfrak{C} \mid \mathbf{R}(\mathbf{c}) = 0 \} = \{ (A, B, AB) \mid A, B \geq 0 \}.$$

We can choose the stoichiometric matrix

$$\mathbb{Q} = \begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \end{pmatrix} \in \mathbb{R}^{2 \times 3}$$

and obtain $\mathbf{u} = \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \mathbb{Q} \mathbf{c} \in \mathfrak{U} := [0, \infty]^2$. The reduction function $\Psi : \mathfrak{U} \rightarrow \mathfrak{C}$ can be calculated explicitly in the form

$$\Psi(u_1, u_2) = \frac{1}{2} \begin{pmatrix} u_1 - u_2 - 1 + s(\mathbf{u}) \\ u_2 - u_1 - 1 + s(\mathbf{u}) \\ u_1 + u_2 + 1 - s(\mathbf{u}) \end{pmatrix} \quad \text{with } s(\mathbf{u}) := \sqrt{(1 + u_1 + u_2)^2 - 4u_1 u_2}.$$

To extend s to a function $s : \mathbb{R}^2 \rightarrow \mathbb{R}$ we simply set $s(u_1, u_2) = 1 + u_1 + u_2$ whenever $u_1 \leq 0$ or $u_2 \leq 0$ and observe that s is globally Lipschitz continuous. Moreover, $s_j(\mathbf{u}) = \partial_{u_j} s(\mathbf{u})$ satisfies $s_1(\mathbf{u}) \leq 1$, $s_2(\mathbf{u}) \leq 1$ and $s_1(\mathbf{u}) + s_2(\mathbf{u}) \geq 0$ for all $\mathbf{u} \in \mathbb{R}^2$.

From this we can calculate the function $\mathbf{A}(\mathbf{u}) = \mathbb{Q} \mathbf{D} \Psi(\mathbf{u})$ with $\mathbf{D} = \text{diag}(d_j)$:

$$\mathbf{A}(\mathbf{u}) = \frac{1}{2} \begin{pmatrix} (d_1 + d_3)u_1 + (d_3 - d_1)(1 + u_2 - s(\mathbf{u})) \\ (d_2 + d_3)u_2 + (d_3 - d_2)(1 + u_1 - s(\mathbf{u})) \end{pmatrix}.$$

For general C^1 functions \mathbf{A} we have the equivalence

$$\forall \mathbf{u}, \tilde{\mathbf{u}} : \langle \mathbf{A}(\mathbf{u}) - \mathbf{A}(\tilde{\mathbf{u}}), \mathbf{u} - \tilde{\mathbf{u}} \rangle \geq a_{10} |\mathbf{u} - \tilde{\mathbf{u}}|^2 \quad \iff \quad \forall \mathbf{u} : \frac{1}{2} (\mathbf{D} \mathbf{A}(\mathbf{u}) + \mathbf{D} \mathbf{A}(\mathbf{u})^\top) \geq a_{10} I_{m \times m}.$$

Abbreviating $s_j = \partial_{u_j} s(\mathbf{u})$ and $\delta_j = 1 - d_j/d_3$ for $j = 1, 2$ we find

$$\frac{1}{2} (\mathbf{D} \mathbf{A}(\mathbf{u}) + \mathbf{D} \mathbf{A}(\mathbf{u})^\top) = \frac{d_3}{2} \begin{pmatrix} 2 - \delta_1 - \delta_1 s_1 & \frac{1}{2} (\delta_1 + \delta_2 - \delta_1 s_2 - \delta_2 s_1) \\ \frac{1}{2} (\delta_1 + \delta_2 - \delta_1 s_2 - \delta_2 s_1) & 2 - \delta_2 - \delta_2 s_2 \end{pmatrix} =: \mathbf{G}.$$

For $d_1 = d_2 = d_3$ we have $\delta_1 = \delta_2 = 0$ and obtain $\mathbf{G} = d_3 I_{2 \times 2}$ giving monotonicity with $a_{10} = d_3 > 0$. Using $s_j \in [-1, 1]$ it is also easy to show that $|\delta_1|, |\delta_2| < 1/2$ is sufficient for showing that \mathbf{G} is positive definite. More precisely, we have the following result.

