Rough paths and cubature

The Ninomiya-Victoir method

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## Some applications of cubature on Wiener space

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## Outline

## Cubature on Wiener space

- The weak approximation problem
- Cubature on Wiener space
- 2 Rough paths and cubature
- The Ninomiya-Victoir method

## 4 Outlook

- Multi-Level Monte Carlo
- Adaptive cubature

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Weak approximation of solutions of SDEs

$$dX_t = V_0(X_t)dt + \sum_{i=1}^d V_i(X_t) \circ dB_t^i \eqqcolon \sum_{i=0}^d V_i(X_t) \circ dB_t^i, \quad (1)$$

- $V_0, \ldots, V_d : \mathbb{R}^N \to \mathbb{R}^N$  vector fields,
- $B_t$  a *d*-dimensional Brownian motion,  $B_t^0 := t$ ,
- $X_0 = x \in \mathbb{R}^N$ .

#### Problem

For  $f : \mathbb{R}^N \to \mathbb{R}$  sufficiently regular, compute  $u(0, x) := E[f(X_T)]$ .

#### Example

- Option pricing
- ▶ Numerical solution of parabolic PDEs:  $\partial_t u + Lu = 0$

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# Stochastic Taylor expansion

Ito formula for Stratonovich calculus

$$df(X_t) = V_0 f(X_t) dt + \sum_{i=1}^d V_i f(X_t) \circ dB_t^i = \sum_{i=0}^d V_i f(X_t) \circ dB_t^i,$$
  
where  $V_i f(x) \coloneqq V_i(x) \cdot \nabla f(x)$ .

$$f(X_t) = f(x) + \sum_{i=0}^d \int_0^t V_i f(X_s) \circ dB_s^i,$$

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where 
$$V_i f(x) \coloneqq V_i(x) \cdot \nabla f(x)$$
.

$$f(X_t) = f(x) + \sum_{i=0}^d \int_0^t \underbrace{\bigvee_{i=0}^i f(X_s)}_{=V_i f(x) + \sum_{j=0}^d \int_0^s V_j V_i f(X_u) \circ dB_u^j} \circ dB_s^j,$$

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where  $V_i f(x) \coloneqq V_i(x) \cdot \nabla f(x)$ .

$$f(X_t) = f(x) + \sum_{i=0}^d V_i f(x) B_t^i + \sum_{i,j=0}^d \int_{0 \le u \le s \le t} V_j V_i f(X_u) \circ dB_u^j \circ dB_s^i,$$

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where 
$$V_i f(x) \coloneqq V_i(x) \cdot \nabla f(x)$$
.

$$f(X_t) = f(x) + \sum_{i=0}^d V_i f(x) B_t^i$$
  
+ 
$$\sum_{i,j=0}^d \int_{0 \le u \le s \le t} \underbrace{V_j V_i f(X_u)}_{=V_j V_i f(x) + \sum_{l=0}^d \int_0^u V_l V_j V_l f(X_v) \circ dB_v^l} \circ dB_u^j \circ dB_s^j,$$

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where 
$$V_i f(x) := V_i(x) \cdot \nabla f(x)$$
.

$$f(X_t) = f(x) + \sum_{i_1=0}^{d} V_{i_1}f(x)B_t^{i_1} + \sum_{i_1,i_2=0}^{d} V_{i_1}V_{i_2}f(x)\int_0^t B_{t_2}^{i_1} \circ dB_{t_2}^{i_2} + \sum_{i_1,i_2,i_3=0}^d \int_{0 \le t_1 \le t_2 \le t_3 \le t} V_{i_1}V_{i_2}V_{i_3}f(X_{t_1}) \circ dB_{t_1}^{i_1} \circ dB_{t_2}^{i_2} \circ dB_{t_3}^{i_3},$$

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where  $V_i f(x) \coloneqq V_i(x) \cdot \nabla f(x)$ .

$$f(X_t) = \sum_{k=0}^{m} \sum_{(i_1,\dots,i_k)\in\{0,\dots,d\}^k} V_{i_1}\cdots V_{i_k}f(x)B_t^{(i_1,\dots,i_k)} + R_m(t,x,f),$$
  
$$\sup_x \sqrt{E[R_m^2]} = O(t^{\frac{m+1}{2}}), B_t^{(i_1,\dots,i_k)} \coloneqq \int_{0\le t_1\le\dots\le t_k\le t} \circ dB_{t_1}^{i_1}\cdots \circ dB_{t_k}^{i_k}.$$

