

Cryospheric IBVP's In Support of General Circulation Models Of the Earth's Climate Evolution

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Introduction

1.) Objects

We discuss large ice masses on our planet Earth:

- **Ice Sheets:** Large Ice masses **sitting on solid** ground (rock, soil) also called **Inland Ices**.
Ex: Greenland, Antarctica, Fenno-Scandinavian, Laurentide Ice sheets
 - **Ice Shelves:** (German Schelfeise) Large Ice masses **floating on the ocean or lake water** and being fed by inland ice, called **Grand Barriers** by explorers of the 19-20th centuries
Ex: Ross, Ronne-Filchner Ice Shelves
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- Related examples, Glaciers, Marine ice sheets, ice streams
 - Not treated here is Sea-Ice = Frozen ocean water

2.) Material Behaviour

Cold Ice: This is a non-Newtonian fluid. Power law fluid,

$$\mathbf{D} = A(T)f(II_{\sigma'})\boldsymbol{\sigma}' \quad f(x) = x^{(n-1)/2} \quad n = 3$$

Temperate Ice : (T = melting temperature, everywhere). This is a mixture of class I of a viscous fluid with incorporated water bubbles, which can diffuse through the ice matrix. At the bubble walls melting/freezing processes can occur depending on the frictional heat available through viscous stress power.

$$\mathbf{D} = A(\omega)f(II_{\sigma'})\boldsymbol{\sigma}' \quad f(x) = x^{(n-1)/2} \quad n = 3$$

$$\omega = \text{Water content} = \rho_{\text{water}}/\rho_{\text{mixture}}$$

+ Mass balance for the water, moisture balance equation

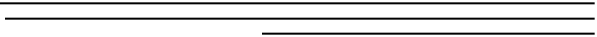
Cold and temperate ice often exist in separate domains of the same ice mass. They are then called **Polythermal Ice Masses**.

The cold and temperate domains are separated by a singular surface, across which the **Stefan condition** between the jump of the water mass flow and jump in heat flow must be related by the latent heat

This surface is called the COLD TEMPERATE TRANSITION SURFACE (CTS)

The moisture flow in such a mixture of class I is **diffusive** with extremely small diffusivity. If this **diffusivity is zero**, then

- Moisture balance equation is **hyperbolic**, not parabolic
- No Stefan condition at CTS, heat flow across CTS is continuous,
- Zero moisture jump across CTS, $[[\rho\omega]] = 0$
- **Some solutions violate observations**



Boundary conditions

- $z = h_s(x, y, t) \quad : \quad T = T_s(x, y, z, t), \quad b_s = b_s(x, y, z, t).$

- $z = h_b(x, y, t) \quad : \quad \kappa_I \frac{\partial T_I}{\partial n} = \kappa_R \frac{\partial T_R}{\partial n}, \quad T_I = T_R < T_M$

$$b_b = \frac{1}{\rho_w L_s} \left(\kappa_I \frac{\partial T_I}{\partial n} - \kappa_R \frac{\partial T_R}{\partial n} + \boldsymbol{\tau}^* \cdot \boldsymbol{v}_{\parallel} \right), \quad T_I = T_R = T_M,$$

$$\boldsymbol{v}_{\parallel} = \begin{cases} C \left(|\boldsymbol{\tau}^*|, p^* \right) \boldsymbol{\tau}^* = c |\boldsymbol{\tau}^*|^{m-1} p^{*-l} \boldsymbol{\tau}^*, & \text{if } T = T_M, \\ 0, & \text{if } T < T_M, \end{cases}$$

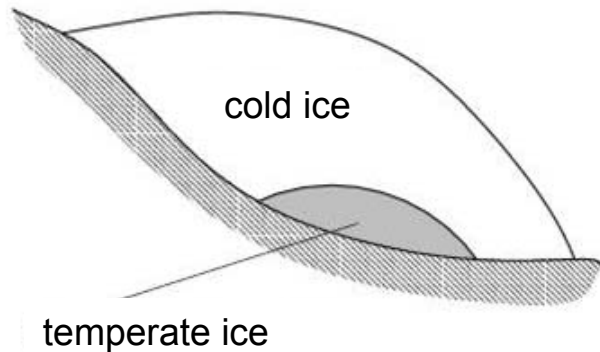
$$\boldsymbol{v}_{\parallel} = - \left(\boldsymbol{v} - (\boldsymbol{v} \cdot \boldsymbol{n}) \boldsymbol{n} \right)$$

$$\boldsymbol{\tau}^* = \left(\boldsymbol{\sigma} - p^* \mathbf{1} \right) \boldsymbol{n}.$$

- $z = h_b(x, y) \quad : \quad \kappa_R \frac{\partial T_R}{\partial z} = -G.$

Constitutive relations of temperate ice in polythermal ice masses

Polythermal ice masses consist of disjoint regions with cold and temperate ice, respectively.



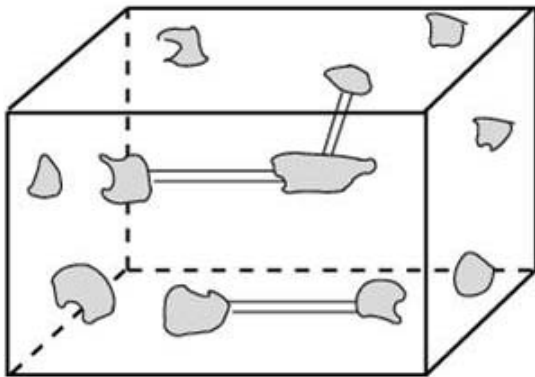
Definition: Temperate ice is a mixture of ice and water inclusions, where both ice and water are at the melting point.

The water inclusions are partly connected along the grain boundaries. Thus, the water can diffusively move, if, however, only very slowly.

Definition: Let ρ_w and ρ be the mass densities for the water and the ice-water mixture. The variable

$$\omega \equiv \rho_w / \rho$$

is called the **moisture content of temperate ice**.



The moisture content in the temperate ice of polythermal ice masses is 3–5 %, no more!

