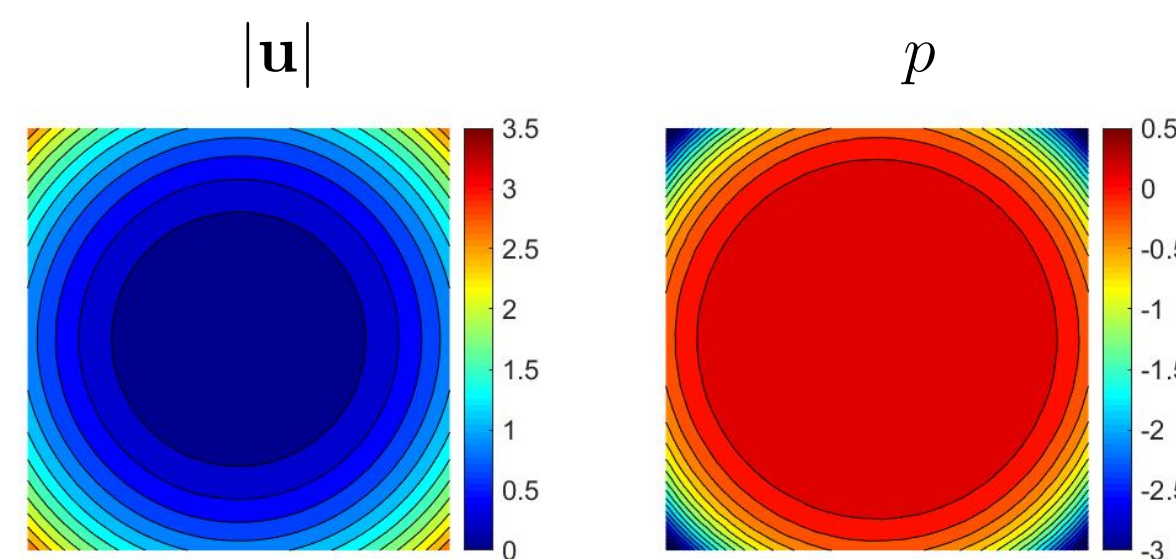


Navier-Stokes Equations

$$\mathbf{u}_t - \nu \Delta \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} + 2\Omega \times \mathbf{u} + \nabla p = \mathbf{f}$$

$$\nabla \cdot \mathbf{u} = 0$$



Stabilisation at Work

$$-\nu \Delta \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} + \nabla p = \mathbf{0}, \quad \nabla \cdot \mathbf{u} = 0$$