Lemma 5.2 (Monotonicity) *The function $\mathbf{A} : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is strictly monotone ($\exists a_{10} > 0 \forall \mathbf{u}, \mathbf{w} \in \mathbb{R}^2: \langle \mathbf{A}(\mathbf{w}) - \mathbf{A}(\mathbf{u}), \mathbf{w} - \mathbf{u} \rangle \geq a_{10} |\mathbf{w} - \mathbf{u}|^2$) if and only if*

$$(3 - \sqrt{8})d_3 < d_j < (3 + \sqrt{8})d_3 \quad \text{for } j = 1, 2.$$

Proof. We keep δ_1 and δ_2 fixed and observe that $\mu(s_1, s_2) := \det \mathbf{G}$ is a quadratic polynomial in (s_1, s_2) which is concave, as the quadratic terms can be combined to $-(\delta_2 s_1 - \delta_1 s_2)^2$. As all (s_1, s_2) lie in the triangle $S := \{ (s_1, s_2) \mid s_1 \leq 1, s_2 \leq 1, s_1 + s_2 \geq 0 \}$ the assertion follows if we can show that $\min \{ \mu(s_1, s_2) \mid (s_1, s_2) \in S \}$ is positive. By concavity the minimum is attained in one of the three corners because they are the extremal points.

We have $\mu(1, 1) > 0$ whenever $\delta_1 < 1$ and $\delta_2 < 1$. Moreover, $\mu(1, -1) > 0$ holds for $|\delta_1 + 2| < \sqrt{8}$ and $\mu(-1, 1) > 0$ holds for $|\delta_2 + 2| < \sqrt{8}$. Inserting $\delta_j = 1 - d_j/d_3$, the desired result follows. ■

Under the assumptions of the above monotonicity result, our existence theory in Theorem 2.2 provides unique similarity profiles $\mathbf{U} : \mathbb{R} \rightarrow \mathbb{R}^2$ connecting \mathbf{U}_- and \mathbf{U}_+ . These solutions give rise to similarity profiles $\mathbf{C} = \Psi \circ \mathbf{U}$ connecting $\Psi(\mathbf{U}_+)$ and $\Psi(\mathbf{U}_-)$ if and only if $\mathbf{U}(y) \in \mathfrak{U} = [0, \infty]^2$ for all $y \in \mathbb{R}$, thus providing $\mathbf{C}(y) = \Psi(\mathbf{U}(y)) \in \mathfrak{C} = [0, \infty]^3$. In general we cannot guarantee this condition, but Corollary 2.3 provides an estimate of the form

$$|\mathbf{U}(y) - \tilde{\mathbf{u}}_{\pm}(y)| \leq C_* |\mathbf{U}_+ - \mathbf{U}_-| = C_* \Delta_{\pm},$$

where C_* only depends on d_1, d_2 , and d_3 , but not on \mathbf{U}_{\pm} . As $\tilde{\mathbf{u}}_{\pm}(y)$ takes values on the straight line connecting \mathbf{U}_- and \mathbf{U}_+ , we conclude that our abstract theory is applicable if $(3 - \sqrt{8})d_3 < d_1, d_2 < (3 + \sqrt{8})d_3$ and $|\mathbf{U}_+ - \mathbf{U}_-|$ is sufficiently small compared to the distance of \mathbf{U}_+ and \mathbf{U}_- from the boundary of \mathfrak{U} . Then similarity profiles $\mathbf{C} : \mathbb{R} \rightarrow \mathbb{R}^3$ solving (5.8) exist and are unique.

