



Some mathematical results for a model of thermally-induced phase transformation in shape-memory materials

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Mathematics for key technologies

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Previous works:

- ▷ The model for average of the transformation strain
 - ▶ Souza, Mamiya & Zouain'98, Auricchio & Petrini'04
 - ▶ Mielke'07, Mielke & P.'07, Auricchio, Mielke & Stefanelli'08
- ▷ The model for each pure phase independently
 - ▶ Mielke, Theil & Levitas'02, Govindjee, Mielke & Hall'02, Kružík, Mielke & Roubíček'05
- ▷ The energetic formulation theory of rate-independent systems
 - ▶ Mielke & Theil'04, Mielke'05



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We consider a body with reference configuration $\Omega \subset \mathbb{R}^d$.

- ▷ $u : \Omega \rightarrow \mathbb{R}^d$: the **phase transformation** and **deformations**
- ▷ $z : \Omega \rightarrow Z := \text{conv}\{e_1, \dots, e_N\}$: the **internal variable**

The **potential energy** has the following form:

$$\mathcal{E}(t, u, z) := \int_{\Omega} \left(W(e(u), z, \theta) + \frac{\sigma}{2} |\nabla z|^2 \right) dx - \langle l(t), u \rangle,$$

- ▷ W : the stored energy density depends on $e(u)$, z , θ
 - ▶ $e(u) := \frac{1}{2}(\nabla u + \nabla u^T)$: the linearized deformation θ : the temperature
- ▷ $\sigma > 0$: measures some nonlocal interaction effect for z
- ▷ $l(t)$: the applied mechanical loading

The **dissipation potential** is defined by

$$\mathcal{D}(z_1, z_2) = \int_{\Omega} \psi(x, z_2 - z_1) dx,$$

- ▷ $\psi(x, \cdot)$: convex, l.s.c., positively homogeneous of degree **1** for a.e. $x \in \Omega$

Assumptions

- ▶ We do not solve an associated **heat equation**, i.e. $\theta = \theta_{\text{appl}}(t, x)$ is given
 - ▶ This approximation used in engineering models:
 - ▶ the changes of the loading are slow
 - ▶ the body is small in at least one direction
 - ⇒ excess heat can be transported very fast to the surface
 - ▶ Examples: the wires
- ▶ $u = u_{\text{Dir}}(t)$ on $\Gamma_{\text{Dir}} \subset \partial\Omega$

Notations: the set $\mathcal{Q} := \mathcal{F} \times \mathcal{Z}$ where

- ▶ $\mathcal{F} := \{\tilde{u} \in H^1(\Omega; \mathbb{R}^d) \mid \tilde{u}|_{\Gamma_{\text{Dir}}} = 0\}$: the set of admissible displacements
- ▶ $\mathcal{Z} := \{z \in H^1(\Omega; \mathbb{R}^N) \mid z(x) \in Z \text{ a.e. } x \in \Omega\}$: the set where lies the internal variable

Assumption: Initial data $(u(0), z(0)) = (u_0, z_0) \in \mathcal{F} \times \mathcal{Z}$ are given.

Energetic formulation: (Theil & Mielke'04, Mielke'05)

A function $q := (\tilde{u} = u - u_{\text{Dir}}(t), z) : [0, T] \rightarrow \mathcal{Q}$ is an *energetic solution* of the rate-independent problem associated with \mathcal{E} and \mathcal{D} if for all $(s, t) \in [0, T]^2$, the *global stability condition* (S) and the *global energy conservation* (E) are satisfied, i.e.

$$(S) \quad \forall \bar{q} = (\bar{u}, \bar{z}) \in \mathcal{Q} : \tilde{\mathcal{E}}(t, q(t)) \leq \tilde{\mathcal{E}}(t, \bar{q}) + \mathcal{D}(z(t), \bar{z}),$$

$$(E) \quad \tilde{\mathcal{E}}(t, q(t)) + \text{Var}_{\mathcal{D}}(z; [0, t]) = \tilde{\mathcal{E}}(0, q(0)) + \int_0^t \partial_s \tilde{\mathcal{E}}(s, q(s)) ds,$$

with $\tilde{\mathcal{E}}(t, q(t)) := \mathcal{E}(t, \tilde{u}(t) + u_{\text{Dir}}(t), z(t), \theta_{\text{appl}}(t))$,

$$\text{Var}_{\mathcal{D}}(z; [r, s]) := \sup \left\{ \sum_{j=1}^p \mathcal{D}(z(t_{j-1}), z(t_j)) \mid p \in \mathbb{N}, r \leq t_0 < \dots < t_p \leq s \right\}.$$



