



On the viscoelastodynamic problem with Signorini boundary conditions

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Mathematics for key technologies



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- 1 Mathematical model
- 2 Existence result
- 3 The trace spaces
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The dynamical evolution system for Kelvin-Voigt material is

$$\rho u_{tt} = Au + Bu_t + f, \quad x \in \Omega, \quad t > 0$$

The boundary conditions are given by

$$\sigma_T^A + (\sigma_T^B)_t = 0,$$

$$\sigma_N^A + (\sigma_N^B)_t \geq 0, \quad u_N \geq 0, \quad u_N(\sigma_N^A + (\sigma_N^B)_t) = 0$$

Notations: Let $C = A$ or $C = B$

▷ σ_N^C : the normal component of the stress vector at the boundary

▷ σ_T^C : the tangential component of the stress vector at the boundary

Assumptions: the material is **homogeneous** and **isotropic**



State variables

$u : [0, T] \times \Omega \rightarrow \mathbb{R}$ displacement

Applied field

$\ell : [0, T] \times \Omega \rightarrow \mathbb{R}$ density forces

Notations:

- ▷ $\Omega = (-\infty, 0)$
- ▷ $K = \{v \in H^1_{loc}(\Omega \times [0, \infty)) : v_{xt} \in L^2_{loc}([0, \infty); L^2(\Omega)), v(0, \cdot) \geq 0\}$

We consider the following problem (DI):

$$u_{tt} - u_{xx} - \alpha u_{xt} = \ell, \quad \alpha > 0$$

damped wave equation

$$0 \leq u(0, t) \perp (u_x + \alpha u_{xt})(0, t) \geq 0$$

unilateral bdry conditions

$$u(\cdot, 0) = u_0 \quad \text{and} \quad u_t(\cdot, 0) = u_1$$

Cauchy initial data



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$$u_{tt} - u_{xx} - \alpha u_{xxt} = \underbrace{\ell}_{\in L^2_{loc}([0, \infty); L^2(\Omega))}, \quad \alpha > 0 \quad \text{damped wave equation}$$

$$0 \leq u(0, t) \perp (u_x + \alpha u_{xt})(0, t) \geq 0 \quad \text{unilateral bdry conditions}$$

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The weak formulation **(VI)** is given by

Find $u \in K$ such that for all $v \in K$ and for all $\tau \in (0, \infty)$, we have

$$\begin{aligned} & \int_{\Omega} (u_t(v - u))|_0^\tau dx - \int_0^\tau \int_{\Omega} u_t(v_t - u_t) dx dt \\ & + \int_0^\tau \int_{\Omega} (u_x + \alpha u_{xt})(v_x - u_x) dx dt \geq \int_0^\tau \int_{\Omega} \ell(v - u) dx dt \end{aligned}$$



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**Penalized Problem (PP)** (here $r^- = -\min(r, 0)$)

$$u_{tt}^\epsilon - u_{xx}^\epsilon - \alpha u_{xxt}^\epsilon = \ell, \quad \alpha > 0 \quad \text{damped wave equation}$$

$$(u_x^\epsilon + \alpha u_{xt}^\epsilon)(0, t) = \frac{1}{\epsilon}(u^\epsilon(0, t))^- \quad \text{normal compliance conditions}^1$$

$$u^\epsilon(\cdot, 0) = u_0 \quad \text{and} \quad u_t^\epsilon(\cdot, 0) = u_1 \quad \text{Cauchy initial data}$$

¹Martins, Oden. *Nonlinear Anal.*, 1988.

²Jarušek. *Czechoslovak Math. J.*, 1996.

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Theorem (Existence and uniqueness results²)

There exists a unique weak solution $u^\epsilon \in H_{loc}^1([0, \infty) \times \Omega)$ of the problem (PP) such that $u_{xt}^\epsilon \in L^2_{loc}([0, \infty); L^2(\Omega))$.

Idea of the proof: Use Galerkin method.

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Theorem (Existence result)

There exists a solution of (VI); this solution can be obtained as a limit of a subsequence of (PP).

Sketch of the proof: A-priori estimates give us

- ▷ $u^\epsilon \in L^\infty_{loc}([0, \infty); L^2(\Omega))$
- ▷ $u_t^\epsilon \in L^\infty_{loc}([0, \infty); L^2(\Omega))$
- ▷ $u_x^\epsilon \in L^\infty_{loc}([0, \infty); L^2(\Omega))$
- ▷ $u_{xt}^\epsilon \in L^2_{loc}([0, \infty); L^2(\Omega))$
- ▷ $u_{xx}^\epsilon \in L^\infty_{loc}([0, \infty); L^2(\Omega))$

Moreover $u_t \in C^0([0, \infty); L^2(\Omega))$ equipped with the weak topology.