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Random ODE	S			

Let W be a (d + 1)-dimensional process with paths of bounded variation, define X
<sub>t</sub> = X(W)<sub>t</sub> by the random ODE

$$\frac{d}{dt}\widetilde{X}_t = \sum_{i=0}^d V_i(\widetilde{X}_t)\dot{W}_t^i, \quad \widetilde{X}_0 = x.$$
(2)

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Ordinary Taylor expansion:

$$f(\widetilde{X}_{t}) = \sum_{k=0}^{m} \sum_{(i_{1},...,i_{k})\in\{0,...,d\}^{k}} V_{i_{1}}\cdots V_{i_{k}}f(x)W_{t}^{(i_{1},...,i_{k})} + \widetilde{R}_{m}(t,x,f)$$

Remember: Stochastic Taylor expansion

$$f(X_t) = \sum_{k=0}^{m} \sum_{(i_1,...,i_k) \in \{0,...,d\}^k} V_{i_1} \cdots V_{i_k} f(x) B_t^{(i_1,...,i_k)} + R_m(t,x,f)$$

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# Cubature on Wiener space

#### Definition

W is a cubature formula on Wiener space of degree m iff  $E\left[W_t^{(i_1,...,i_k)}\right] = E\left[B_t^{(i_1,...,i_k)}\right]$  for  $k \le m$ .

#### Remark

In fact, only need multi-indices  $(i_1, ..., i_k)$  such that  $k + \#\{\ell : i_\ell = 0\} \le m$ :  $B_t^0$  counts twice due to scaling of Brownian motion. This property is ignored for ease of presentation!

- Cubature formulas with finite support exist (Lyons and Victoir)
- Construction of cubature formulas for m > 5 interesting open problem

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Weak approxi	mation			

• Local error: 
$$E[f(X_t)] - E[f(\widetilde{X}_t^{(m)})] = O(t^{(m+1)/2}).$$

- ► Fix a grid 0 = t<sub>0</sub> < t<sub>1</sub> < ··· < t<sub>n</sub> = T, define W by concatenation of independent cubature formulas (of degree m) on the subintervals [t<sub>i</sub>, t<sub>i+1</sub>].
- Global error:  $E[f(X_T)] E[f(\widetilde{X}_T^{(m)})] = O((\sup \Delta t)^{(m-1)/2})$
- Used very stringent regularity conditions!
- Weaker assumption: non-uniform grid + Hörmander condition, allow f to be uniformly Lipschitz only (Kusuoka)
- Support of W grows exponentially in n, but n usually small (otherwise: recombination techniques or (quasi) Monte Carlo)

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Extensions				

- ► Jump diffusions (B. and Teichmann): add jump times to grid, but at most *m*/2 for each initial interval
- May reduce order of cubature method by two for each jump
- Backward SDEs (Crisan and Manolarakis): allows to solve semilinear parabolic PDEs with cubature methods
- Stochastic PDEs (B. and Teichmann): epxectation of an SPDE approximated by an expectation of a random PDE

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Conceptually easier than Euler methods in this case

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Example: SPI	DEs			

$$dX_t = (AX_t + \alpha(X_t))dt + \sum_{i=1}^d \sigma_i(X_t)dB_t^i$$

• Cubature method: solution  $\widetilde{X}$  of random PDE

$$\dot{\widetilde{X}}_t = (A\widetilde{X}_t + lpha_0(\widetilde{X}_t)) + \sum_{i=1}^d \sigma_i(\widetilde{X}_t) \dot{W}_t^i$$

- Use existing deterministic PDE solvers
- Euler method: iteration

$$\overline{X}_{n+1} = (A\overline{X}_n + \alpha(\overline{X}_n))\Delta t_n + \sum_{i=1}^d \sigma_i(\overline{X}_n)\Delta B_n^i,$$

► Need to discretice A and develop new solver from scratch

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Need to discretice A and develop new solver from scratch

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Signature				

#### Definition

The collection of random variables

$$S_{0,t}^m \coloneqq \left(B_t^{(i_1,\ldots,i_k)}\right)_{k \le m}$$

is called truncated signature of the Brownian motion. (Analogous definition for other processes/paths.)