Remark: (S) is equivalent to

$$q(t) \in \mathcal{S}(t) := \{q \in \mathcal{Q} \mid \forall \bar{q} \in \mathcal{Q} : \tilde{\mathcal{E}}(t, q) \leq \tilde{\mathcal{E}}(t, \bar{q}) + \mathcal{D}(z, \bar{z})\}$$

for all $t \in [0, T]$.



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Notations:

- ▷ \mathcal{F}_h, V_h : closed subspaces resp. of \mathcal{F} and $V := H^1(\Omega; \mathbb{R}^N)$
- ▷ $\mathcal{Q}_h := \mathcal{F}_h \times \mathcal{Z}_h$ and $\mathcal{Z}_h = \{z_h \in V_h \mid z_h(x) \in Z \text{ a.e. in } \Omega\} := \mathcal{Z} \cap V_h$
- ▷ $\Pi^\tau := \{0 = t_0^\tau < t_1^\tau < \dots < t_{k^\tau}^\tau = T\}$: a partition with $\tau \in (0, T)$ and $t_k^\tau - t_{k-1}^\tau \leq \tau$ for $k = 1, \dots, k^\tau$

Assumptions:

- ▷ $\forall q = (\tilde{u}, z) \in \mathcal{Q} \quad \exists (q_h)_{h>0} : q_h = (\tilde{u}_h, z_h) \in \mathcal{Q}_h$ and $q_h \rightarrow q$ strongly in \mathcal{Q}
- ▷ the initial condition q_0 is approximated by $[q_0]^h \in \mathcal{Q}_h$

One has to solve the following **incremental problems**:

$$(\text{IP})^{\tau, h} \begin{cases} \text{for } k = 1, \dots, k^\tau \text{ find} \\ q_k^{\tau, h} \in \text{Argmin}\{\tilde{\mathcal{E}}(t_k^\tau, \hat{q}^h) + \mathcal{D}(z_{k-1}^{\tau, h}, \hat{z}^h) \mid \hat{q}^h \in \mathcal{Q}_h\}, \end{cases}$$

where $q_k^{\tau, h} := (\tilde{u}_k^{\tau, h}, z_k^{\tau, h})$ and $\hat{q}^h := (\hat{u}^h, \hat{z}^h)$.



Assumptions:

- ▷ $\theta_{\text{appl}} \in C^1([0, T]; L^\infty(\Omega; [\theta_{\min}, \theta_{\max}]))$, $l \in C^1([0, T]; (H^1(\Omega; \mathbb{R}^d))')$
- ▷ $u_{\text{Dir}} \in C^1([0, T]; H^1(\Omega; \mathbb{R}^d))$
- ▷ $\forall v \in \mathbb{R}_0^N \quad \exists c_\psi, C_\psi > 0 : c_\psi |v|_1 \leq \psi(x, v) \leq C_\psi |v|_1$ with $|v|_1 := \sum_{j=1}^N |v_j|$
- ▷ $W \in C^0(\mathbb{R}_{\text{sym}}^{d \times d} \times Z \times [\theta_{\min}, \theta_{\max}]; \mathbb{R})$ is strictly convex $\forall (z, \theta) \in Z \times [\theta_{\min}, \theta_{\max}]$
- ▷ $\forall (e, z, \theta) \in \mathbb{R}_{\text{sym}}^{d \times d} \times Z \times [\theta_{\min}, \theta_{\max}] \quad \exists c, C > 0 :$
$$c(|e|^2 + |z|^2) - C \leq W(e, z, \theta) \leq c(|e|^2 + |z|^2) + C$$

Proposition 1. The following properties hold:

- (i) \mathcal{D} is continuous for the weak topology of $H^1(\Omega)$
- (ii) for all $t \in [0, T]$, $\tilde{\mathcal{E}}(t, \cdot)$ has weakly compact sublevels
- (iii) $\forall (t, q) \in [0, T] \times \mathcal{Q} \quad \exists C, c > 0 : C \|q\|_{\mathcal{Q}}^2 - c \leq \tilde{\mathcal{E}}(t, q) \leq C \|q\|_{\mathcal{Q}}^2 + c$



The incremental problems $(IP)_\Pi^h$ admit a solution $(q_k^{\tau,h})_{1 \leq k \leq k^\tau}$, we have

$$\begin{aligned} \forall \bar{q}^{\tau,h} \in \mathcal{Q}_h : \tilde{\mathcal{E}}(t_k^\tau, q_k^{\tau,h}) &\leq \tilde{\mathcal{E}}(t_k^\tau, \bar{q}^{\tau,h}) + \mathcal{D}(z_{k-1}^{\tau,h}, \bar{z}^{\tau,h}) - \mathcal{D}(z_{k-1}^{\tau,h}, z_k^{\tau,h}) \\ &\leq \tilde{\mathcal{E}}(t_k^\tau, \bar{q}^{\tau,h}) + \mathcal{D}(z_k^{\tau,h}, \bar{z}^{\tau,h}), \end{aligned}$$

i.e. $q_k^{\tau,h} \in \mathcal{S}_h(t_k^\tau) = \{q^h \in \mathcal{Q}_h \mid \bar{q}^h \in \mathcal{Q}_h : \tilde{\mathcal{E}}(t, q^h) \leq \tilde{\mathcal{E}}(t, \bar{q}^h) + \mathcal{D}(z^h, \bar{z}^h)\}$.

Assumptions:

- ▷ $\partial_\theta W \in C^0(\mathbb{R}_{\text{sym}}^{d \times d} \times Z \times [\theta_{\min}, \theta_{\max}]; \mathbb{R})$
- ▷ $\partial_e W \in C^0(\mathbb{R}_{\text{sym}}^{d \times d} \times Z \times [\theta_{\min}, \theta_{\max}]; \mathbb{R}_{\text{sym}}^{d \times d})$

Then for all $1 \leq k \leq k^\tau$ (**discrete upper energy inequality**)

$$\tilde{\mathcal{E}}(t_k^\tau, q_k^{\tau,h}) - \tilde{\mathcal{E}}(t_{k-1}^\tau, q_{k-1}^{\tau,h}) + \mathcal{D}(z_{k-1}^{\tau,h}, z_k^{\tau,h}) \leq \int_{t_{k-1}^\tau}^{t_k^\tau} \partial_t \tilde{\mathcal{E}}(t, q_{k-1}^{\tau,h}) dt,$$

and for all $2 \leq k \leq k^\tau$ (**discrete lower energy inequality**)

$$\tilde{\mathcal{E}}(t_k^\tau, q_k^{\tau,h}) - \tilde{\mathcal{E}}(t_{k-1}^\tau, q_{k-1}^{\tau,h}) + \mathcal{D}(z_{k-1}^{\tau,h}, z_k^{\tau,h}) \geq \int_{t_{k-1}^\tau}^{t_k^\tau} \partial_t \tilde{\mathcal{E}}(t, q_k^{\tau,h}) dt.$$



We define now the approximate solution $\bar{q}^{\tau,h} : [0, T] \rightarrow \mathcal{Q}$ as the **right-continuous piecewise constant** approximation, namely

$$\bar{q}^{\tau,h}(t) := \begin{cases} q_{k-1}^{\tau,h} & \text{for } t_{k-1}^{\tau} \leq t < t_k^{\tau}, k = 1, \dots, k^{\tau}, \\ q_{k^{\tau}}^{\tau,h} & \text{for } t = T. \end{cases}$$

Goal: investigate the asymptotics as $h \rightarrow 0$ and $\tau \rightarrow 0$.