Field equations

mixture mass: $div \mathbf{v} = 0$

water mass:
(moisture content) $\frac{d\omega}{dt} = -div \mathbf{j}_\omega + \zeta_\omega$

mixture momentum: $\rho \frac{d\mathbf{v}}{dt} = div \mathbf{T} + \rho \mathbf{g}$

mixture energy: $\rho \frac{d\varepsilon}{dt} = -div \mathbf{q} + tr(\mathbf{T}\mathbf{D})$

Here ω = moisture content

$\mathbf{j}_\omega$ = $\rho\omega(\mathbf{v}_{\text{water}} - \mathbf{v})$ moisture flux

$\mathbf{T}$ = Cauchy stress of mixture

ε = internal energy of mixture

$\mathbf{q}$ = heat flux of mixture

Postulate: The binary mixture of temperate ice in polythermal ice masses can be treated as a viscous heat conducting Newtonian-Fourier-Fick fluid with Glen-type constitutive relation for the stress.

Thermodynamics then show

$$\begin{aligned}\mathbf{j}_\omega &= -\rho v_\omega \text{grad} \omega, & \text{Fick's first law} \\ \mathbf{q} &= -k(T) \text{grad} T, & \text{Fourier's law} \\ \mathbf{D} &= A(\omega) f(H_{T_b}) \mathbf{T}_D, & \text{Generalized Glen's law}\end{aligned}$$

Remarks:

- The rate factor is now a function of the moisture content and not the temperature (which is given by the Clausius-Clapeyron equation)
- It is assumed that **the free energy or enthalpy does not depend on the moisture content**. Then the **Gibbs relation** reduces to

$$\begin{aligned}d\eta &= \frac{1}{T} \left(d\varepsilon + p d\left(\frac{1}{\rho}\right) \right) & \text{in the interior} \\ [[\eta]]T &= [[\varepsilon]] + p[[1/\rho]] & \text{at phase change surfaces}\end{aligned}$$

and the Clausius-Clapeyron equation becomes

$$\frac{dT}{dp} = -c_M(T) \approx \text{constant}$$

where T is always the freezing/melting temperature. So

$$T - T_0 = -c_M (p - p_0)$$

Expression for the internal energy of temperate ice

Entropy

$$\dot{\eta} = \underbrace{(\eta_{water} - \eta_{ice})}_{\equiv L/T \text{ (latent heat)}} \dot{\omega} = \frac{L}{T} \dot{\omega}$$

Internal energy

$$\dot{\epsilon} = T \dot{\eta} - p \underbrace{\left(\frac{1}{\rho} \right)}_{\approx 0} = L \dot{\omega} = \dot{\epsilon}, \quad \text{we also ignore } \rho \omega \dot{T}$$

Thus, the energy equation becomes

$$\rho L \dot{\omega} = \text{div}(\kappa(T) \text{grad} T) + 2A(\omega) f(H_{TD}) H_{TD}$$

and mass balance reduces to

$$\rho \dot{\omega} = \text{div}(v_{\omega} \text{grad} \omega) + \zeta_{\omega}$$

So: $\rightarrow$

$$\zeta_{\omega} = \frac{1}{L} \{ 2A(\omega) f(H_{TD}) H_{TD} \} + \underbrace{\frac{1}{L} \text{div}(\kappa(T) \text{grad} T) - v_{\omega} \text{div}(\text{grad} \omega)}_{\text{negligible}}$$

$$\zeta_{\omega} = \frac{1}{L} A(\omega) f(H_{TD}) H_{TD}$$

Jump conditions at the CTS

$$[[T]] = 0 \quad (\text{Def. of phase change surface})$$

$$[[\mathbf{v}_{||}]] = 0 \quad (\text{Def. of phase change surface})$$

$$[[\mathcal{M}]] = 0 \rightarrow \mathcal{M} = \rho(\mathbf{v} - \mathbf{w}) \cdot \mathbf{n} \quad (\text{Mass balance})$$

$$[[\mathbf{v}]]\mathcal{M} - [[\mathbf{Tn}]] = 0 \rightarrow [[\mathbf{Tn}]] \approx 0, \quad (\text{Momentum balance})$$

$$[[[-\omega]]]\mathcal{M} + [[[\mathbf{j}_{\omega} \cdot \mathbf{n}]]] = 0 \quad (\text{mass bal. for water})$$

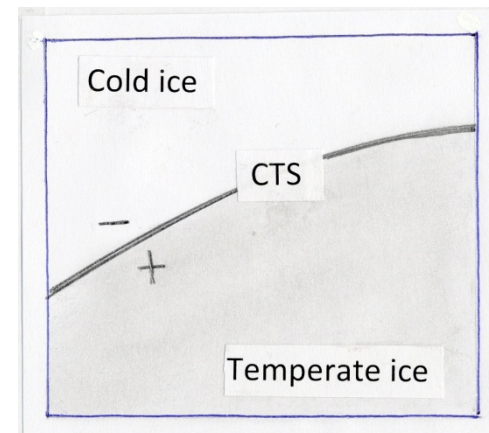
$$[[[\epsilon + (\mathbf{v} \cdot \mathbf{v})/2]]]\mathcal{M} + [[[\mathbf{q} \cdot \mathbf{n}]]] - [[[\mathbf{v}]] \cdot \mathbf{Tn}] = 0 \quad (\text{balance of energy})$$

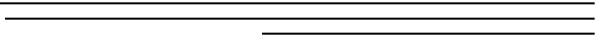
$\approx 0 \qquad \qquad \qquad \approx 0$

$$[[[\epsilon]]]\mathcal{M} + [[[\mathbf{q} \cdot \mathbf{n}]]] \approx 0 \qquad [[[\epsilon]]] = L[[[\omega]]]$$

$$L[[[\omega]]]\mathcal{M} + [[[\mathbf{q} \cdot \mathbf{n}]]] = 0 \quad \Leftrightarrow \quad L[[[\mathbf{j}_{\omega} \cdot \mathbf{n}]]] = [[[\mathbf{q} \cdot \mathbf{n}]]]$$