- Values in a certain step *m* nilpotent Lie group (*m* = 2: Heisenberg group).
- Algebra of paths corresponds nicely to group structure:
  - concatenation of paths ≡ multiplication of signatures
  - scaling of paths = dilatation on the group
  - metric on group obtained via geodesic paths
- Rough path: 1/p-Hölder continuous path in the Lie group.
   (For Brownian motion: 2

Linivoreal limit	theorem			
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Rough DE: for a d-dimensional (smooth) path w consider

$$dX(w)_t = \sum_{i=0}^d V_i(X(w)_t) dw_t^i$$

• Define the Ito map  $I(S_0^m(w)) \coloneqq X(w)$ .

- Solution of SDE is continuous map of Brownian motion and
- Given processes  $W^n$  s.t.  $S(W^n) \rightarrow S(B)$ , we have strong ション 小田 マイビット ビー シックション

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$$dX(w)_t = \sum_{i=0}^d V_i(X(w)_t) dw_t^i$$

• Define the Ito map  $I(S_0^m(w)) \coloneqq X(w)$ .

#### Theorem (Lyons)

*I* is continuous in 1/p-Hölder topology, uniformly on bounded sets, provided that  $m \ge |p|$ . Thus, the solution to the rough equation can be extended to a wide family of non-smooth paths (+ signatures).

- Solution of SDE is continuous map of Brownian motion and Lévy area.
- Given processes  $W^n$  s.t.  $S(W^n) \rightarrow S(B)$ , we have strong convergence of the solutions of SDEs. E.g., Wong-Zakai theorem.

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Approximation	า			

- For Continuity, only m = 2 needed, but higher order signature gives better approximation
- Assume a grid  $0 = t_0 < t_1 < \cdots < t_n = T$  and a piecewise smooth process *W* on the grid such that  $S^m(W)_{t_i,t_{i+1}} = S^m(B)_{t_i,t_{i+1}}.$
- Approximation:  $|I(W) I(B)| \le (\sup_i \Delta t_i)^{(m+1-p)/p}, 2$

- Requires sampling of Lévy area.
- Cubature on Wiener space: Weak version of this result.

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# Path-dependent functionals (B. and Friz)

Let *f* be a continuous functional on paths. Goal: Compute  $E[f(X_{\cdot})]$  using cubature on Wiener space.

- ► Consider a grid 0 = t<sub>0</sub> < ··· < t<sub>n</sub> = T and a cubature formula W on the grid.
- By a Donsker theorem for processes with Hölder paths in the Heisenberg group, S<sup>2</sup>(W)<sub>0,</sub>. converges weakly to S<sup>2</sup>(B)<sub>0,</sub>.
- By the universal limit theorem, this implies convergence

$$\mathbb{E}\left[f(\widetilde{X}_{\cdot})\right] \to \mathbb{E}\left[f(X_{\cdot})\right]$$

when sup  $\Delta t_i \rightarrow 0$ .

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## The Ninomiya-Victoir method

- ► On a (uniform) grid  $0 = t_0 < \cdots < t_n = T$  set  $\Delta t_i \coloneqq t_{i+1} t_i$ ,  $\Delta B_i^j \coloneqq B_{t_{i+1}}^j - B_{t_i}^j$ ,  $\Lambda_i$  Bernoulli-distributed
- Set  $\overline{X}_0 = x$  and iteratively

$$\overline{X}_{i+1} \coloneqq \begin{cases} e^{\frac{\Delta t_i}{2} V_0} e^{\Delta B_i^d V_d} \cdots e^{\Delta B_i^1 V_1} e^{\frac{\Delta t_i}{2} V_0} \overline{X}_i, & \Lambda_i = 1, \\ e^{\frac{\Delta t_i}{2} V_0} e^{\Delta B_i^1 V_1} \cdots e^{\Delta B_i^d V_d} e^{\frac{\Delta t_i}{2} V_0} \overline{X}_i, & \Lambda_i = -1. \end{cases}$$
(3)

- $e^{sV_i}x \coloneqq z(1)$ , where  $\dot{z}(t) = sV_i(z(t))$ , z(0) = x
- Global error:  $E[f(X_T)] E[f(\overline{X}_n)] = O((\sup \Delta t_i)^2)$
- Interpretation as cubature method and splitting method

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- Set  $\overline{X}_0 = x$  and iteratively

$$\overline{X}_{i+1} \coloneqq \begin{cases} e^{\frac{\Delta t_i}{2} V_0} e^{\Delta B_i^d V_d} \cdots e^{\Delta B_i^1 V_1} e^{\frac{\Delta t_i}{2} V_0} \overline{X}_i, & \Lambda_i = 1, \\ e^{\frac{\Delta t_i}{2} V_0} e^{\Delta B_i^1 V_1} \cdots e^{\Delta B_i^d V_d} e^{\frac{\Delta t_i}{2} V_0} \overline{X}_i, & \Lambda_i = -1. \end{cases}$$
(3)