Assumptions on W : There exist positive constants $C_0^W, C_1^W, C^\theta, C_0^\theta, C_1^\theta, C^e, C_0^e, C_1^e$ and a nondecreasing function $\omega : [0, \infty) \rightarrow [0, \infty)$ with $\lim_{\tau \rightarrow 0^+} \omega(\tau) = 0$ such that for all $e, e_1, e_2 \in \mathbb{R}_{\text{sym}}^{d \times d}$, $z, z_1, z_2 \in Z$ and $\theta, \theta_1, \theta_2 \in [\theta_{\min}, \theta_{\max}]$, we have

$$|\partial_e W(e, z, \theta)|^2 + |\partial_\theta W(e, z, \theta)| \leq C_1^W (W(e, z, \theta) + C_0^W),$$

$$|\partial_\theta W(e, z, \theta_1) - \partial_\theta W(e, z, \theta_2)| \leq C_1^\theta (W(e, z, \theta_1) + C_0^\theta) \omega(|\theta_1 - \theta_2|),$$

$$|\partial_e W(e, z, \theta_1) - \partial_e W(e, z, \theta_2)|^2 \leq C_1^e (W(e, z, \theta_1) + C_0^e) \omega(|\theta_1 - \theta_2|),$$

$$|\partial_\theta W(e_1, z_1, \theta) - \partial_\theta W(e_2, z_2, \theta)| \leq C^\theta (|e_1 - e_2| + |z_1 - z_2|)(1 + |e_1 + e_2| + |z_1 + z_2|),$$

$$|\partial_e W(e_1, z_1, \theta) - \partial_e W(e_2, z_2, \theta)| \leq C^e (|e_1 - e_2| + |z_1 - z_2|).$$



Proposition 2. We have

(P1) Let $q = (\tilde{u}, z) \in \mathcal{Q}$. Then $\tilde{\mathcal{E}}(\cdot, q)$ lies in $C^1([0, T])$ and

$$\begin{aligned}\partial_t \tilde{\mathcal{E}}(t, q) &= \int_{\Omega} \partial_e W(e(u + u_{\text{Dir}}(t)), z, \theta_{\text{appl}}(t)) e(\dot{u}_{\text{Dir}}(t)) \, dx \\ &\quad + \int_{\Omega} \partial_{\theta} W(e(u + u_{\text{Dir}}(t)), z, \theta_{\text{appl}}(t)) \dot{\theta}_{\text{appl}}(t) \, dx - \langle \dot{l}(t), u \rangle.\end{aligned}$$

(P2) There exist $C_0^{\mathcal{E}}, C_1^{\mathcal{E}} > 0$ such that

$$\forall (t, q) \in [0, T] \times \mathcal{Q} : |\partial_t \tilde{\mathcal{E}}(t, q)| \leq C_1^{\mathcal{E}} (\tilde{\mathcal{E}}(t, q) + C_0^{\mathcal{E}}).$$

(P3) For each $\varepsilon > 0$ and $E \in \mathbb{R}$ there exists $\delta > 0$ such that for all $(s, t, q) \in [0, T]^2 \times \mathcal{Q}$ with $\tilde{\mathcal{E}}(0, q) \leq E$ and $|s - t| < \delta$ we have

$$|\partial_t \tilde{\mathcal{E}}(s, q) - \partial_t \tilde{\mathcal{E}}(t, q)| \leq \varepsilon.$$



Notations: For all $k \in \{0, \dots, k^\tau\}$ and for all $t \in [0, T]$:

- ▷ $\bar{\eta}^{\tau, h}(t) := \mathcal{E}(t, \bar{q}^{\tau, h}(t))$, $\eta_0^h := \mathcal{E}(0, [q_0]^h)$ and $\bar{\delta}^{\tau, h}(t) := \text{Var}_{\mathcal{D}}(\bar{z}^{\tau, h}; [0, t])$,
- ▷ $\eta_k^{\tau, h} := \mathcal{E}(t_k^\tau, q_k^{\tau, h})$ and $\delta_k^{\tau, h} := \mathcal{D}(z_{k-1}^{\tau, h}, z_k^{\tau, h})$.

Step 1: A priori estimates

Lemma 1. $\|\bar{q}^{\tau, h}(t)\|_{\mathcal{Q}}$, $|\bar{\eta}^{\tau, h}(t)|$, $|\partial_t \tilde{\mathcal{E}}(t, \bar{q}^{\tau, h}(t))|$, $\text{Var}(\bar{\eta}^{\tau, h}; [0, t])$ and $|\bar{\delta}^{\tau, h}(t)|$ are bounded independently of τ , h and t .