Stefan Condition





3.) Shallow Ice Approximation for Ice Sheets

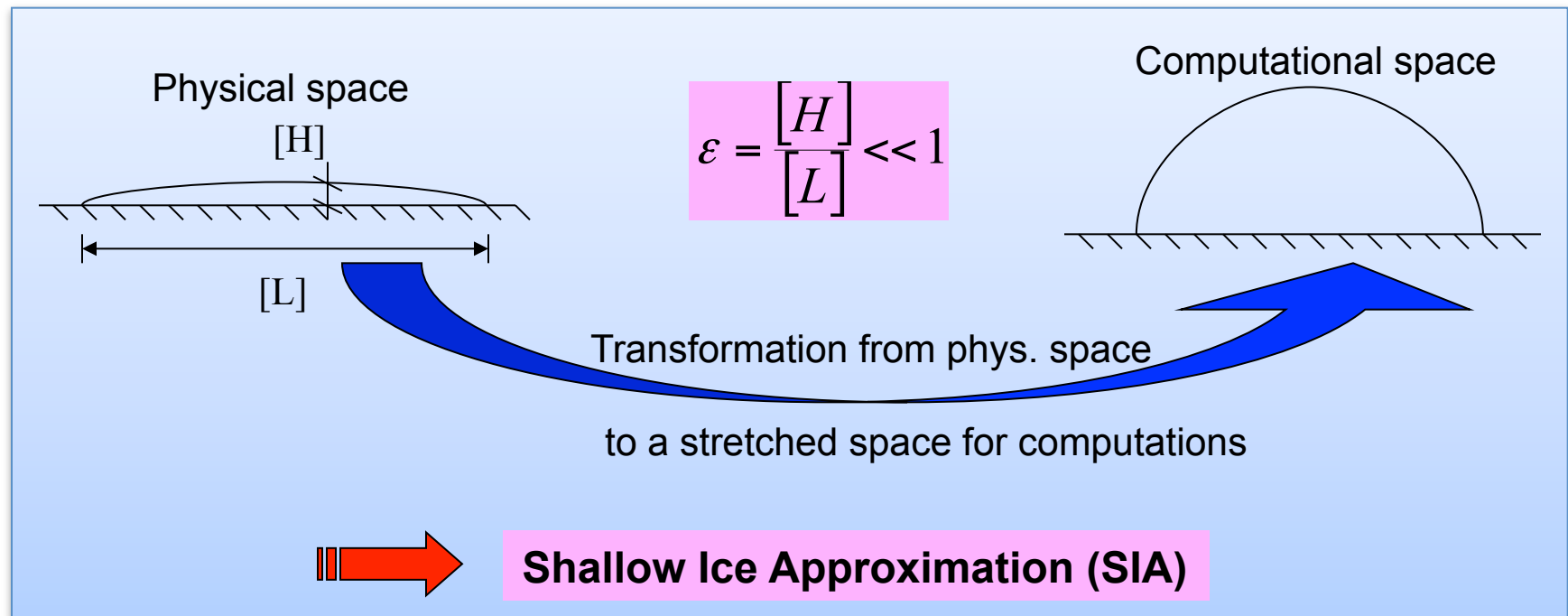
3.1 Motivation

Goal: The boundary value problem governing the evolution of cold or temperate ice in polythermal ice sheets is in its general 3D formulation far too complicated that numerical computations can be performed economically over times spanning one or several Ice Ages.

Simplifications are called for to achieve this.

Fact: Ice sheets and glaciers are shallow but long and wide, **but not always**

Method: Use the small aspect ratio $\varepsilon = (\text{typ. height})/(\text{typ. length}) \ll 1$ to simplify the problem.



3.3 The scaling analysis

- Length**

horizontal	$[L]$	10^5 - 10^6	m
vertical	$[H]$	10^2 - 10^3	m
- Velocities**

horizontal	$[U]$	10^2 - 10^3	m a^{-1}
vertical	$[W]$	1	m a^{-1}
- Stresses**
 (pressure, frictional stresses)

$[\rho g H]$	10^5 - 10^6	Pa
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- Temperature**
 (Temperature range)

$[T]$	273.15°	K
$[\Delta T]$	20 - 30°	K
- Typical stretching**

$[D]=[b]/[H]$	10^{-3} - 10^{-1}	a^{-1} *
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- Typical material stress**

$[\sigma]=\varepsilon[\rho g H]$	10^4 - 10^5	Pa
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*[a] is a typical accumulation rate

$$[H] / [L] = [W] / [U] = \varepsilon \ll 1,$$

$$H_{\sigma'} = [\rho g H] \underset{\uparrow}{\varepsilon}^2 \left\{ \tau_{xz}^{*2} + \tau_{yz}^{*2} + \underset{\uparrow}{\varepsilon}^2 \left[\frac{1}{2} \left(\sigma_x^{*2} + \sigma_y^{*2} + \sigma_z^{*2} \right) + \tau_{xy}^{*2} \right] \right\} = [\rho g H] \underset{\uparrow}{\varepsilon}^2 H^*,$$

$$\begin{array}{ccccccc} \text{↑} & F = \frac{[U^2]}{g[L]}, & \text{↑} & G = \frac{\varepsilon^2}{S_\Sigma D_\Delta}, & S_\Sigma = \frac{[\sigma]}{[\rho g H]}, & D_\Delta = \frac{[W][H]}{[D]}, \end{array}$$

$$D = \frac{[\chi_I]}{\rho c_p} \frac{1}{[WH]}, \quad \mathcal{E} = \frac{A}{S_\Sigma D_\Delta}, \quad A = \frac{g[H]}{c_p [\Delta T]}$$