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There exists a solution of (VI); this solution can be obtained as a limit of a subsequence of (PP).

Sketch of the proof: A-priori estimates enable to pass to the limit in the variational formulation associated to the penalized problem

$$\begin{aligned} & \int_{\Omega} u_t^\epsilon \varphi(v - u^\epsilon) \Big|_0^\tau dx - \int_0^\tau \int_{\Omega} u_t^\epsilon (\varphi(v - u^\epsilon))_t dx dt \\ & - \frac{1}{\epsilon} \int_0^\tau (((u^\epsilon(0, \cdot))^-) \varphi)^2 dt - \frac{1}{\epsilon} \int_0^\tau ((u^\epsilon(0, \cdot))^-\varphi v) dt \\ & + \int_0^\tau \int_{\Omega} (u_x^\epsilon + \alpha u_{xt}^\epsilon)(\varphi(v_x - u_x^\epsilon)) dx dt = \int_0^\tau \int_{\Omega} \ell \varphi(v - u^\epsilon) dx dt \end{aligned}$$

where $\varphi \in C_0^\infty(\bar{\Omega} \times [0, \infty))$ taken its values in $[0, 1]$.



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where $\varphi \in C_0^\infty(\bar{\Omega} \times [0, \infty))$ taken its values in $[0, 1]$.

Remark: Nothing is known about uniqueness.



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AIM: Characterize the trace spaces

Recall that $u(0, t) \in H_{\text{loc}}^a([0, \infty))$ for $a \in \mathbb{R}$

$$\Updownarrow \\ |\omega|^a \hat{u}(0, \omega) \in L^2(\mathbb{R})$$

- ▷ ω : the dual variable of t
- ▷ $\hat{u}(0, \omega)$: the Fourier transform of $u(0, t)$

Theorem (Regularity of the trace³)

Let u^ϵ be the solution of (PP). Then we may extract a subsequence, still denoted by u^ϵ , such that

$$u^\epsilon(0, t) \rightharpoonup u(0, t) \quad \text{weakly in } H_{\text{loc}}^{5/4}([0, \infty)).$$

Moreover u is a strong solution of (DI).

³P., Schatzman. *C. R. Math. Acad. Sci.*, 2002.



Sketch of the proof:

- ▷ Introduce \bar{u} solution of **(DI)** with the **Dirichlet boundary conditions**



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- ▷ Introduce \bar{u} solution of **(DI)** with the **Dirichlet boundary conditions**
- ▷ Let $v^\epsilon = u^\epsilon - \bar{u}$ be a solution of

$$v_{tt}^\epsilon - (1+\alpha\partial_t)v_{xx}^\epsilon = 0, \quad x \in \Omega, \quad t > 0$$

$$(1+\alpha\partial_t)v_x^\epsilon(0, t) = \bar{g} + \frac{1}{\epsilon}(v^\epsilon(0, t))^- \quad \text{where} \quad \bar{g} = -(\bar{u}_x + \alpha\bar{u}_{xt})(0, t)$$

$$v^\epsilon(\cdot, 0) = 0 \quad \text{and} \quad v_t^\epsilon(\cdot, 0) = 0$$



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$$v^\epsilon(\cdot, 0) = 0 \quad \text{and} \quad v_t^\epsilon(\cdot, 0) = 0$$

- ▷ Use the **Fourier transform** in t

$$\hat{v}_{xx}^\epsilon(x, \omega) = \hat{\lambda}^2 \hat{v}^\epsilon(x, \omega) \quad \text{where} \quad \hat{\lambda} = \frac{i\omega}{\sqrt{1+i\alpha\omega}}$$

$$\rightsquigarrow \hat{v}^\epsilon(x, \omega) = \hat{a}^\epsilon e^{\hat{\lambda}x}$$



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- ▷ Use the boundary conditions

$$((1 + \alpha \partial_t) v_x^\epsilon)(0, \omega) = \hat{\lambda}_1 \hat{v}^\epsilon(0, \omega) \quad \text{where} \quad \hat{\lambda}_1 = (1 + i\alpha\omega)\hat{\lambda}$$

$$\rightsquigarrow \lambda_1 * v^\epsilon(0, t) = \bar{g} + \frac{1}{\epsilon} (v^\epsilon(0, t))^-$$



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The energy balance is obtained by multiplying **(DI)** by u_t and integrating over $\Omega \times (0, \tau)$, i.e.

$$\begin{aligned} & \frac{1}{2} \int_{\Omega} (|u_t|^2 + |u_x|^2) \Big|_0^\tau dx + \alpha \int_0^\tau \int_{\Omega} |u_{xt}|^2 dx dt \\ &= \int_0^\tau \int_{\Omega} \ell u_t dx dt + \int_0^\tau (u_x + \alpha u_{xt})(0, t) u_t(0, t) dt \end{aligned}$$

The energy losses are purely viscous iff $\int_0^\tau (u_x + \alpha u_{xt})(0, t) u_t(0, t) dt = 0$.