Step 2. Selection of subsequences

Proposition 3. (Helly's selection principle) Assume that

$$\left. \begin{array}{l} \forall (z, \tilde{z}) \in \mathcal{Z}^2, \forall (z^h, \tilde{z}^h) \in \mathcal{Z}_h^2 : \\ z = \lim_{h \rightarrow 0} z^h \text{ and } \tilde{z} = \lim_{h \rightarrow 0} \tilde{z}^h \end{array} \right\} \Rightarrow \mathcal{D}(z, \tilde{z}) \leq \liminf_{h \rightarrow 0} \mathcal{D}(z^h, \tilde{z}^h),$$

$$\left. \begin{array}{l} \forall z \in \mathcal{Z}, \forall K \subset \mathcal{Z} \text{ sequentially compact}, \forall (z_n)_{n \in \mathbb{N}} \in K^{\mathbb{N}} : \\ \min(\mathcal{D}(z_n, z), \mathcal{D}(z, z_n)) \rightarrow 0 \text{ for } n \rightarrow \infty \end{array} \right\} \Rightarrow z = \lim_{n \rightarrow \infty} z_n.$$

Let $(z_n)_{n \in \mathbb{N}}$ be a sequence such that

$$\exists C > 0 \forall n \in \mathbb{N} : \text{Var}_{\mathcal{D}}(z_n; [0, T]) \leq C,$$

$$\exists K \subset \mathcal{Z} \text{ sequentially compact } \forall n \in \mathbb{N} \forall t \in [0, T] : z_n(t) \in K.$$

Then, there exists $(z_{n_j})_{j \in \mathbb{N}}$, a nondecreasing function $\delta : [0, T] \rightarrow \mathbb{R}$, and $z : [0, T] \rightarrow \mathcal{Z}$ such that for all $(s, t) \in [0, T]^2$ with $s \leq t$

$$z(t) = \lim_{j \rightarrow \infty} z_{n_j}(t), \quad \delta(t) = \lim_{j \rightarrow \infty} \text{Var}_{\mathcal{D}}(z_{n_j}; [0, t]), \quad \text{Var}_{\mathcal{D}}(z; [s, t]) \leq \delta(t) - \delta(s).$$



Assumptions on $\psi \Rightarrow \mathcal{D}$ satisfies the properties given in Proposition 1 with Lemma 1 \Rightarrow there exists a subsequence $(\tau_n, h_n)_{n \in \mathbb{N}}$ such that for all $(s, t) \in [0, T]^2$, $s \leq t$:

$$\bar{\eta}^{\tau_n, h_n}(t) \rightarrow \eta(t), \quad \bar{\delta}^{\tau_n, h_n}(t) \rightarrow \delta(t), \quad \bar{z}^{\tau_n, h_n}(t) \rightarrow z(t) \text{ in } \mathcal{Z},$$

$$\text{Var}_{\mathcal{D}}(z; [s, t]) \leq \delta(t) - \delta(s), \quad \partial_t \mathcal{E}(\cdot, \bar{q}^{\tau_n, h_n}) \rightharpoonup \xi_* \text{ weakly } * \text{ in } L^\infty([0, T]).$$

with $\eta \in \text{BV}([0, T]; \mathbb{R})$, $\delta : [0, T] \rightarrow \mathbb{R}$ a non decreasing function, $z : [0, T] \rightarrow \mathcal{Z}$.

Step 3: Stability of the limit process.

Since $\|\bar{q}^{\tau, h}(t)\|_{\mathcal{Q}}$ is bounded independently of τ and h , there exists a subsequence $(n_j^t)_{j \in \mathbb{N}}$ (depending on t) such that

$$\bar{q}^{\tau_{n_j^t}, h_{n_j^t}}(t) \rightharpoonup q(t) \text{ weakly in } \mathcal{Q},$$

and thus $q(t) = (\tilde{u}(t), z(t))$.