Dimensionless field equations

$$\frac{\partial u^*}{\partial x^*} + \frac{\partial v^*}{\partial y^*} + \frac{\partial w^*}{\partial z^*} = 0, \quad \leftarrow$$

$$\frac{F}{\varepsilon} \frac{du^*}{dt^*} = -\frac{\partial p^*}{\partial x^*} + \varepsilon^2 \frac{\partial \sigma_x^*}{\partial x^*} + \varepsilon^2 \frac{\partial \tau_{xy}^*}{\partial y^*} + \frac{\partial \tau_{xz}^*}{\partial z^*},$$

$$\frac{F}{\varepsilon} \frac{dv^*}{dt^*} = \varepsilon^2 \frac{\partial \tau_{xy}^*}{\partial x^*} - \frac{\partial p^*}{\partial y^*} + \varepsilon^2 \frac{\partial \sigma_y^*}{\partial y^*} + \frac{\partial \tau_{yz}^*}{\partial z^*},$$

$$F \varepsilon \frac{dw^*}{dt^*} = \varepsilon^2 \left\{ \frac{\partial \tau_{xz}^*}{\partial x^*} + \frac{\partial \tau_{yz}^*}{\partial y^*} \right\} - \frac{\partial p^*}{\partial z^*} + \varepsilon^2 \frac{\partial \sigma_z^*}{\partial z^*} - 1,$$

$$\frac{dT^*}{dt^*} = D \left\{ \varepsilon^2 \nabla_H^* (\chi_I^* \nabla_H^* T^*) + \frac{\partial}{\partial z^*} \left(\chi^* \frac{\partial T^*}{\partial z^*} \right) \right\} + \varepsilon 2 A^* (T^*) f^* (II_{\sigma'}) II_{\sigma'},$$

$$\frac{\partial u^*}{\partial z^*} + \varepsilon^2 \frac{\partial w^*}{\partial x^*} = 2 G A^* (T^*) f^* (II_{\sigma'}) \tau_{xz}^*,$$

$$\frac{\partial v^*}{\partial z^*} + \varepsilon^2 \frac{\partial w^*}{\partial y^*} = 2 G A^* (T^*) f^* (II_{\sigma'}) \tau_{yz}^*,$$

$$\frac{\partial u^*}{\partial x^*} = G A^* (T^*) f^* (II_{\sigma'}) \sigma_x^*,$$

$$\frac{\partial v^*}{\partial y^*} = G A^* (T^*) f^* (II_{\sigma'}) \sigma_y^*,$$

$$\frac{\partial w^*}{\partial z^*} = G A^* (T^*) f^* (II_{\sigma'}) \sigma_z^*,$$

$$\frac{\partial u^*}{\partial y^*} + \frac{\partial v^*}{\partial x^*} = 2 G A^* (T^*) f^* (II_{\sigma'}) \tau_{xy}^*,$$

$$A^* = \exp \left(-\frac{Q}{RT_0} \frac{1}{1 + \frac{[\Delta T]}{T_0}} \right),$$

$$f^* = S II^{*(n-1)/2},$$

$$S = \frac{[\sigma] (\varepsilon [\rho g H])^{n-1}}{A_0}.$$

- Choice of N leads to the order of the approximation

- *Approximation of order zero* ($N=0$)
(All terms of order ε^λ , $\lambda \geq 1$ are ignored)



Classical „Shallow Ice Approximation“

$$\Phi = \Phi_0 \quad (\text{SIA})$$

- *Approximation of order one* ($N=1$)
All terms of order ε^λ , $\lambda \geq 2$ are ignored. This approximation does not change the field equations, but only the boundary conditions under certain limited conditions. No new physics is obtained.

- *Approximation of second order* ($N=2$)
(All terms of order ε^λ , $\lambda \geq 3$ are dropped)



„Second Order Shallow Ice Approximation“

$$\Phi = \Phi_0 + \varepsilon \Phi_1 + \varepsilon^2 \Phi_2 \quad (\text{SOSIA})$$

3.4 Limit Theory: Shallow Ice Approximation (SIA)

Consider the distinguished limit

$$F \rightarrow 0, F/\varepsilon \rightarrow 0, \varepsilon \rightarrow 0 \quad (N=0)$$

Field equations

In the Ice

$$\nabla_H \cdot \mathbf{v}_H + \frac{\partial w}{\partial z} = 0,$$

$$-\frac{\partial p}{\partial x} + \frac{\partial \tau_{xz}}{\partial z} = 0,$$

$$-\frac{\partial p}{\partial y} + \frac{\partial \tau_{yz}}{\partial z} = 0,$$

$$-\frac{\partial p}{\partial z} = \rho g, \quad (\text{cryostatic app.})$$

$$\frac{dT}{dt} = \frac{\partial}{\partial z} \left(\kappa_I \frac{\partial T}{\partial z} \right) + 2EA(T') f(\tau^2) \tau^2,$$

$$\frac{\partial \mathbf{v}_H}{\partial z} = 2EA(T') f(\tau^2) \boldsymbol{\tau} \quad \boldsymbol{\tau} = (\tau_{xz}, \tau_{yz})$$

In the rock bed

$$\dot{T}_R = \frac{\partial}{\partial z} \left(\kappa_R \frac{\partial T_R}{\partial z} \right),$$

Note: E is the so-called **enhancement factor**. It accounts for the fact that pleistocene ice and holocene ice have different fluidities due to different contents of impurities (dust content) and induced anisotropies.

Properties of the SIA-Solutions

- The horizontal projection of the velocity vector at any fixed (x,y) -position has the **direction of steepest descent of the free surface**

$$\mathbf{v}_H(x, y, z, t) = -V_H(x, y, z, t) \nabla_H h_s(x, y, t) \quad \text{Isotropic sliding}$$

This vanishes in the direction of the level lines.

- In any (x,y) -position the direction of the longitudinal velocity component does not change with depth. Its direction is that of the steepest descent of the free surface, for all depths.
- A dome (or a trough) is the location at which the horizontal velocity component vanishes for all depths.
Velocities are always **away from a dome** and **towards a trough**. Thus, a **trough will eventually be filled and disappear**.
- A **ridge is a hydrological ice divide**, since at no depth at a ridge, ice can flow transversely to the ridge.

3.5 Some results from climate computations

Model: SICOPOLIS

- Simple parameterization of the climate input
 - Geothermal heat flow **5 km** below the ice rock interface $Q_{\text{geoth}} = 42\text{--}55 \text{ mW m}^{-2}$
 - Relaxing Lithosphere-Asthenosphere system with relaxation time $\tau = 3000$ years
- Glen's (power) flow law with enhancement factor E
 - $E=1$, for **ice younger than 11 ka** (holocene ice)
 - $E=3$, for **ice older than 11 ka** (pleistocene ice)
- Simplified climate input for the free surface, temperature and accumulation function.