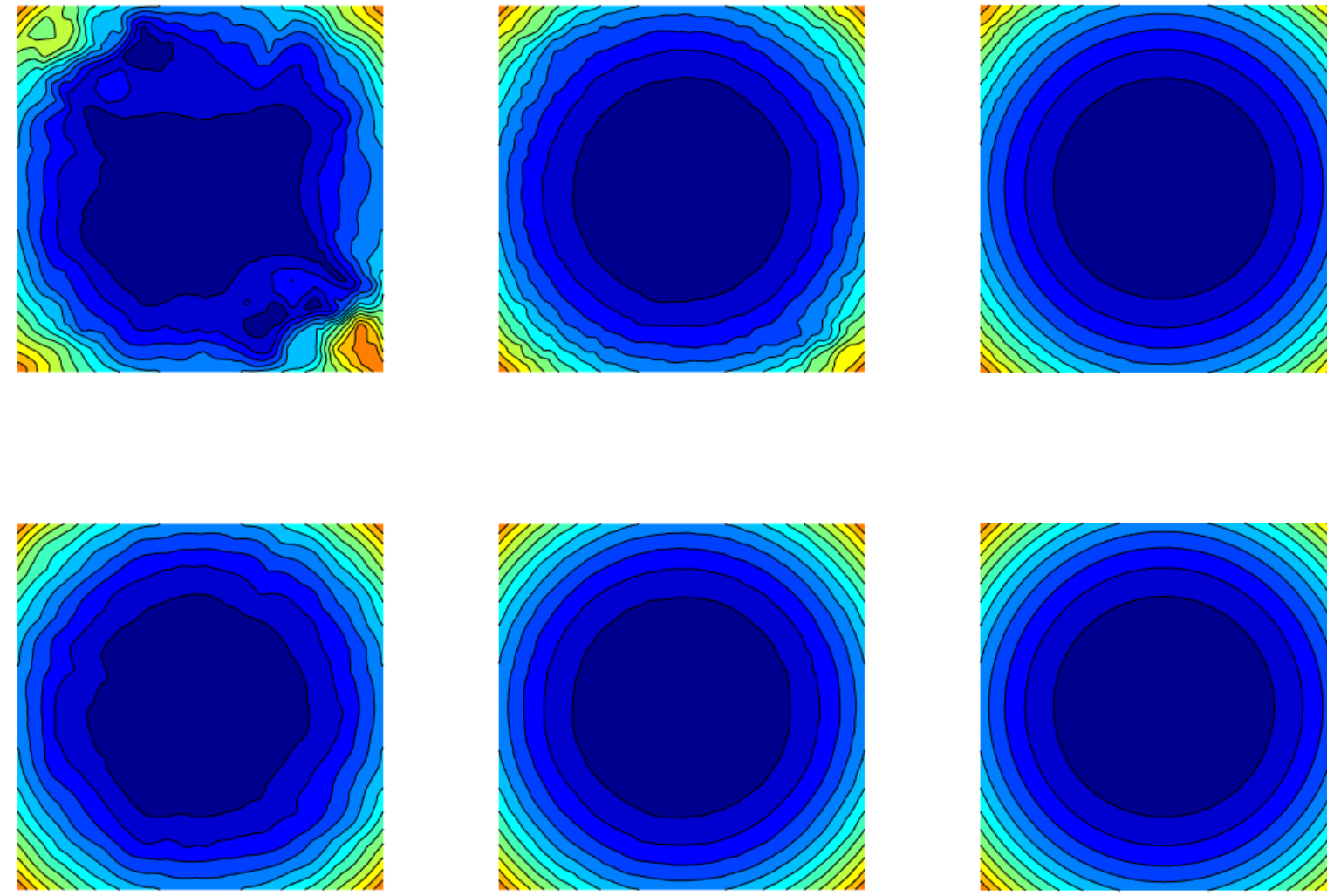
$$\nu = 10^{-2}, \quad \mathbf{u} = \nabla h, \quad h = x^3 y - y^3 x$$

Classical solver:

- Bernardi–Raugel FEM
- spurious velocity oscillations

Stabilised solver:

- stab. Bernardi–Raugel FEM
- pressure-robust velocity



Stabilised Solver

Modifies test functions in:

- exterior force \mathbf{f}
- convection term $(\mathbf{u}_h \cdot \nabla) \mathbf{u}_h$
- Coriolis force $2\Omega \times \mathbf{u}_h$
- discrete time derivative $\dot{\mathbf{u}}_h$

Main properties:

- universal approach (FEM, FV, DG, ...)
- works on unstructured grids
- no artificial diffusion

A Continuous L^2 Orthogonality

$X := H_0^1(D; \mathbb{R}^d)$: velocity space

$Q := L^2(D)$: pressure space

$V_0 := \{v \in X : \nabla \cdot v = 0\}$: divergence-free vectorfields

$L_\sigma^2(D) := \{v \in L^2(D; \mathbb{R}^d) : \nabla \cdot v = 0, v \cdot \mathbf{n} = 0 \text{ along } \partial D\}$

Divergence:

$$\text{div} : X \rightarrow Q, \quad v \mapsto \nabla \cdot v \quad \text{lin., bd. \& surj. (inf-sup stable)}$$

$$(\nabla \varphi, v) = -(\varphi, \nabla \cdot v) \quad \text{for all } (v, \varphi) \in X \times H^1(D)$$

L^2 orthogonality:

$$\forall (v, q) \in V_0 \times H^1 : \quad (\nabla \varphi, v) = 0$$

Helmholtz decomposition:

$\mathbf{f} \in L^2(D; \mathbb{R}^d)$ can be decomposed into

$$\mathbf{f} = \nabla \varphi + \mathbf{w} \quad \text{with } \varphi \in H^1(D) \text{ and } \mathbf{w} \in L_\sigma^2(D)$$