In the present example we obtain nonmonotone profiles $\mathbf{C} : \mathbb{R} \rightarrow \mathfrak{C} \subset \mathbb{R}^3$. For this, consider the case $d_1 = d_2$ and the limits

$$\mathbf{C}_- = (A, B, AB)^{\top} \quad \text{and} \quad \mathbf{C}_+ = (B, A, AB)^{\top} \quad \text{with } A \neq B.$$

Our uniqueness result and the reflection symmetries $x \rightarrow -x$ and $(c_1, c_2) \rightarrow (c_2, c_1)$ imply that the stationary profile \mathbf{C} satisfies $C_1(y) = C_2(-y)$ and $C_3(y) = C_3(-y)$. Using $C_1(y)C_2(y) = C_3(y)$ for all $y \in \mathbb{R}$ we see that C_3 cannot be constant, hence it must be nonmonotone. In Figure 5.1 we show an example.

An interesting open question is whether there is a stationary profile \mathbf{C} connecting the limiting cases

$$\mathbf{C}_- = \Psi(1, 0) = (1, 0, 0)^{\top} \quad \text{and} \quad \mathbf{C}_+ = \Psi(0, 1) = (0, 1, 0)^{\top}.$$

The profile would see only one of the species X_1 or X_2 in the limits to $\pm\infty$, however in the middle region all three species must be present to allow the generation of the other species.

5.6 Two reactions for three species

Consider the two reactions $2X_1 \rightleftharpoons X_2$ and $X_2 \rightleftharpoons X_3$ giving

$$\partial_{\tau} \mathbf{c} = \mathbf{D} \partial_y^2 \mathbf{c} - k_1 (c_1^2 - c_2) \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix} - k_2 (c_2 - c_3) \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}. \quad (5.9)$$

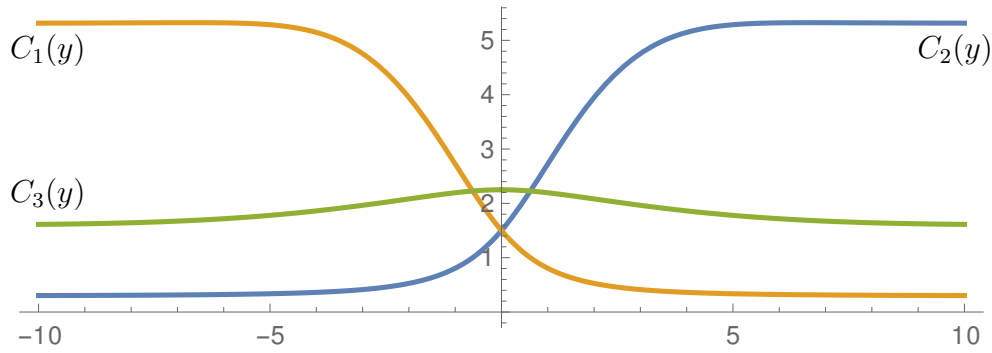


Figure 5.1: Solution $\mathbf{C} = (C_1(y), C_2(y), C_3(y))$ of (5.8) for $d_1 = d_2 = 2$ and $d_3 = 10$ with limiting values $\mathbf{C}_- \approx (5.3, 0.3, 1.6)$ and $\mathbf{C}_+ \approx (0.3, 5.3, 1.6)$. This symmetric solution was obtained by starting with $\mathbf{C}(0) = (1.5, 1.5, 2.25)$ and $\mathbf{C}'(y) = (-1, 1, 0)$.

The set of equilibria is the one-parameter family given by

$$\{\mathbf{c} \in \mathfrak{C} \mid \mathbf{R}(\mathbf{c}) = 0\} = \{(A, A^2, A^2) \mid A \geq 0\}.$$

Note that the RDS system has invariant regions of the form $\Sigma := [b, B] \times [b^2, B^2] \times [b^2, B^2]$ for arbitrary $0 \leq b < B < \infty$, see [Smo94, Chap. 14 §B]. This means that any solution satisfying $\mathbf{c}(0, x) \in \Sigma$ for all $x \in \mathbb{R}$ also satisfies $\mathbf{c}(t, x) \in \Sigma$ for all $t > 0$ and $x \in \mathbb{R}$. Thus, a similarity profile connecting $\mathbf{C}_- = (b, b^2, b^2)$ and $\mathbf{C}_+ = (B, B^2, B^2)$ is expected to lie in the invariant region Σ .