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- Interpretation as cubature method and splitting method

$$Q_{\Delta t}^{NV} = \frac{1}{2} e^{\frac{\Delta t}{2}L_0} e^{\Delta tL_1} \cdots e^{\Delta tL_d} e^{\frac{\Delta t}{2}L_0} + \frac{1}{2} e^{\frac{\Delta t}{2}L_0} e^{\Delta tL_d} \cdots e^{\Delta tL_1} e^{\frac{\Delta t}{2}L_0},$$

where  $L_0 f(x) = V_0 f(x)$ ,  $L_i f(x) = \frac{1}{2} V_i^2 f(x)$ ,  $Q_{\Delta t}^{NV} \approx P_{\Delta t} \coloneqq e^{\Delta t L_0 + \Delta t \sum_{i=1}^d L_i}$ 

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# Applicability in finance (B., Friz and Loeffen)

 Very advantageous when all ODEs can be solved explicitly (otherwise: can use high order Runge-Kutta schemes).

#### Example (Generalized SABR model)

$$dX_t^1 = a \left(X_t^2\right)^{\alpha} \left(X_t^1\right)^{\beta} dB_t^1,$$
  

$$dX_t^2 = \kappa(\theta - X_t^2) dt + bX_t^2(\rho dB_t^1 + \sqrt{1 - \rho^2} dB_t^2),$$
  
here  $1/2 \le \alpha, \beta \le 1$ . (SABR:  $\alpha = 1, \kappa = 0$ .)

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## Example: Generalized SABR model – continued

► Drift trick: choose  $\gamma \in \mathbb{R}^d$ , set  $V_0^{(\gamma)}(x) \coloneqq V_0(x) - \sum_{i=1}^d \gamma^i V_i(x)$ and consider

$$dX_t = V_0^{(\gamma)}(X_t)dt + \sum_{i=1}^d V_i(X_t) \circ d\left(B_t^i + \gamma^i t\right)$$

• Apply N-V-scheme for vector fields  $V_0^{(\gamma)}$ ,  $V_1$ ,...,  $V_d$  with  $\Delta B_j^i$  replaced by  $\Delta B_j^i + \gamma^i \Delta t$ 

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## Generalized SABR – Numerical experiment



Number of timesteps

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## Generalized SABR – Computational time

Method	K	М	Rel. Error	Time
Euler	32	8192000	0.00174	91.94 sec
Ninomiya-Victoir	4	2048000	0.00204	13.93 sec
NV with drift	4	1024000	0.00104	2.88 sec

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# Multi-Level Monte Carlo (Giles)

- Systematic variance reduction technique
- $\overline{X}_T^{(n)} \approx X_T$  based on a uniform grid with size *n*.
- Idea:

Use \$\overline{X}\_T^{(n/2)}\$ as control variate for \$\overline{X}\_T^{(n)}\$; requires computation of \$E[\overline{X}\_T^{(n/2)}]\$ with high accuracy.
 Use \$\overline{X}\_T^{(n/4)}\$ as control variate for \$\overline{X}\_T^{(n/2)}\$;

- Optimal: Work at each level is equal, i.e., the finer the grid, the fewer samples need to be simulated.
- Time discretization error depends on finest grid, (Monte Carlo) integration error on coarsest grid (with most samples).

#### Example

Euler method: complexity reduced from  $O(\epsilon^{-3})$  to  $O(\epsilon^{-2}(\log \epsilon)^2)$ .

Rough paths and cubature

The Ninomiya-Victoir method

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# Multi-Level Monte Carlo (Giles)

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## Error control

#### Idea

Want to use a fine grid only when/where quantity of interest is sensitive.

- Need some computable error control
- A priori error estimates: require no/little additional computations, but are very crude.
- A posteriori estimates: possibly substantial additional work, but accurate error control.
- Computable a posteriori estimates available following Talay and Tubaro

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# Adaptivity following Szepessy et al

## (Stochastic) Control problem

Minimize (expected) work subject to the error (estimate) being smaller than TOL.

Control variable: grid

- Deterministic control problem: leads to non-uniform, deterministic grid
- Stochastic control problem: leads to non-uniform, random grid

#### Stochastic Algorithm

- Start with coarse grid, compute error estimate
- Where necessary, refine grid, and iterate
- Refinement requires some bridging procedure

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