Lemma 2. We have

$$q(t) \in \mathcal{S}(t) = \{q \in \mathcal{Q} \mid \forall \bar{q} \in \mathcal{Q} : \tilde{\mathcal{E}}(t, q) \leq \tilde{\mathcal{E}}(t, \bar{q}) + \mathcal{D}(z, \bar{z})\}.$$



Sketch of the proof. Let $\bar{q} \in \mathcal{Q}$ and define

$$t_j = \max \left\{ t_k^{\tau_{n_j^t}, h_{n_j^t}} \leq t, k = 0, \dots, k_{\tau_{n_j^t}} \right\}.$$

We have $\lim_{j \rightarrow \infty} t_j = t$ and $\bar{q}^{\tau_{n_j^t}, h_{n_j^t}}(t) \in \mathcal{S}_{h_{n_j^t}}(t_j)$.

Using (P1), we have

$$\begin{aligned} \tilde{\mathcal{E}}(t, \bar{q}^{\tau_{n_j^t}, h_{n_j^t}}(t)) &\leq \exp(C_1^\mathcal{E} |t - t_j|) \tilde{\mathcal{E}}(t_j, \bar{q}^{\tau_{n_j^t}, h_{n_j^t}}(t)) + C_0^\mathcal{E} (\exp(C_1^\mathcal{E} |t - t_j|) - 1) \\ &\leq \exp(C_1^\mathcal{E} |t - t_j|) (\tilde{\mathcal{E}}(t_j, q^{h_{n_j^t}}) + \mathcal{D}(\bar{z}^{\tau_{n_j^t}, h_{n_j^t}}(t), z^{h_{n_j^t}})) + C_0^\mathcal{E} (\exp(C_1^\mathcal{E} |t - t_j|) - 1) \end{aligned}$$

for all $q^{h_{n_j^t}} \in \mathcal{Q}_{h_{n_j^t}}$. Then, we choose $(q^{h_{n_j^t}})_{j \in \mathbb{N}}$ such that $q^{h_{n_j^t}} \rightarrow \bar{q}$ in \mathcal{Q} and we

pass to the limit. As a consequence $\tilde{u}(t) \in \text{Argmin} \{ \tilde{\mathcal{E}}(t, \tilde{u}, z(t)) \mid \tilde{u} \in \mathcal{F} \}$.

Since $\tilde{\mathcal{E}}(t, \cdot, z(t))$ is strictly convex, the whole sequence $(\bar{u}^{\tau_{n_j^t}, h_{n_j^t}}(t))_{n_j^t \in \mathbb{N}}$ converges weakly in \mathcal{Q} .

So we have defined a limit process $q \in L^\infty([0, T]; \mathcal{Q})$ which satisfies the global stability property.



Step 4: Upper energy estimate

With the discrete upper energy estimate and step 1, there exists $C > 0$ such that

$$\bar{\eta}^{\tau,h}(t) + \bar{\delta}^{\tau,h}(t) \leq \eta_0^h + \int_0^t \partial_t \tilde{\mathcal{E}}(s, \bar{q}^{\tau,h}(s)) ds + C(\exp(C_1^\mathcal{E} \tau) - 1)$$

for all $t \in [0, T]$, for all τ and h , which yields at the limit

$$\forall t \in [0, T] : \eta(t) + \text{Var}_{\mathcal{D}}(q; [0, t]) \leq \eta(t) + \delta(t) \leq \eta(0) + \int_0^t \xi_*(s) ds.$$

Lemma 3. For all $t \in [0, T]$:

$$\lim_{n \rightarrow \infty} \tilde{\mathcal{E}}(t, \bar{q}^{\tau_n, h_n}(t)) = \eta(t) = \tilde{\mathcal{E}}(t, q(t)),$$

$$\lim_{n \rightarrow \infty} \partial_t \tilde{\mathcal{E}}(t, \bar{q}^{\tau_n, h_n}(t)) = \partial_t \tilde{\mathcal{E}}(t, q(t)).$$



Sketch of the proof. Since $\tilde{\mathcal{E}}(t, \cdot)$ is l.s.c., we have

$$\tilde{\mathcal{E}}(t, q(t)) \leq \liminf_{n \rightarrow \infty} \tilde{\mathcal{E}}(t, \bar{q}^{\tau_n, h_n}(t)) = \liminf_{n \rightarrow \infty} \bar{\eta}^{\tau_n, h_n}(t) = \eta(t).$$