The stoichiometric matrix is $\mathbb{Q} = (1 \ 2 \ 2) \in \mathbb{R}^{1 \times 3}$ and

$$u = \mathbb{Q}\mathbf{c} = c_1 + 2c_2 + 2c_3 \quad \text{yields } \Psi(u) = \begin{pmatrix} \sigma(u) \\ (u - \sigma(u))/4 \\ (u - \sigma(u))/4 \end{pmatrix} \quad \text{with } \sigma(u) = (\sqrt{1+16u} - 1)/8.$$

With $\sigma'(u) = 1/\sqrt{1+16u} \in [0, 1]$ we easily see that all mappings $u \mapsto \Psi_j(u)$ are monotonously increasing. Moreover, the function $A(u) = \mathbb{Q}\mathbf{D}\Psi(u)$ satisfies

$$A(u) = \frac{d_2+d_3}{2} u + (d_1 - \frac{d_2+d_3}{2}) \sigma(u) \quad \text{and } \min\{d_1, \frac{d_2+d_3}{2}\} \leq A'(u) \leq \max\{d_1, \frac{d_2+d_3}{2}\}.$$

Thus, the scalar theory of Section 3 is applicable and for $0 \leq U_- \leq U_+ < \infty$ there exists a unique similarity profile $U \in C^\infty(\mathbb{R}; [U_-, U_+])$ that is monotonously increasing.

As a consequence, the profile equation

$$\mathbf{D}\mathbf{C}''(y) + \frac{y}{2}\mathbf{C}'(y) + \lambda_1(y) \begin{pmatrix} 2 \\ -1 \\ 0 \end{pmatrix} + \lambda_2(y) \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix} = 0, \tag{5.10}$$

$$C_1(y)^2 = C_2(y) = C_3(y) \quad \text{and } \mathbf{C}(\pm\infty) = \begin{pmatrix} B_\pm \\ B_\pm^2 \\ B_\pm^2 \end{pmatrix}$$

has for all $B_- \leq B_+$ a unique solution \mathbf{C} and each component C_j is monotonously increasing, and hence lying in the invariant region $\Sigma = [B_-, B_+] \times [B_-^2, B_+^2] \times [B_-^2, B_+^2]$.

6 Various systems with similarity profiles

In this section we mention the connection of our theory to two more systems in which similarity profiles play a nontrivial role. The first example concerns the diffusive mixing between role patterns in the real Ginzburg-Landau equation as studied in [BrK92, GaM98]. The second example is a system of two degenerate parabolic equations that are coupled to satisfy a thermodynamical conservation law.

6.1 Profiles connecting roles in the Ginzburg-Landau equation

For a complex-valued amplitude $Z(t, x) \in \mathbb{C}$ the real Ginzburg-Landau equation (i.e. the coefficients are real)

$$\dot{Z} = Z_{xx} + Z - |Z|^2 Z \quad (6.1)$$

is an important model in bifurcation theory and pattern formation. It has an explicit two-parameter family of steady state pattern in form of the role solutions $Z(x) = U_{\eta, \varphi}(x) := \sqrt{1-\eta^2} e^{i(\eta x + \varphi)}$ with wave number $\eta \in [-1, 1]$ and phase $\varphi \in [0, 2\pi]$.

Starting from [BrK92, CoE92], it was shown in [GaM98] that asymptotically self-similar profiles exist that connect two different role solutions U_{η_-, φ_-} at $x \rightarrow -\infty$ and U_{η_+, φ_+} at $x \rightarrow \infty$. Indeed, the monotone operator approach used in Theorem 2.2 for solving the profile equation was initiated in [GaM98, Thm. 3.1].