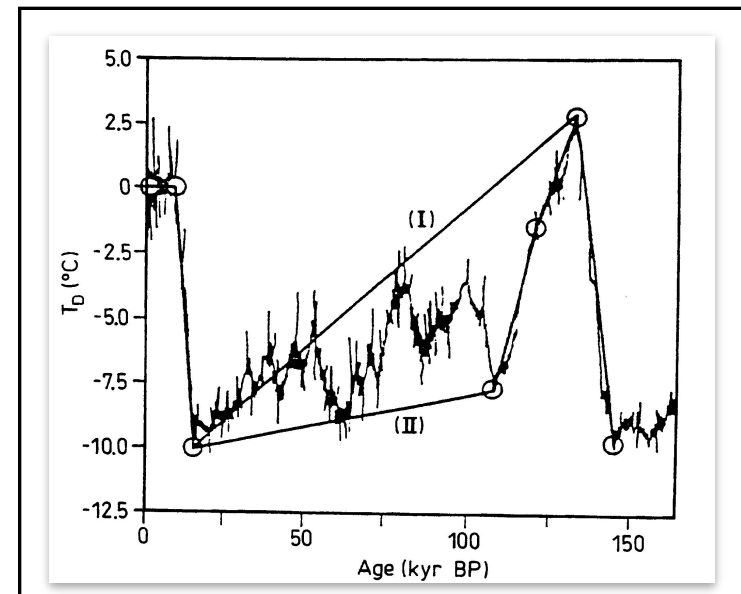
Atm. Temperature at free surface:

$$T_a(x, y, t) = T_a(x, y, t)|_{loc} + T_D(t),$$

Accumulation-Ablation rate:

$$b = S - M \quad \left[m \text{ a}^{-1}, \text{ ice equivalent} \right]$$

S=snow fall, M= melting rate



Climate Parameterization

- Temperature

$T_a(x,y,t)$: from 20th century measurements,

$T_D(t)$: from proxi-data of ice-core measurements,

- Snow fall

$S_{\text{today}}(x,y)$: from 20th century measurements,

$S(x,y,t)$: linear parameterization with $T_D(t)$,

- Melting: Positive Degree Day (PDD-M), or energy balance

$$M = \frac{\beta_2}{Y} \max \left(0, \sum_+ - \frac{P_{\max} Y}{\beta_1} S \right)$$

$$S(t) = S_{\min} + (S_{\text{today}} - S_{\min}) \frac{T_D(t) - T_D^{\min}}{T_D^{\text{today}} - T_D^{\min}},$$

$$S_{\min} = 0.5 S_{\text{today}}, \quad T_D^{\min} = -10^\circ \text{C}, \quad T_D^{\text{today}} = 0^\circ \text{C}$$

$$\sum_+ = \begin{cases} Y T_a & T_A \leq T_a, \\ \frac{Y}{\pi} \left(T_a \arccos \left(-\frac{T_a}{T_A} \right) + \sqrt{T_A^2 - T_a^2} \right) & -T_A < T_a < T_A, \\ 0 & -T_A \geq T_a, \end{cases}$$

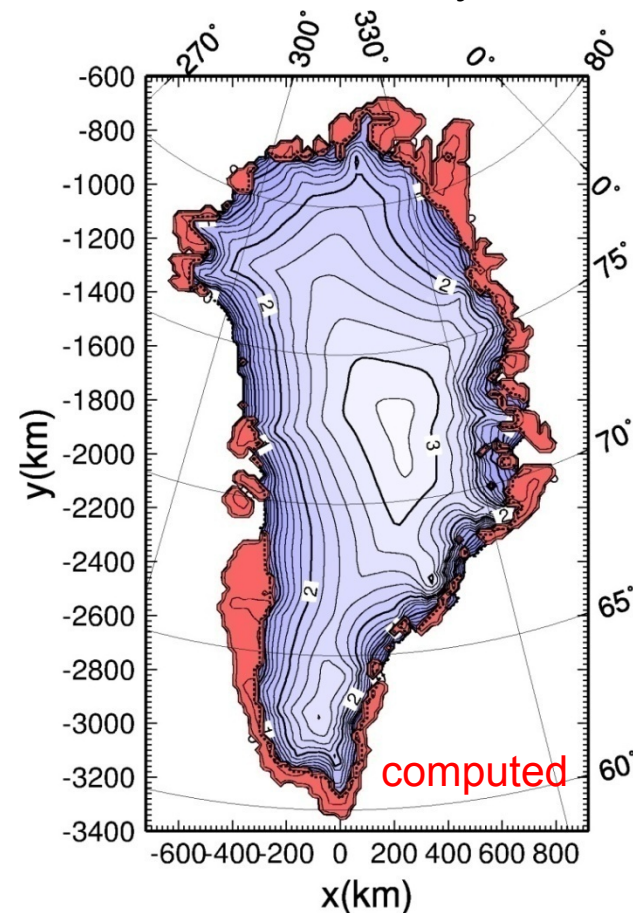
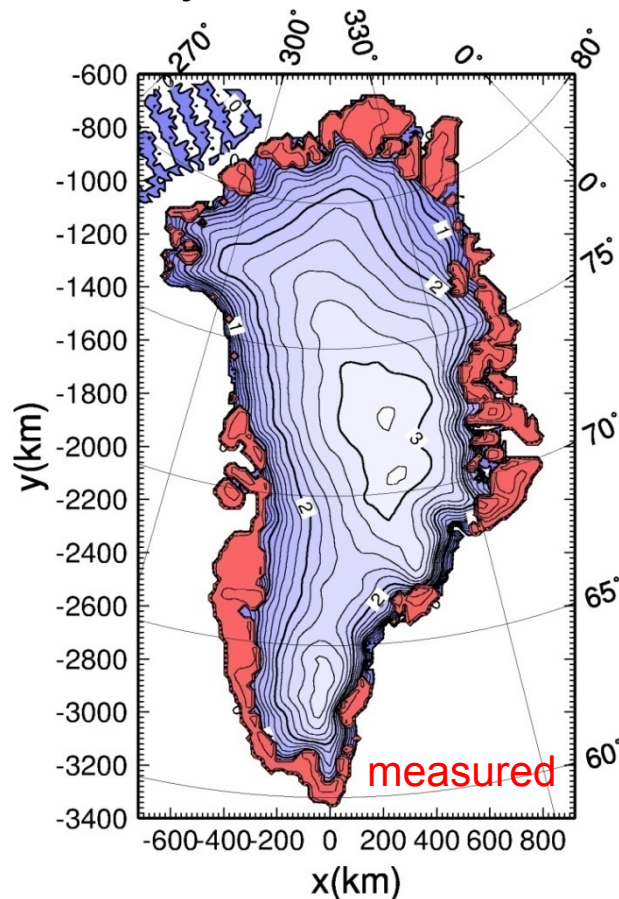
$$\beta_1 = 0.9, \quad \beta_2 = 2.6 \quad [\text{m water equivalent a}^{-1} \text{C}^{-1}]$$

