



Exercise Sheet 8

- 1) Let X be a Hilbert space and let $F : X \rightarrow \overline{\mathbb{R}}$ be convex, proper and lower semi-continuous. Consider again the function

$$F_\gamma(u) = \inf_{v \in X} J_\gamma(u, v) = F(v) + \frac{1}{2\gamma} \|u - v\|_X^2$$

from sheet 6, together with its unique minimizer $P_\gamma : X \rightarrow X$ defined by

$$P_\gamma(u) = \arg \min_{v \in X} J(u, v).$$

Show the following properties:

- (i) $F_\gamma(u) \uparrow F(u)$ as $\gamma \downarrow 0$.
- (ii) $P_\gamma(u) \rightarrow u$ as $\gamma \rightarrow 0$ for all $u \in \overline{\text{dom}(F)}$ and $P_\gamma(u) \rightarrow \text{Proj}_{\overline{\text{dom}(F)}}(u)$ as $\gamma \rightarrow 0$ for $u \in X$.
- (iii) For $u \in \text{dom}(F)$ we have $\nabla P_\gamma(u) \rightarrow p^* \in X$ as $\gamma \rightarrow 0$ where

$$p^* \in \arg \min_{p \in \partial F(u)} \|p\|_X^2$$

- 2) For $n \leq 3$ and $\Omega \subset \mathbb{R}^n$ open, bounded with C^2 boundary consider the following state constrained optimal control problem. Here $b \in H^2(\Omega)$, $b > 0$, $\alpha > 0$ and $y_d \in L^2(\Omega)$.

(P)
$$\min_{(y,u) \in H_0^1(\Omega) \times L^2(\Omega)} J(y, u) := \frac{1}{2} \|y - y_d\|_{L^2(\Omega)}^2 + \frac{\alpha}{2} \|u\|_{L^2(\Omega)}^2$$

subject to
$$\begin{aligned} -\Delta y &= u \text{ on } \Omega, \\ y &= 0 \text{ on } \partial\Omega, \\ y &\leq b \text{ a.e. on } \Omega, \end{aligned}$$

- (i) Show that (P) has a unique solution in $[H_0^1(\Omega) \cap H^2(\Omega)] \times L^2(\Omega)$.
- (ii) Show that if $(\bar{y}, \bar{u}) \in H_0^1(\Omega) \times L^2(\Omega)$ solves (P) there is a $\bar{\mu} \in \mathcal{M}(\Omega) := C_0(\Omega)'$ and $p \in L^2(\Omega)$ such that

(Opt)
$$\begin{aligned} -\Delta \bar{y} &= \bar{u} && \text{in } H_0^1(\Omega) \\ \langle \bar{p}, -\Delta v \rangle_{L^2(\Omega)} + \langle \bar{\mu}, v \rangle_{\mathcal{M}(\Omega)} &= -\langle \bar{y} - y_d, v \rangle_{L^2(\Omega)} && \text{for every } v \in H^2(\Omega) \cap H_0^1(\Omega) \\ \alpha \bar{u} - \bar{p} &= 0 && \text{in } \Omega \\ \bar{y} \leq b \quad \langle \bar{\mu}, v - \bar{y} \rangle_{\mathcal{M}(\Omega)} &\leq 0 && \text{for all } v \in C(\overline{\Omega}), v \leq b \end{aligned}$$

- 3) Consider for the same assumptions as in exercise 2) the regularized problem with $\gamma > 0$:

(P $_\gamma$)
$$\min_{(y,u) \in H_0^1(\Omega) \times L^2(\Omega)} J_\gamma(y, u) := \frac{1}{2} \|y - y_d\|_{L^2(\Omega)}^2 + \frac{\alpha}{2} \|u\|_{L^2(\Omega)}^2 + \frac{1}{2\gamma} \|\max(0, \hat{\mu} + \gamma(y - b))\|_{L^2(\Omega)}^2$$

subject to
$$\begin{aligned} -\Delta y &= u \text{ on } \Omega, \\ y &= 0 \text{ on } \partial\Omega. \end{aligned}$$

Here $\hat{\mu} \in L^2(\Omega)$, $\hat{\mu} \geq 0$ is a fixed, optional shift-parameter.

- (i) Show that (\mathbf{P}_γ) has a unique solution $(\bar{y}_\gamma, \bar{u}_\gamma) \in [H_0^1(\Omega) \cap H^2(\Omega)] \times L^2(\Omega)$, which satisfies the first order system

$$\begin{aligned}
 & -\Delta \bar{y}_\gamma = \bar{u}_\gamma && \text{in } H_0^1(\Omega) \\
 (\text{Opt}_\gamma) \quad & -\Delta \bar{p}_\gamma = (\bar{y}_\gamma - y_d) - \max(0, \hat{\mu} + \gamma(\bar{y}_\gamma - b)) && \text{in } H_0^1(\Omega) \\
 & \alpha \bar{u}_\gamma - \bar{p}_\gamma = 0 && \text{in } \Omega
 \end{aligned}$$

- (ii) Define $\bar{\mu}_\gamma = \max(0, \hat{\mu} + \gamma(\bar{y}_\gamma - b))$ and show that given $\gamma_0 \geq 0$ the path $(\bar{y}_\gamma, \bar{u}_\gamma, \bar{p}_\gamma, \bar{\mu}_\gamma)_{\gamma \geq \gamma_0}$ is bounded in the space $Y \times L^2(\Omega) \times L^2(\Omega) \times Y'$. Here the space Y is defined as

$$Y := H_0^1(\Omega) \cap H^2(\Omega).$$

Moreover $(\bar{y}_\gamma, \bar{u}_\gamma, \bar{p}_\gamma, \bar{\mu}_\gamma) \rightarrow (\bar{y}, \bar{u}, \bar{p}, \bar{\mu})$ in $Y \times L^2(\Omega) \times L^2(\Omega) \times Y'$ as $\gamma \rightarrow \infty$ where $(\bar{y}, \bar{u}, \bar{p}, \bar{\mu})$ solves (\mathbf{P}) .

- (iii) Bonus: Show that for any $\gamma_0 > 0$ the mapping

$$[\gamma_0, +\infty) \rightarrow Y \times L^2(\Omega) \times L^2(\Omega) \times Y' \quad \gamma \mapsto (\bar{y}_\gamma, \bar{u}_\gamma, \bar{p}_\gamma, \bar{\mu}_\gamma)$$

is Lipschitz continuous.