Helmholtz projector:

$$\mathbb{P}(\mathbf{f}) = \mathbb{P}(\nabla \varphi + \mathbf{w}) := \mathbf{w} = \underset{\beta \in V_0}{\text{argmin}} \|f - \beta\|_{L^2(D)}$$

$$\|\mathbb{P}(\nabla \varphi)\|_{V_0^*} = 0$$

Repairing the Discrete L^2 Orthogonality and the Divergence-Free Momentum Balance

$X_h \subset X$: discrete velocity space

$Q_h \subset Q$: discrete pressure space

$V_{0,h} := \{v_h \in X_h : \nabla_h \cdot v_h = 0\}$: discretely divergence-free vectorfields

Discrete divergence:

$$\text{div}_h : X_h \rightarrow Q_h, \quad v_h \mapsto \nabla_h \cdot v_h := \pi_{Q_h}(\nabla \cdot v_h) \quad \text{inf-sup stable}$$

$$\forall (v_h, q) \in X_h \times H^1(D) : \quad (\nabla \varphi, v_h) = -(\varphi, \nabla \cdot v_h) \neq -(\varphi, \nabla_h \cdot v_h)$$

Incomplete L^2 orthogonality:

$$\forall (v_h, q_h) \in V_{0,h} \times Q_h : \quad (q_h, \nabla_h \cdot v_h) = 0$$

Reconstruction operator:

$$\pi : X_h \rightarrow H(\text{div}, D) \quad \text{such that } \nabla \cdot (\pi V_{0,h}) \equiv 0 \quad \text{and}$$

$$\forall (v_h, q) \in X_h \times H^1(D) : \quad (\nabla \varphi, \pi v_h) = -(\varphi, \nabla \cdot (\pi v_h)) = -(\varphi, \nabla_h \cdot (\pi v_h))$$

Discrete Helmholtz projectors:

classical	stabilised
$\mathbb{P}_h(\mathbf{f}) := \underset{\beta_h \in V_{0,h}}{\text{argmin}} \ f - \beta_h\ _{L^2(D)}$	$\mathbb{P}_h^*(\mathbf{f}) := \underset{\pi \beta_h \in \pi(V_{0,h})}{\text{argmin}} \ f - \pi \beta_h\ _{L^2(D)}$
$\ \mathbb{P}_h(\nabla \varphi)\ _{V_{0,h}^*} \leq \min_{q_h \in Q_h} \ \varphi - q_h\ _{L^2(D)}$	$\ \mathbb{P}_h^*(\nabla \varphi)\ _{V_{0,h}^*} = 0$
$\mathbb{P}_h(\mathbf{f}) = \mathbb{P}_h(\mathbb{P}\mathbf{f}) + \mathbb{P}_h(\nabla \varphi)$	$\Rightarrow \forall v_h \in V_{0,h} : (\mathbf{f}, \pi v_h) = (\mathbb{P}\mathbf{f}, \pi v_h)$

Stabilisation by Variational Crime

Seek $\mathbf{u}_h \in V_{0,h}$ (plus appropriate boundary conditions) such that for all $\mathbf{v}_h \in V_{0,h}$

Classical solver:

$$(\dot{\mathbf{u}}_h, \mathbf{v}_h) + (\nu \nabla \mathbf{u}_h, \nabla \mathbf{v}_h) + ((\mathbf{u}_h \cdot \nabla) \mathbf{u}_h, \mathbf{v}_h) + ((\mathbf{u}_h \cdot \nabla) \mathbf{u}_h, \mathbf{v}_h) + (2\Omega \times \mathbf{u}_h, \mathbf{v}_h) = (\mathbf{f}, \mathbf{v}_h)$$

$$\Downarrow \quad \text{(theoretically)}$$

$$(\mathbb{P}_h(\dot{\mathbf{u}}_h), \mathbf{v}_h) + (\nu \nabla \mathbf{u}_h, \nabla \mathbf{v}_h) + (\mathbb{P}_h((\mathbf{u}_h \cdot \nabla) \mathbf{u}_h), \mathbf{v}_h) + (2\mathbb{P}_h(\Omega \times \mathbf{u}_h), \mathbf{v}_h) = (\mathbb{P}_h(\mathbf{f}), \mathbf{v}_h)$$