$$Y = 10a, \quad P_{\max} = 0.6$$

Example 1: Steady state presence Greenland Ice Sheet

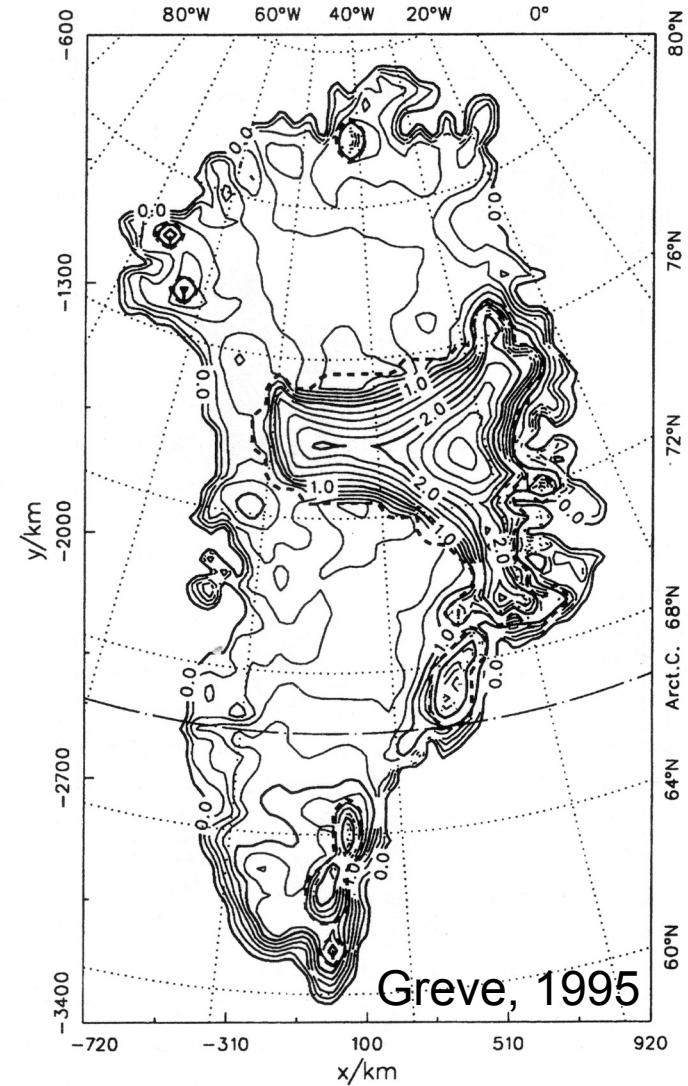
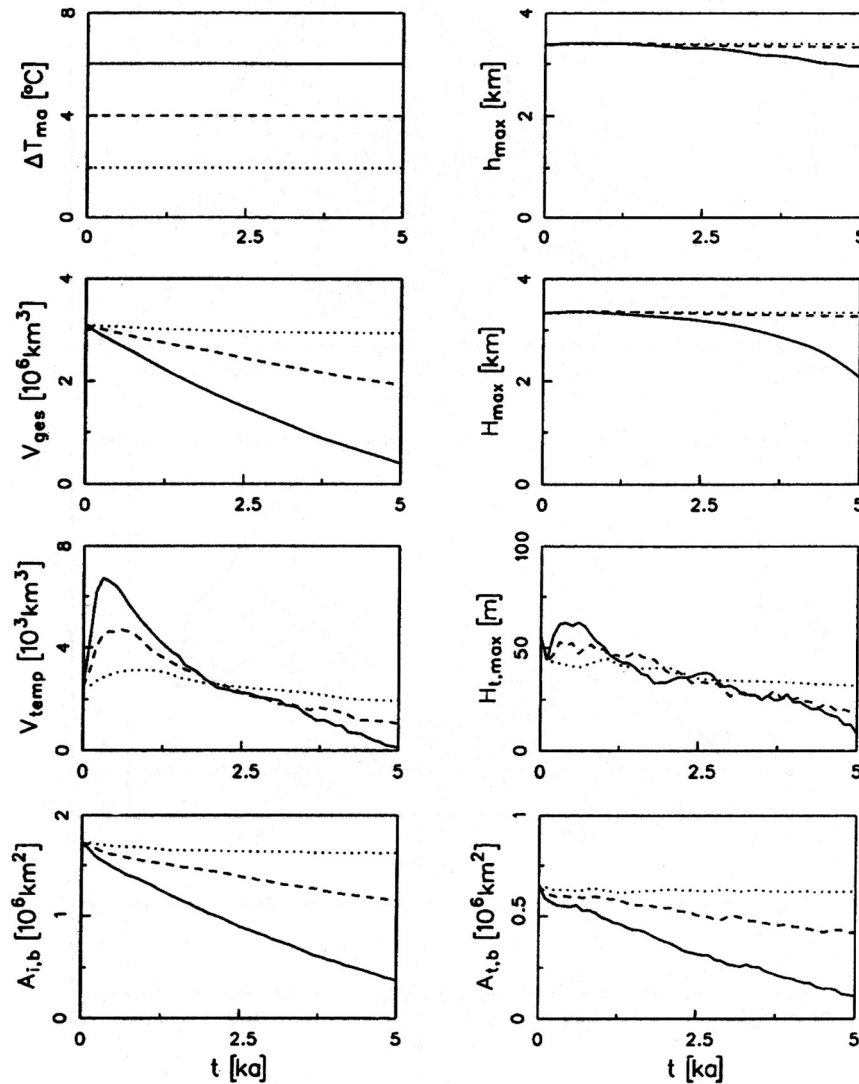
Reproduction of today's geometry of the Greenland Ice Sheet