- ▷ $u_t(0, t) = 0$ a.e. on $\text{supp}((u_x + \alpha u_{xt})(0, t))$
- ▷ $(u_x + \alpha u_{xt})(0, t)$ is only a measure
- ⇏ $\int_0^\tau (u_x + \alpha u_{xt})(0, t) u_t(0, t) dt = 0$

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The energy losses are purely viscous iff $\int_0^\tau (u_x^\epsilon + \alpha u_{xt}^\epsilon)(0, t) u_t^\epsilon(0, t) dt = 0$.

- ▷ $u_t^\epsilon(0, t) \in H_{loc}^{1/4}(0, \infty)$
- ▷ $(u_x^\epsilon + \alpha u_{xt}^\epsilon)(0, t) \in H_{loc}^{-1/4}(0, \infty)$
- ⇏ $\int_0^\tau (u_x^\epsilon + \alpha u_{xt}^\epsilon)(0, t) u_t^\epsilon(0, t) dt = 0$



(DI) is reduced to pseudodifferential linear complementarity pb (**LCP**)

$$\lambda_1 * w(t) = \bar{g} + b, \quad 0 \leq w(t) \perp b \geq 0 \quad \text{with} \quad w(t) = v(0, t)$$

Assumptions & Notations: let $\sigma_j, \tau_j : 0 \leq \sigma_0 < \tau_0 < \sigma_1 < \tau_1 \dots$

- ▷ $\text{supp } w \subset \bigcup_j [\sigma_j, \tau_j]$ and $\text{supp } b \subset \bigcup_j [\tau_j, \sigma_{j+1}]$
- ▷ $\bar{g} = \mu * \phi$, ϕ is a measure, $\mu = (\pi t)^{-1/2}$
- ▷ $\omega = \frac{H(t)}{\pi(t+1)\sqrt{t}}$ and $\nu = \frac{H(t)e^{-t/\alpha}}{\alpha}$ with H : Heaviside function
- ▷ $\phi_0 = \phi$ and $\phi_{j+1} = 1_{[\sigma_{j+1}, \infty)}(\phi_j + \int_{[\tau_j, \sigma_{j+1}]} e^{-(\cdot-s)/\alpha} \omega(\frac{\cdot-\sigma_{j+1}}{\sigma_{j+1}-s}) \frac{\psi_j(s)}{\sigma_{j+1}-s}$
with $\psi_j = \phi_j 1_{[\tau_j, \sigma_{j+1}]} + \delta(\cdot - \tau_j) e^{-\tau_j/\alpha} \int_{[\sigma_j, \tau_j]} e^{s/\alpha} \phi_j$

Then w is given by

$$w 1_{[\sigma_j, \tau_j]} = (H * \nu * \phi_j) 1_{[\sigma_j, \tau_j]}$$



We do not know if for a given $\bar{g} = \mu * \phi$, there is a solution of **(LCP)** having a locally finite structure \Rightarrow construction of w^n satisfying **(ALCP)**, i.e.

$$\lambda_1 * w^n(t) = \bar{g}^n + b^n, \quad 0 \leq w^n(t) \perp b^n \geq 0$$

A-priori estimates **(ALCP)** imply that there exists a subsequence s.t.

- ▷ $w^n \rightarrow w$ uniformly on compact sets and $w_t^n \rightharpoonup w_t$ in $L^\infty(0, T)$ weakly *
- ▷ $b^n \rightharpoonup b$ in $\mathcal{M}^1(0, T)$ weakly *
- ▷ w and b satisfy **(LCP)**

In particular, w_t is essentially bounded $\Rightarrow b$ has no atoms.

Theorem

Let N be the set of atoms of ϕ , $N_1 = \cup_j \{\sigma_j, \tau_j\}$, $U = \{t \in \mathbb{R} : w(t) > 0\}$.
 Then for all $t \notin N \cup N_1 \cup U$, w is differentiable at t with $w_t(t) = 0$.

$\Rightarrow \langle w_t, b \rangle = 0 \Rightarrow$ the energy losses are purely viscous.



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- ▷ Study the same problems with Signorini boundary conditions **distributed over the surface**



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Thank you for your attention !

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