Stabilised solver:

$$(\dot{\mathbf{u}}_h, \pi \mathbf{v}_h) + (\nu \nabla \mathbf{u}_h, \nabla \mathbf{v}_h) + ((\mathbf{u}_h \cdot \nabla) \mathbf{u}_h, \pi \mathbf{v}_h) + (2\Omega \times \mathbf{u}_h, \pi \mathbf{v}_h) = (\mathbf{f}, \pi \mathbf{v}_h)$$

$$\Downarrow \quad \text{(theoretically)}$$

$$(\mathbb{P}(\dot{\mathbf{u}}_h), \mathbf{v}_h) + (\nu \nabla \mathbf{u}_h, \nabla \mathbf{v}_h) + (\mathbb{P}((\mathbf{u}_h \cdot \nabla) \mathbf{u}_h), \mathbf{v}_h) + (2\mathbb{P}(\Omega \times \mathbf{u}_h), \pi \mathbf{v}_h) = (\mathbb{P}(\mathbf{f}), \pi \mathbf{v}_h)$$

A Priori Error Estimates for Stokes Equations

$$-\nu \Delta \mathbf{u} + \nabla p = \mathbf{f}, \quad \nabla \cdot \mathbf{u} = 0$$

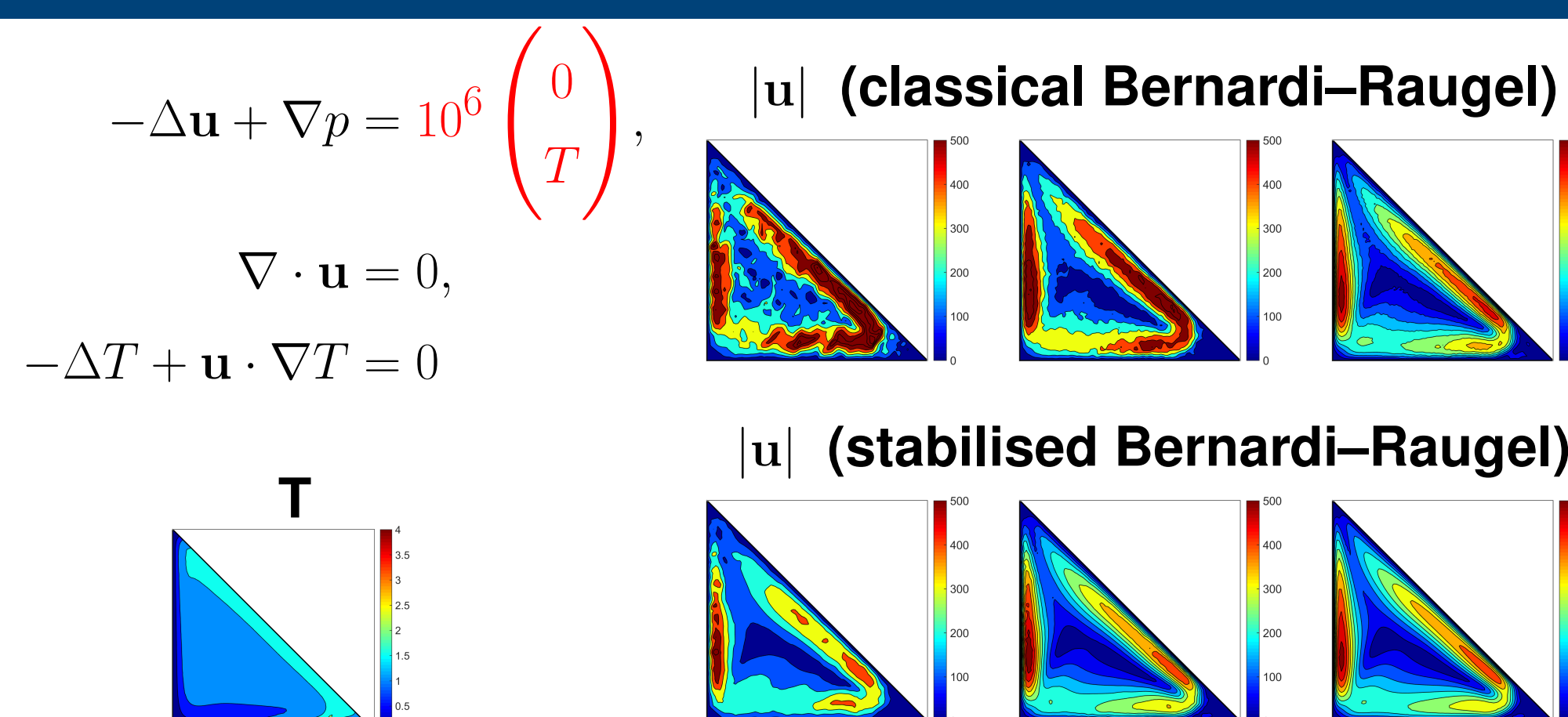
Classical solver:

$$\|\nabla(\mathbf{u} - \mathbf{u}_h)\|_{L^2(D)} \leq C_1 \inf_{\mathbf{v}_h \in V_h} \|\nabla(\mathbf{u} - \mathbf{v}_h)\|_{L^2(D)} + \frac{1}{\nu} \inf_{q_h \in Q_h} \|p - q_h\|_{L^2(D)}$$

Stabilised/Pressure-robust solver:

$$\|\nabla(\mathbf{u} - \mathbf{u}_h)\|_{L^2(D)} \leq C_1 \inf_{\mathbf{v}_h \in V_h} \|\nabla(\mathbf{u} - \mathbf{v}_h)\|_{L^2(D)} + C_2 h^k |\mathbf{u}|_{H^{k+1}(D)}$$

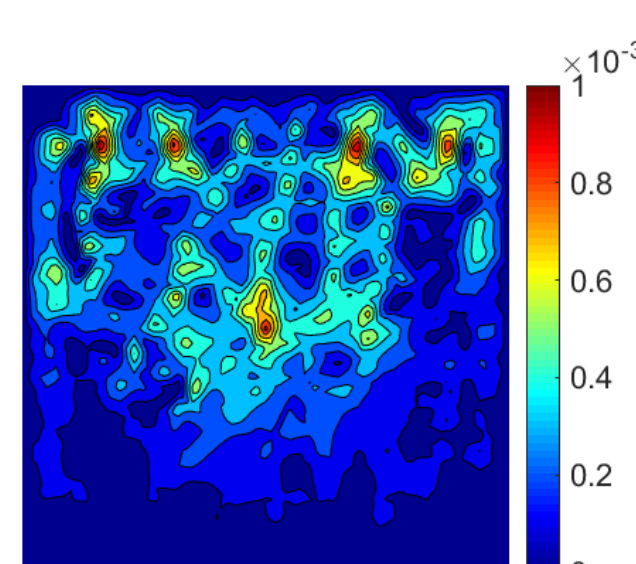
Example: Natural Convection



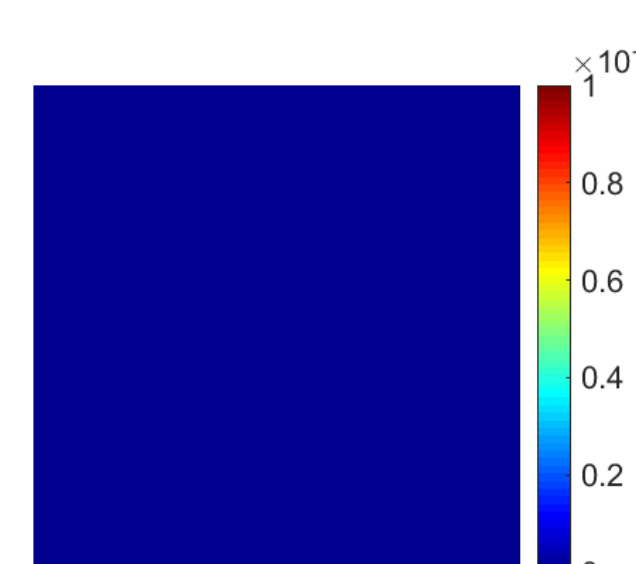
Outlook: Pressure-Robust Solvers & Coriolis Force

$$-\Delta \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} + 2y \mathbf{u}^\perp + \nabla p = \mathbf{0}, \quad \nabla \cdot \mathbf{u} = 0, \quad \mathbf{u} = (1, 0)^T, \quad p = y^2$$

classical Bernardi–Raugel



stabilised Bernardi–Raugel



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