But $\bar{q}^{\tau_n, h_n}(t) \in \mathcal{S}_{h_n}(t_j)$ and with the same computations as in step 2 with $\bar{q}^{\tau_n, h_n} \rightarrow q(t)$ in \mathcal{Q} , we get

$$\eta(t) = \limsup_{n \rightarrow \infty} \tilde{\mathcal{E}}(t, \bar{q}^{\tau_n, h_n}(t)) \leq \tilde{\mathcal{E}}(t, q(t)) + \mathcal{D}(z(t), z(t)) = \tilde{\mathcal{E}}(t, q(t)),$$

and thus $\lim_{n \rightarrow \infty} \tilde{\mathcal{E}}(t, \bar{q}^{\tau_n, h_n}(t)) = \eta(t) = \tilde{\mathcal{E}}(t, q(t))$. Then, using (P2), we find

$$\lim_{n \rightarrow \infty} \partial_t \tilde{\mathcal{E}}(t, \bar{q}^{\tau_n, h_n}(t)) = \partial_t \tilde{\mathcal{E}}(t, q(t)).$$

**Step 5: Lower energy estimate.****Notations:**

- ▷ $\Pi^n := \{0 = t_0^n < t_1^n < \dots < t_{N_n}^n = t\}$: a sequence of partitions of $[0, t]$, such that $\lim_{n \rightarrow \infty} \Delta(\Pi^n) = 0$ and

$$\int_0^t \partial_t \tilde{\mathcal{E}}(\sigma, q(\sigma)) d\sigma = \lim_{n \rightarrow \infty} \sum_{j=1}^{N_n} \partial_t \tilde{\mathcal{E}}(t_j^n, q(t_j^n))(t_j^n - t_{j-1}^n).$$

- ▷ $\mu_j^n := \int_{t_{j-1}^n}^{t_j^n} (\partial_t \tilde{\mathcal{E}}(s, q(t_j^n)) - \partial_t \tilde{\mathcal{E}}(t_j^n, q(t_j^n))) ds$

We have $q(t_{j-1}^n) \in \mathcal{S}(t_{j-1}^n)$. Choosing $\bar{q} = (\tilde{u}(t_j^n), z(t_j^n))$, we obtain

$$\tilde{\mathcal{E}}(t_j^n, q(t_j^n)) - \tilde{\mathcal{E}}(t_{j-1}^n, q(t_{j-1}^n)) + \mathcal{D}(q(t_{j-1}^n), q(t_j^n)) \geq \int_{t_{j-1}^n}^{t_j^n} \partial_t \tilde{\mathcal{E}}(s, q(t_j^n)) ds$$

and after summation over j

$$\tilde{\mathcal{E}}(t, q(t)) - \tilde{\mathcal{E}}(0, q(0)) + \text{Var}_{\mathcal{D}}(q; [0, t]) \geq \sum_{j=1}^{N_n} \partial_t \tilde{\mathcal{E}}(t_j^n, q(t_j^n))(t_j^n - t_{j-1}^n) + \sum_{j=1}^{N_n} \mu_j^n,$$



Notice that

$$|\mu_j^n| \leq (t_j^n - t_{j-1}^n) \omega_E(\Delta(\Pi^n))$$

with $\lim_{\rho \rightarrow 0} \omega_E(\rho) = 0$.

Then passing to the limit as $\Delta(\Pi^n)$ tends to zero, we get

$$\tilde{\mathcal{E}}(t, q(t)) - \tilde{\mathcal{E}}(0, q(0)) + \text{Var}_{\mathcal{D}}(q; [0, t]) \geq \int_0^t \partial_t \tilde{\mathcal{E}}(s, q(s)) ds.$$