- Start with today's geometry, temperature and accumulation formulations and initial temperature of -10°C
- Computation subject to external boundary conditions for 100000 years

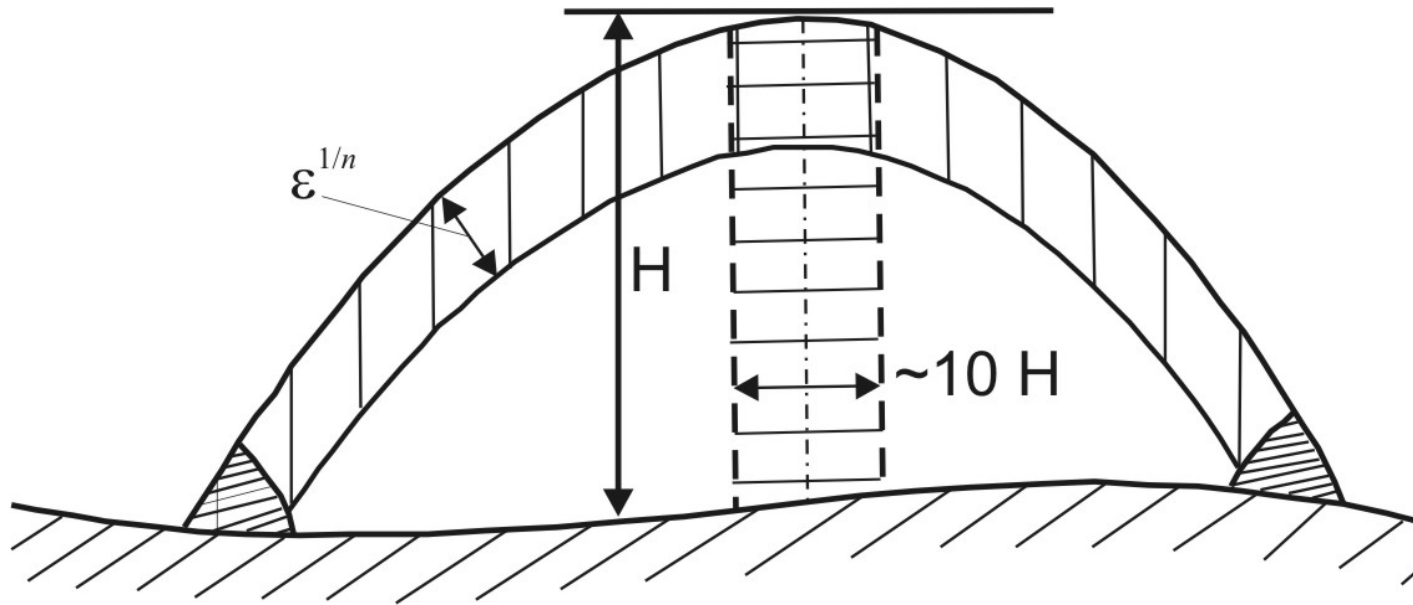


Example 2:

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toda
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3.6 Limitations of the SIA

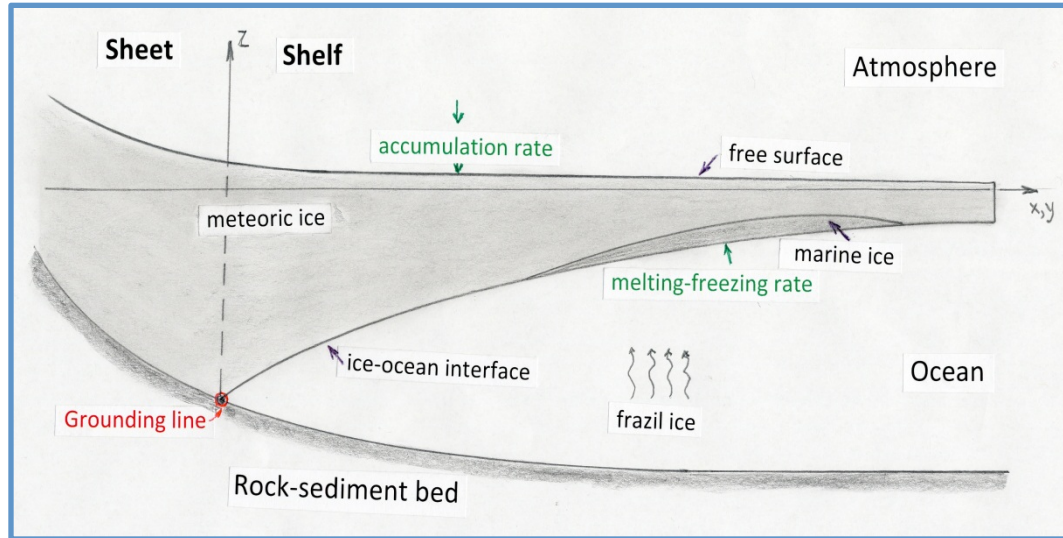


It is easy to see that

- The diffusion equation for the surface height has infinite viscosity at a dome
- the longitudinal stresses of the SIA-solution at the dome are infinitely large
- the longitudinal stresses at the free surface are infinitely large if an infinite viscosity law (power law) is used

Regularize the viscosity law → Polynomial law → Use second order SIA

Shallow Shelf Approximation (SSA)



Aspect ratio $\varepsilon = [H]/[L] \ll 1$

Important

- Same class of viscous material as for SIA
- $T_{xx}', T_{yy}', T_{zz}', T_{xy}'$ are significant
- T_{xz}', T_{yz}' are not significant
- Cryostatic pressure assumption
- Depth integration of mass and momentum balances