Writing $Z = r e^{iu}$ and assuming $r(t, x) > 0$, the real Ginzburg-Landau equation can be rewritten as the coupled system $\dot{r} = r_{xx} + r(1-r^2-u_x^2)$, $\dot{u} = u_{xx} + 2\frac{r_x}{r}u_x$. Assuming $r^2 + u_x^2 \approx 1$ for $t \gg 1$, one is lead to the so-called *phase diffusion equation*

$$\dot{u} = (A(u_x))_x = A'(u_x)u_{xx}, \quad \text{where } A'(\eta) = \frac{1-3\eta^2}{1-\eta^2}.$$

Introducing the local wave number $\eta(t, x) = u_x(t, x)$ one finds the quasilinear equation

$$\dot{\eta} = (A(\eta))_{xx} \quad \text{with } A'(\eta) > 0 \text{ for } \eta \in \left] \frac{-1}{\sqrt{3}}, \frac{1}{\sqrt{3}} \right[.$$

The existence of self-similar profiles $\bar{\eta} : \mathbb{R} \rightarrow [\eta_-, \eta_+]$ connecting η_- and η_+ (where $-1/\sqrt{3} < \eta_- \leq \eta_+ < 1/\sqrt{3}$) as well as the local convergence of the full solutions $Z(t, x)$ of (6.1) to the corresponding asymptotic profile $\sqrt{1-\bar{\eta}(x/t^{1/2})} e^{i t^{1/2} H(x/t^{1/2})}$ with $H'(y) = \bar{\eta}(y)$ is established in [GaM98] using suitable weighted Sobolev norms.

6.2 A coupled system motivated by thermodynamics

The following degenerate parabolic system couples a velocity-like variable v to an energy-like variable w such that the total momentum $\mathcal{V}(v) = \int_{\mathbb{R}^d} v(x) dx$ and the total energy $\mathcal{E}(v, w) = \int_{\mathbb{R}^d} (\frac{1}{2}v(x)^2 + w(x)) dx$ are conserved along solutions of

$$\dot{v} = \operatorname{div}(\eta(w)\nabla v), \quad \text{for } (t, x) \in]0, \infty[\times \mathbb{R}^d, \quad (6.2a)$$

$$\dot{w} = \operatorname{div}(\kappa(w)\nabla w) + \eta(w)|\nabla v|^2 \quad \text{for } (t, x) \in]0, \infty[\times \mathbb{R}^d, \quad (6.2b)$$

see [Mie23] for more motivation. Because of the full invariance under the parabolic scaling, the parabolically scaled equation is independent of τ :

$$\partial_\tau \tilde{v} - \frac{1}{2} y \cdot \nabla \tilde{v} = \operatorname{div}(\eta(\tilde{w}) \nabla \tilde{v}), \quad \partial_\tau \tilde{w} - \frac{1}{2} y \cdot \nabla \tilde{w} = \operatorname{div}(\kappa(\tilde{w}) \nabla \tilde{w}) + \eta(\tilde{w}) |\nabla \tilde{v}|^2. \quad (6.3)$$

As the system contains the porous medium equation (4.1) with $A(w) = \frac{1}{\beta+1} w^{\beta+1}$ (by simply setting $v \equiv 0$) there are the classical Barenblatt solutions as a steady state $(V, W) = (0, B_M)$ where $M \geq 0$ is the mass $M = \int_{\mathbb{R}^d} B_M(y) \, dy$. As studied in Section 3, there are also similarity profiles of the form $(v, w) = (0, W)$, however, we expect that it is also possible to show that for each pair (V_\pm, W_\pm) with $V_-, V_+ \in \mathbb{R}$ and $W_-, W_+ \geq 0$ there is a unique similarity profile. However, it seems that our monotonicity approach developed in Section 2 cannot be used here.

Nevertheless, a nontrivial explicit self-similar solution can be given in the case $\eta(w) = \kappa(w) = w$ with the limits $(V_\pm, W_\pm) = (\pm\sqrt{2} B, 0)$ (cf. [Mie23, Ex. 2.2]), namely

$$(V(y), W(y)) = \begin{cases} (y/\sqrt{2}, B^2 - y^2/4) & \text{for } |y| \leq 2B, \\ (\pm\sqrt{2} B, 0) & \text{for } \pm y \geq 2B, \end{cases} \quad (6.4)$$

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