Finally we have

$$\begin{aligned} & \tilde{\mathcal{E}}(0, q(0)) + \int_0^t \partial_t \tilde{\mathcal{E}}(s, q(s)) ds \\ & \leq \tilde{\mathcal{E}}(t, q(t)) + \text{Var}_{\mathcal{D}}(q; [0, t]) \leq \eta(t) + \delta(t) \leq \tilde{\mathcal{E}}(0, q(0)) + \int_0^t \xi_*(s) ds, \end{aligned}$$

and $\xi_* = \partial_t \tilde{\mathcal{E}}(\cdot, q)$ a.e. in $[0, T]$. Hence all the inequalities are in fact equalities, thus

$$\forall t \in [0, T] : \delta(t) = \text{Var}_{\mathcal{D}}(q; [0, t]).$$

and

$$\partial_t \tilde{\mathcal{E}}(\cdot, \bar{q}^{\tau_n, h_n}) \rightarrow \partial_t \tilde{\mathcal{E}}(\cdot, q) \text{ strongly in } L^1([0, T]).$$



Assumption: Let $[q_0]^h \in \mathcal{Q}_h$ be such that $[q_0]^h \rightarrow q_0$ in \mathcal{Q} .

Theorem 1 (Convergence of the approximate solutions). There exist a subsequence $(\tau_n, h_n)_{n \in \mathbb{N}}$ tending to $(0, 0)$ and an energetic solution $q = (\tilde{u}, z) : [0, T] \rightarrow \mathcal{Q}$ of (S) and (E) such that $q(0) = q_0$,

$$\tilde{u} \in L^\infty([0, T]; H^1(\Omega; \mathbb{R}^d)),$$

$$z \in L^\infty([0, T]; H^1(\Omega; Z)) \cap BV([0, T]; L^1(\Omega; Z)),$$

and, for all $t \in [0, T]$, the following convergences hold:

$$\bar{q}^{\tau_n, h_n}(t) \rightarrow q(t) \text{ strongly in } \mathcal{Q},$$

$$\tilde{\mathcal{E}}(t, \bar{q}^{\tau_n, h_n}(t)) \rightarrow \tilde{\mathcal{E}}(t, q(t)),$$

$$\text{Var}_{\mathcal{D}}(\bar{z}^{\tau_n, h_n}; [0, t]) \rightarrow \text{Var}_{\mathcal{D}}(z; [0, t]),$$

$$\partial_t \tilde{\mathcal{E}}(\cdot, \bar{q}^{\tau_n, h_n}) \rightarrow \partial_t \tilde{\mathcal{E}}(\cdot, q) \text{ strongly in } L^1([0, T]).$$



- 1 Introduction
- 2 Mathematical formulation
- 3 Convergence of the space-time discretization
- 4 Temporal regularity via uniform convexity**

**Assumption:**

▷ W is α_W -uniformly convex in its first two arguments

Proposition 3. q is Lipschitz continuous.

Sketch of the proof. The uniform convexity of W implies that there exists $\kappa > 0$ such that $(t, q_1, q_2) \in [0, T] \times (\mathcal{F} \times V)^2$:

$$\frac{\kappa}{2} \|q_2 - q_1\|_{\mathcal{Q}}^2 \leq \tilde{\mathcal{E}}(t, q_2) - \tilde{\mathcal{E}}(t, q_1) - \langle D_q \tilde{\mathcal{E}}(t, q_1), q_2 - q_1 \rangle.$$

On the other hand, (S) implies

$$(S)_{\text{loc}} \quad \forall s \in [0, T], \forall v = (\tilde{u}, z) \in \mathcal{Q} : \langle D_q \tilde{\mathcal{E}}(s), v - q(s) \rangle + \mathcal{D}(z(s), z) \geq 0.$$

So, with $q_1 = q(s)$, $q_2 = q(t)$, $0 \leq s \leq t \leq T$

$$\begin{aligned} \frac{\kappa}{2} \|q(t) - q(s)\|_{\mathcal{Q}}^2 &\leq \tilde{\mathcal{E}}(s, q(t)) - \tilde{\mathcal{E}}(s, q(s)) + \text{Var}_{\mathcal{D}}(z; s, t) \\ &= - \int_s^t \partial_r \tilde{\mathcal{E}}(r, q(t)) dr + \int_s^t \partial_r \tilde{\mathcal{E}}(r, q(r)) dr \leq C \int_s^t \|q(r) - q(t)\|_{\mathcal{Q}} dr. \end{aligned}$$

Then we infer that $\|q(t) - q(s)\|_{\mathcal{Q}} \leq \frac{2C}{\kappa}(t - s)$