Perturbation expansion in ε
 Theory to $O(\varepsilon^0) \Rightarrow$ SSA
 Theory to $O(\varepsilon) \Rightarrow$ SO-SSA

Paper:

Weis, M. Greve, R and Hutter, K. (1999)
 Theory of Shallow ice shelves,
 CMT, **11**, 15-50

Shelf-Sheet Models

Equations

(SIA)

$$0 = -\frac{\partial p_{(0)}}{\partial x} + \frac{\partial T_{xz}^E}{\partial z}$$

$$0 = -\frac{\partial p_{(0)}}{\partial y} + \frac{\partial T_{yz}^E}{\partial z} \quad \text{parabolic}$$

elliptic (SSA)

$$1 = -\frac{\partial p_{(0)}}{\partial z}$$

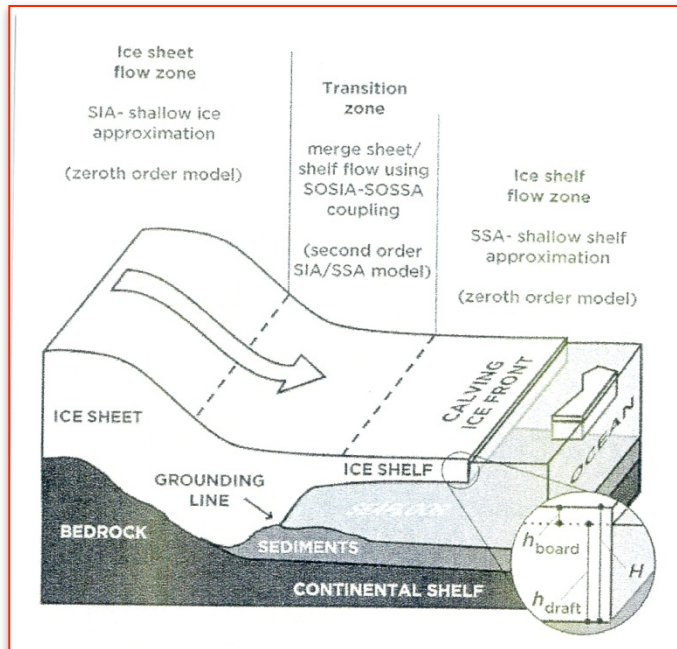
$$0 = -\frac{\partial p_{(0)}}{\partial x} + \frac{\partial T_{xx}^E}{\partial x} + \frac{\partial T_{xy}^E}{\partial y} + \frac{\partial T_{xz}^E}{\partial z}$$

$$0 = -\frac{\partial p_{(0)}}{\partial y} + \frac{\partial T_{xy}^E}{\partial x} + \frac{\partial T_{yy}^E}{\partial y} + \frac{\partial T_{yz}^E}{\partial z}$$

$$\frac{\rho_{sw}}{\rho_{sw} - \rho} = -\frac{\partial p_{(0)}}{\partial z} + \frac{\partial T_{zz}^E}{\partial z} \quad \uparrow$$

Ice streams are described by neither SIA nor by SSA

Shelf-Sheet Coupling



The two sets of zeroth order equations cannot be coupled

⇒ **Matching procedure**

Ref: Chugunov and Wilshinsky
J. Glaciol **23**, 1996

⇒ **Second order equations**

Refs:

Baral Dambaru, Dissertation TU Darmstadt 1999.

Full derivation for shallow ice sheets and shallow ice shelves **SO-SIA**, **SO-SSA**

Baral, D. Greve, R. and Hutter, K. 2001 Appl. Mech. Reviews 54, 215-250

Short version for **SO-SIA**

SO-SIA – SO-SSA Ccoupling

$$0 = -\frac{\partial p_{(2)}}{\partial x} + \frac{\partial T_{xx}^E(0)}{\partial x} + \frac{\partial T_{xy}^E(0)}{\partial y} + \frac{\partial T_{xz}^E(2)}{\partial z},$$

$$(SO - SIA) \quad 0 = -\frac{\partial p_{(2)}}{\partial y} + \frac{\partial T_{xy}^E(0)}{\partial x} + \frac{\partial T_{yy}^E(0)}{\partial y} + \frac{\partial T_{yz}^E(2)}{\partial z},$$

$$0 = -\frac{\partial p_{(2)}}{\partial z} + \frac{\partial T_{xz}^E(0)}{\partial x} + \frac{\partial T_{yz}^E(0)}{\partial y} + \frac{\partial T_{zz}^E(0)}{\partial z}.$$

$$0 = -\frac{\partial p_{(2)}}{\partial x} + \frac{\partial T_{xx}^E(2)}{\partial x} + \frac{\partial T_{xy}^E(2)}{\partial y} + \frac{\partial T_{xz}^E(2)}{\partial z},$$

$$(SO - SSA) \quad 0 = -\frac{\partial p_{(2)}}{\partial y} + \frac{\partial T_{xy}^E(2)}{\partial x} + \frac{\partial T_{yy}^E(2)}{\partial y} + \frac{\partial T_{yz}^E(2)}{\partial z},$$

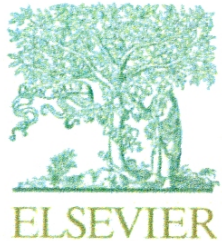
$$0 = -\frac{\partial p_{(2)}}{\partial z} + \frac{\partial T_{xz}^E(0)}{\partial x} + \frac{\partial T_{yz}^E(0)}{\partial y} + \frac{\partial T_{zz}^E(2)}{\partial z},$$

Proposal for procedure:

Construct SIA and SSA solutions

Construct SO-SIA and SO-SSA solutions

and patch them together at the grounding line



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Capabilities and limitations of numerical ice sheet models: a discussion for Earth-scientists and modelers

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Ahlkrona, J, Kirchner, N. and Lötstedt, P.:

A numerical study of scaling relations for non-Newtonian thin film flows with applications in ice sheet modeling.

Q. Jl. Mech. Appl. Math. (under review)

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